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**Derivatives of noninteger order  
and their applications**

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## Introduction

In this paper we define the derivatives of noninteger order for functions of several real variables, examine their properties and solve certain initial and boundary value problems for differential equations of noninteger order. In Chapter V we also present other applications of these derivatives.

G. W. Leibniz was the first who gave a definition of the derivative of noninteger order and since then the existence, properties and applications of such derivatives have been examined by many authors with the considerations focused mostly on the one-dimensional case (cf. [34] and [40]).

A number of the results discussed here, especially those concerning initial and boundary value problems for differential equations of noninteger order, have been published in the author's earlier papers (cf. [24]–[28]); however, in this paper these results are generalized and uniformly presented.

The paper consists of five chapters. In Chapter I we introduce the notation, and give the definition and basic properties of the derivatives of noninteger order.

Chapters II–IV deal with boundary value, multipoint and initial value problems for partial and ordinary differential equations of noninteger order, respectively.

Chapter II concerns a characteristic problem which generalizes the Darboux problem for the Mangeron polyvibrating equation (cf. [6], [21] and [23]). Reducing the problem to a nonlinear integral equation we give sufficient conditions for the existence and uniqueness of its solution. Moreover, we prove that the solution depends continuously on the initial data.

In Chapter III we consider a two-dimensional noncharacteristic boundary value problem of Z. Szmydt type and prove the existence of its solution.

In Chapter IV we examine a multipoint problem for ordinary differential equations of noninteger order.

Finally, in Chapter V we give further applications of the derivatives of noninteger order. First, basing on the properties of the derivatives given in Chapter I, we construct new examples of Mikusiński operators which are functions. Then, we generalize the Cauchy and Schwarz integral formulae for analytic functions of several complex variables defined in a polydisc.

Throughout the paper  $\mathbb{N}$  denotes the set of positive integers,  $\mathbb{N}_0 = \mathbb{N} \cup \{0\}$ ,  $\mathbb{R}$  is the set of reals,  $\mathbb{R}_+$  the set of nonnegative numbers and  $\mathbb{C}$  the set of complex numbers.

## I. Derivatives of noninteger order

Let  $x = (x_i)$ ,  $t = (t_i)$  and  $\alpha = (\alpha_i)$  belong to  $\mathbb{R}^n$ . We write  $t < x$  ( $t \leq x$ ) if  $t_i < x_i$  ( $t_i \leq x_i$ ) for  $i = \overline{1, n}$  and set  $|x|_+ := \sum_{i=1}^n x_i$ ,  $x^\alpha := \prod_{i=1}^n x_i^{\alpha_i}$ ,  $\mathbf{0} := (0, \dots, 0) \in \mathbb{R}^n$  and  $\mathbf{1} := (1, \dots, 1) \in \mathbb{R}^n$ .

For  $t < x$ , the open  $n$ -dimensional interval  $(t; x)$  is defined to be the subset of the form  $\{\xi \in \mathbb{R}^n : t < \xi < x\}$ . Other types of intervals are defined similarly. Finally, for  $x \in \mathbb{R}^n$  and a nonempty domain  $\Omega \subset \mathbb{R}^n$  we introduce the set  $\Omega(x) := \{t \in \overline{\Omega} : t \leq x\}$ .

Let  $f: \Omega \rightarrow \mathbb{R}$  be locally integrable (we write briefly  $f \in L^1_{\text{loc}}$ ), and  $p = (p_i) \in \mathbb{N}_0^n$  such that  $\alpha \leq p$ . We define the derivative  $\mathcal{D}^\alpha f$  at the point  $x$  by

$$(1.1) \quad \mathcal{D}^\alpha f(x) := \begin{cases} D^{\mathbf{1}} \int_{\Omega(x)} (x-t)^{-\alpha} f(t) dt / \Gamma(\mathbf{1} - \alpha) & \text{for } \alpha \leq \mathbf{0}; \\ D^p \mathcal{D}^{\alpha-p} f(x) & \text{for } \alpha \in \mathbb{R}^n \setminus (-\infty, 0]^n \end{cases}$$

( $\Gamma(\alpha) := \prod_{i=1}^n \Gamma(\alpha_i)$  with  $\Gamma(\alpha_i)$  being the value of the Euler gamma function), where  $D^{\mathbf{1}}$  and  $D^p$  are understood in the classical sense (we assume that for  $p > \mathbf{0}$ ,  $D^{p-1} \mathcal{D}^{\alpha-p} f$  is absolutely continuous in each variable).

By the derivative  $\mathcal{D}^\alpha f$  of  $f$  in  $\Omega$  we mean the function which assigns the number  $\mathcal{D}^\alpha f(x)$  to every point  $x \in \Omega$ .

PROPOSITION 1.1 ([9], pp. 311, 312). *Let  $I_1, I_2 \subset \mathbb{R}$ ,  $I = I_1 \times I_2$ , and let  $\mu, \nu: I_1 \rightarrow I_2$  be monotonic and absolutely continuous. If  $v: I \rightarrow \mathbb{R}$  is absolutely continuous in the first variable and measurable in the second, and if  $|v(\xi, h)| \leq M(\eta)$  with  $M \in L^1(I_2)$  and  $D_\xi v \in L^1(I)$ , then*

$$\begin{aligned} & \left( \int_{\mu(\xi)}^{\nu(\xi)} v(\xi, \eta) d\eta \right)' \\ &= \int_{\mu(\xi)}^{\nu(\xi)} D_\xi v(\xi, \eta) d\eta + \nu'(\xi) v(\xi, \nu(\xi)) - \mu'(\xi) v(\xi, \mu(\xi)) \quad \text{a.e. in } I_1. \end{aligned}$$

Let  $A_i := \inf\{x_i : x \in \Omega\}$  and  $B_i := \sup\{x_i : x \in \Omega\}$  and write  $A := (A_i)$ ,  $B := (B_i) \in \mathbb{R}^n$ . If  $\Omega$  is bounded then, without loss of generality, we set  $A = \mathbf{0}$ .

It easily follows from Definition 1.1 and Proposition 1.1 that, for  $\alpha = p \in \mathbb{N}_0^n$ ,

$$\begin{aligned} \mathcal{D}^p f(x) &= D^{p+1} \int_{\Omega(x)} f(t) dt = D^p \left( D^{\mathbf{1}} \int_{(A;x)} f(t) \chi_\Omega(t) dt \right) \\ &= D^p f(x) \quad \text{a.e. in } \Omega \end{aligned}$$

(where  $\chi_\Omega$  is the characteristic function of  $\Omega$ ), and for  $\alpha > \mathbf{0}$ ,

$$\mathcal{D}^{-\alpha} f(x) = \int_{\Omega(x)} (x-t)^{\alpha-1} f(t) dt / \Gamma(\alpha) \quad \text{a.e. in } \Omega.$$

Denote by  $\|\cdot\|_m$  the  $L^m(\Omega)$ -norm ( $m \geq 1$ ).

LEMMA 1.1. *If  $\Omega$  is a bounded domain in  $\mathbb{R}^n$ ,  $\alpha \geq \mathbf{0}$  and  $f \in L^m(\Omega)$ , then  $\mathcal{D}^{-\alpha}f \in L^m(\Omega)$  and the linear operator  $\mathcal{D}^{-\alpha} : L^m(\Omega) \rightarrow L^m(\Omega)$  is continuous. Moreover, for  $\alpha > \mathbf{0}$  the operator  $\mathcal{D}^{-\alpha}$  is completely continuous.*

Proof.  $f \geq 0$  implies  $\mathcal{D}^{-\alpha}f \geq 0$ . Observe that  $z \leq 1 - 1/m + z^m/m$  for  $z \in \mathbb{R}_+$  and  $m \geq 1$ . Thus,  $\mathcal{D}^{-\alpha}|f(x)| \leq \mathcal{D}^{-\alpha}(1 - 1/m) + \mathcal{D}^{-\alpha}|f(x)|^m/m$ , whence and by the Fubini theorem we get

$$\int_{\Omega} |\mathcal{D}^{-\alpha}f(x)| dx \leq \text{const}(1 + \|f\|_m^m),$$

(here and in the sequel const denotes a positive constant).

This proves that  $\mathcal{D}^{-\alpha}f \in L^1(\Omega)$ .

Next, we prove that  $\mathcal{D}^{-\alpha}f \in L^m(\Omega)$ . Obviously this holds for  $m = 1$ . Let  $m > 1$ . By the Hölder inequality, for  $\alpha > \mathbf{0}$  we obtain

$$\begin{aligned} & \left( \int_{\Omega(x)} (x-t)^{\alpha-1} |f(t)| dt \right)^m \\ & \leq \left( \int_{(\mathbf{0};x)} (x-t)^{\alpha-1} dt \right)^{m/(m-1)} \int_{\Omega(x)} (x-t)^{\alpha-1} |f(t)|^m dt \end{aligned}$$

and hence  $(\mathcal{D}^{-\alpha}|f(x)|)^m \leq \text{const} \mathcal{D}^{-\alpha}|f(x)|$ . As  $|f|^m \in L^1(\Omega)$ , we have  $\mathcal{D}^{-\alpha}|f|^m \in L^1(\Omega)$  and, by the above inequality,  $|\mathcal{D}^{-\alpha}f|^m \in L^1(\Omega)$ . Moreover,

$$(1.2) \quad \|\mathcal{D}^{-\alpha}f\|_m \leq \text{const} \|f\|_m$$

whence  $\mathcal{D}^{-\alpha} : L^m(\Omega) \rightarrow L^m(\Omega)$  is continuous. The argument for  $\alpha \geq \mathbf{0}$  is analogous. Thus, the proof of the first assertion is complete.

Now, we prove the complete continuity of  $\mathcal{D}^{-\alpha}$  for  $\alpha > \mathbf{0}$ . First we consider the case  $m = 1$ . By (1.2) with  $m = 1$ , the operator  $\mathcal{D}^{-\alpha}$  is bounded. Let  $h = (h_i) > \mathbf{0}$ . Then

$$\int_{\Omega} \left| \int_{\Omega(x+h)} (x+h-t)^{\alpha-1} f(t) dt - \int_{\Omega(x)} (x-t)^{\alpha-1} f(t) dt \right| dx \leq I_1 + I_2 + I_3,$$

where

$$\begin{aligned} I_1 &:= \int_{\Omega} dx \int_{(x;x+h)} (x+h-t)^{\alpha-1} \chi_{\Omega}(t) |f(t)| dt, \\ I_2 &:= \int_{\Omega} dx \int_{\Omega_{x,h}} (x+h-t)^{\alpha-1} \chi_{\Omega}(t) |f(t)| dt, \\ I_3 &:= \int_{\Omega} dx \int_{(\mathbf{0};x)} |(x+h-t)^{\alpha-1} - (x-t)^{\alpha-1}| \chi_{\Omega}(t) |f(t)| dt \end{aligned}$$

and  $\Omega_{x,h} := (\mathbf{0}; x+h) \setminus ((\mathbf{0}; x) \cup (x; x+h))$ .

The integral  $I_1$  can be estimated by

$$I_1 = \int_{(\mathbf{0};h)} (h - \sigma)^{\alpha-1} \left( \int_{\Omega} \chi_{\Omega}(x + \sigma) |f(x + \sigma)| dx \right) d\sigma \leq h^{\alpha} \|f\|_1 / \alpha^1.$$

Now, observe that  $\Omega_{x,h}$  is the sum of the sets

$$\Omega_{x,h}^{(i)} := \bigtimes_{k=1}^{i-1} (x_k; x_k + h_k) \times (0; x_k) \times \bigtimes_{k=i+1}^n (x_k; x_k + h_k).$$

Repeating the argument used for  $I_1$  we obtain

$$I_2 = \sum_{i=1}^n \int_{\Omega} dx \int_{\Omega_{x,h}^{(i)}} (x + h - t)^{\alpha-1} \chi_{\Omega}(t) |f(t)| dt \leq \text{const} \sum_{i=1}^n \prod_{\substack{j=1 \\ j \neq i}}^n h^{\alpha_j} \|f\|_1.$$

In order to estimate  $I_3$  we use the following proposition whose inductive proof is omitted.

PROPOSITION 1.2. *If  $a_i, b_i \in \mathbb{R}$  ( $i = \overline{1, n}$ ), then*

$$\prod_{i=1}^n a_i - \prod_{i=1}^n b_i = \sum_{i=1}^n (a_i - b_i) \prod_{j=1}^{i-1} a_j \prod_{k=i+1}^n b_k$$

(where here and in the sequel  $\prod_{j=q}^p a_j = 1$  for  $p < q$ ).

By the Fubini theorem we have

$$I_3 \leq \int_{\Omega} \left( \int_{(t;B)} |(x + h - t)^{\alpha-1} - (x - t)^{\alpha-1}| dx \right) \chi_{\Omega}(t) |f(t)| dt$$

and hence, by Proposition 1.2, we get

$$\begin{aligned} & \int_{(t;B)} |(x + h - t)^{\alpha-1} - (x - t)^{\alpha-1}| dx \\ & \leq \sum_{i=1}^n \int_{(t;B)} |(x_i + h_i - t_i)^{\alpha_i-1} - (x_i - t_i)^{\alpha_i-1}| \prod_{j=1}^{i-1} (x_j + h_j - t_j)^{\alpha_j-1} \\ & \quad \times \prod_{k=i+1}^n (x_k - t_k)^{\alpha_k-1} dx \leq \text{const} \sum_{i=1}^n h^{\tilde{\alpha}_i} \prod_{\substack{j=1 \\ j \neq i}}^n B^{\tilde{\alpha}_j}, \end{aligned}$$

where  $\tilde{\alpha}_i := \min(1, \alpha_i)$ . Thus

$$I_3 \leq \text{const} \sum_{i=1}^n h^{\tilde{\alpha}_i} \|f\|_1.$$

Combining the estimates of  $I_1$ ,  $I_2$  and  $I_3$ , we obtain

$$\int_{\Omega} |\mathcal{D}^{-\alpha} f(x + h) - \mathcal{D}^{-\alpha} f(x)| dx \leq P(h) \|f\|_1,$$

where  $P(h) \rightarrow 0$  as  $h \rightarrow \mathbf{0}$ .

Set  $B_\varrho^m := \{f \in L^m(\Omega) : \|f\|_m \leq \varrho\}$ . From the M. Riesz compactness theorem (cf. [18], p. 242 and [12], p. 166), we conclude that the set  $\mathcal{D}^{-\alpha}(B_\varrho^1)$  is relatively compact in  $L^1(\Omega)$ . Hence, the operator  $\mathcal{D}^{-\alpha}$  is completely continuous, as required.

Now, assume that  $m > 1$ . For  $\alpha \geq 1$  the operator  $\mathcal{D}^{-\alpha} : L^m(\Omega) \rightarrow L^m(\Omega)$  is completely continuous since its kernel is continuous.

Define

$$[\mathcal{D}^{-\alpha} f]_n(x) := \int_{\Omega(x)} \min\{(x-t)^{\alpha-1}, n\} f(t) dt / \Gamma(\alpha).$$

Clearly, the operator  $[\mathcal{D}^{-\alpha}]_n : L^m(\Omega) \rightarrow L^m(\Omega)$  is completely continuous.

Assume that  $\alpha_1 = \min(\alpha_1, \dots, \alpha_n) < 1$  and fix  $1 < r < 1/(1 - \alpha_1)$ . Then  $c_1 := \int_{\Omega(x)} (x-t)^{r(\alpha-1)} dt < \infty$ .

By the Hölder inequality, we have the estimate

$$\begin{aligned} |\mathcal{D}^{-\alpha} f(x) - [\mathcal{D}^{-\alpha} f]_n(x)| \\ \leq \left( \int_{\Omega(x)} k_n(x, t) dt \right)^{1-1/m} \left( \int_{\Omega(x)} k_n(x, t) |f(t)|^m dt \right)^{1/m} / \Gamma(\alpha) \end{aligned}$$

with  $k_n(x, t) = (x-t)^{\alpha-1} - [(x-t)^{\alpha-1}]_n$ . Moreover,

$$\int_{\Omega(x)} k_n(x, t) dt \leq \int_{A_n(x)} (x-t)^{\alpha-1} dt$$

where  $A_n(x) := \{t \in \Omega(x) : (x-t)^{\alpha-1} > n\}$ . Note that

$$(x-t)^{\alpha-1} < n^{1-r} (x-t)^{r(\alpha-1)}$$

for  $t \in A_n(x)$  and hence

$$\int_{\Omega(x)} k_n(x, t) dt \leq c_1 n^{1-r}.$$

Thus

$$\|\mathcal{D}^{-\alpha} f - [\mathcal{D}^{-\alpha} f]_n\|_m \leq \text{const} (c_1 n^{1-r})^{1-1/m} \|\mathcal{D}^{-\alpha} |f|^m\|_1^{1/m}.$$

Consequently, by (1.2) we have

$$\|\mathcal{D}^{-\alpha} f - [\mathcal{D}^{-\alpha} f]_n\|_m \leq \text{const} n^{(1-r)(1-1/m)} \|f\|_m,$$

which proves that  $\mathcal{D}^{-\alpha}$ , as a limit (in the space  $L^m(\Omega)$ ) of completely continuous operators, is completely continuous.

**Remark 1.1.** Let  $\gamma \in \mathbb{R}^n$ . We say that  $f$  belongs to  $C_\gamma(\Omega)$  if  $f$  is continuous in  $\Omega$  and  $f(t)(t-A)^\gamma$  is bounded for every  $t \in \bar{\Omega}$ .  $C_\gamma(\Omega)$  with the norm  $|f|_\gamma := \max\{|f(t)|(t-A)^\gamma : t \in \bar{\Omega}\}$  is a Banach space. Assume that  $\alpha, \gamma \geq \mathbf{0}$ ,  $\mathbf{0} \leq \delta < \mathbf{1}$  and  $\alpha + \gamma - \delta \geq \mathbf{0}$ . Observe that  $|\mathcal{D}^{-\alpha} f|_\gamma \leq c_{\Omega, \alpha, \delta, \gamma} |f|_\delta$ , with  $c_{\Omega, \alpha, \delta, \gamma} := (B-A)^{\alpha+\gamma-\delta} \Gamma(\mathbf{1}-\delta) / \Gamma(\mathbf{1}+\alpha-\delta)$ , and hence,  $\mathcal{D}^{-\alpha}$  is a bounded linear operator from  $C_\delta(\Omega)$  into  $C_\gamma(\Omega)$ , completely continuous for  $\alpha > \mathbf{0}$ .



In the sequel we shall use

PROPOSITION 1.3 (generalized Minkowski inequality, [29], pp. 27, 28, [30], pp. 158–160). *Let  $\Omega_k \subset \mathbb{R}^{n_k}$  with  $n_k \in \mathbb{N}$ ,  $k = 1, 2$ , be measurable sets and let  $m \geq 1$ . Then for any function  $v : \Omega_1 \times \Omega_2 \rightarrow \mathbb{R}$ ,*

$$\left( \int_{\Omega_1} \left| \int_{\Omega_2} v(\xi, \eta) d\eta \right|^m d\xi \right)^{1/m} \leq \int_{\Omega_2} \left( \int_{\Omega_1} |v(\xi, \eta)|^m d\xi \right)^{1/m} d\eta,$$

provided that the integrals on the right-hand side exist.

LEMMA 1.2. *Let  $f \in L^m(\Omega)$  with  $\Omega \subset \mathbb{R}^n$  being bounded. The function  $\mathbb{R}_+^n \ni \alpha \rightarrow \mathcal{D}^{-\alpha} f \in L^m(\Omega)$  is continuous. Moreover, the function  $\alpha \rightarrow \mathcal{D}^{-\alpha}$ , mapping  $\mathbb{R}_+^n \setminus \{\mathbf{0}\}$  into the space of linear continuous operators from  $L^m(\Omega)$  into itself (cf. Lemma 1.1), is also continuous.*

Proof. By Proposition 1.3, for  $f \in L^m(\Omega)$  and  $\alpha \in \mathbb{R}_+^n$ ,

$$(1.3) \quad \|\mathcal{D}^{-\alpha} f\|_m \leq B^\alpha \|f\|_m / \Gamma(\mathbf{1} + \alpha).$$

1°. Consider the case  $\alpha > \mathbf{0}$ . We have

$$\mathcal{D}^{-\alpha} f(x) - \mathcal{D}^{-\beta} f(x) = T_1 f(x) + T_2 f(x),$$

where

$$T_1 f(x) := \int_{\Omega(x)} (x-t)^{\alpha-1} f(t) dt / (1/\Gamma(\alpha) - 1/\Gamma(\beta)),$$

$$T_2 f(x) := \int_{\Omega(x)} [(x-t)^{\alpha-1} - (x-t)^{\beta-1}] f(t) dt / \Gamma(\alpha)$$

and  $\beta > \mathbf{0}$ .

Inequality (1.3) immediately yields

$$\|T_1 f\|_m \leq |1 - \Gamma(\alpha)/\Gamma(\beta)| B^\alpha \|f\|_m / \Gamma(\mathbf{1} + \alpha).$$

To estimate the norm of  $T_2 f$ , by changing the variable we have

$$|T_2 f(x)| \leq \int_{(\mathbf{0}; B)} t^{\alpha-1} |1 - t^{\beta-\alpha}| |f(x-t) \chi_\Omega(x-t)| dt / \Gamma(\alpha).$$

Proposition 1.3 now gives

$$\begin{aligned} \|T_2 f\|_m &\leq \int_{(\mathbf{0}; B)} t^{\alpha-1} |1 - t^{\beta-\alpha}| \left( \int_{\Omega} |f(x-t) \chi_\Omega(x-t)|^m dx \right)^{1/m} / \Gamma(\alpha) \\ &\leq \|f\|_m \int_{(\mathbf{0}; B)} t^{\alpha-1} |1 - t^{\beta-\alpha}| dt / \Gamma(\alpha). \end{aligned}$$

Summarizing, we obtain

$$\begin{aligned} \|\mathcal{D}^{-\alpha} f - \mathcal{D}^{-\beta} f\|_m / \|f\|_m &\leq |1 - \Gamma(\alpha)/\Gamma(\beta)| B^\alpha / \Gamma(\mathbf{1} + \alpha) \\ &\quad + \int_{(\mathbf{0}; B)} t^{\alpha-1} |1 - t^{\beta-\alpha}| dt / \Gamma(\alpha). \end{aligned}$$

Since the above integral is convergent as  $\beta \rightarrow \alpha$ , and since  $\Gamma$  is continuous for  $\beta > \mathbf{0}$  and  $\Gamma(\beta) \neq 0$ , the right-hand side converges to 0 as  $\beta \rightarrow \alpha$ .

2°. For  $\alpha \geq \mathbf{0}$ ,  $\alpha \neq \mathbf{0}$ , the above considerations are valid with the  $n$ -dimensional integrals replaced by  $\kappa$ -dimensional ones, where  $\kappa := |(\text{sgn } \alpha_i)|_+$  ( $0 < \kappa < n$ ).

Hence, the second assertion holds. Moreover, it implies

$$\|\mathcal{D}^{-\alpha} f - \mathcal{D}^{-\beta} f\|_m \rightarrow 0 \quad \text{as } \beta \rightarrow \alpha.$$

3°. Consider the case  $\alpha = \mathbf{0}$ . We shall prove that  $\|\mathcal{D}^{-\beta} f - f\|_m \rightarrow 0$  as  $\beta \rightarrow \mathbf{0}$ . Without loss of generality we can assume that  $\beta > \mathbf{0}$ . Indeed, otherwise

$$\|\mathcal{D}^{-\beta} f - f\|_m \leq \|\mathcal{D}^{-\beta} f - \mathcal{D}^{-\gamma} f\|_m + \|\mathcal{D}^{-\gamma} f - f\|_m,$$

where  $\gamma > \mathbf{0}$ , and the first term of the right-hand side tends to 0 as  $\gamma \rightarrow \beta$  (cf. the proof above).

We have

$$\begin{aligned} |\mathcal{D}^{-\beta} f(x) - f(x)| &\leq \left| \int_{(\mathbf{0};x)} t^{\beta-1} f(x-t) \chi_{\Omega}(x-t) dt / \Gamma(\beta) - f(x) \right| \\ &\leq T_3 f(x) + T_4(x) \end{aligned}$$

where

$$T_3 f(x) := \int_{(\mathbf{0};x)} t^{\beta-1} [f(x-t) \chi_{\Omega}(x-t) - f(x)] dt / \Gamma(\beta)$$

and

$$T_4 f(x) := f(x) [x^{\beta} / \Gamma(\mathbf{1} + \beta) - 1].$$

Obviously,

$$\|T_4 f\|_m^m \leq \int_{\Omega} |f(x)|^m |x^{\beta} / \Gamma(\mathbf{1} + \beta) - 1|^m dx$$

and the Lebesgue dominated convergence theorem immediately shows that  $\|T_4 f\|_m \rightarrow 0$  as  $\beta \rightarrow \mathbf{0}$ .

For given  $\varepsilon > 0$ , let  $P$  be a polynomial such that  $\|f - P\|_m < \varepsilon$ . Hence  $\|T_3 f\|_m \leq \|T_3(f - P)\|_m + \|T_3 P\|_m$ . Applying Proposition 1.3 to the first term on the right-hand side we have

$$\|T_3(f - P)\|_m \leq 2B^{\beta} \|f - P\|_m / \Gamma(\mathbf{1} + \beta) < \text{const } \varepsilon.$$

For the second term we have

$$\begin{aligned} \|T_3 P\|_m^m &\leq \int_{\Omega} \left( \int_{(\mathbf{0};x)} t^{\beta-1} \max_{1 \leq i \leq n} (\max_{t \in \Omega} |D_i P(t)|) |t|_+ dt / \Gamma(\beta) \right)^m dx \\ &\leq \text{const} (|\beta|_+ / \Gamma(\mathbf{1} + \beta))^m \end{aligned}$$

with const being independent of  $\beta$ , and so  $T_3 P \rightarrow 0$  as  $\beta \rightarrow \mathbf{0}$ . Hence, the proof is complete.

In the sequel we need the notation

$$R_{\partial\Omega} = \{x \in \bar{\Omega} : \Omega(x) = \{x\}\} \quad \text{and} \quad \Omega_b = \bar{\Omega} \setminus R_{\partial\Omega}.$$

LEMMA 1.3 (cf. [47], p. 126). *Let  $f \in L^1(\Omega)$  with  $\Omega$  bounded,  $\alpha \geq \mathbf{0}$ ,  $\lambda > 0$  and assume that*

- (i) *there is a neighbourhood  $U$  of  $R_{\partial\Omega}$  in  $\mathbb{R}^n$  such that  $f < 0$  a.e. in  $U \cap \Omega_b$ ,*
- (ii)  *$f < \lambda \mathcal{D}^{-\alpha} f$  a.e. in  $\Omega_b$ .*

*Then  $f \leq 0$  a.e. in  $\Omega_b$ .*

PROOF. Assume that  $f$  satisfying (i) and (ii) is continuous, and that  $\Lambda = \{x \in \Omega_b : f(x) \geq 0\} \neq \emptyset$ . Set  $s^0 = \inf\{|x|_+ : x \in \Lambda\} = |x^0|_+$ . Obviously  $x^0 \in \bar{\Lambda}$ . Moreover,  $f(x^0) \geq 0$  by the continuity of  $f$ . If  $x^0 \in \Lambda$ , then  $|x|_+ < |x^0|_+ = s^0$  for every  $x \in \Omega(x^0) \setminus \{x^0\}$  and this implies  $f < 0$  in  $\Omega(x^0) \setminus \{x^0\}$ . Hence, by (ii) and definition (1.1), we have  $f(x^0) < \lambda \mathcal{D}^{-\alpha} f(x^0) < 0$ , contrary to the assumption  $x^0 \in \Lambda$ . Thus,  $x^0 \in \bar{\Lambda} \setminus \Lambda \subset R_{\partial\Omega}$  and  $U \cap \Lambda \neq \emptyset$ . But (i) shows that  $f < 0$  in  $U$ , and, by the definition of  $\Lambda$ ,  $f \geq 0$  in  $\Lambda$ . Therefore  $\Lambda = \emptyset$  and the assertion holds for  $f$  continuous.

Let  $f$  be an integrable function satisfying (i) and (ii). By the Lusin theorem, there exists a sequence  $(f_k)_{k=1}^\infty$  of continuous functions such that  $f_k \leq f$  and  $\lim_{k \rightarrow \infty} f_k = f$  a.e. in  $\Omega$ . We will show that the functions  $f_k$  ( $k \in \mathbb{N}$ ) also satisfy (i) and (ii). Obviously,  $f_k < 0$  in  $U \cap \Omega_b$  for every  $k$ . Assume that  $f_k \geq \lambda \mathcal{D}^{-\alpha} f_k$  on a subset of  $\Omega_b$  having a nonzero measure. By the Lebesgue dominated convergence theorem,  $f = \lim_{k \rightarrow \infty} f_k \geq \lambda \lim_{k \rightarrow \infty} \mathcal{D}^{-\alpha} f_k = \lambda \mathcal{D}^{-\alpha} f$ , which contradicts (ii) for  $f$ . Since the assertion of our lemma holds for every continuous function,  $f_k \leq 0$  in  $\Omega_b$  (more precisely,  $f_k < 0$ ) and hence  $f \leq 0$  a.e. in  $\Omega_b$ , which ends the proof.

The following corollary is an immediate consequence of the above lemma.

COROLLARY 1.1. *Let  $\Omega$  be a bounded domain and  $v \in L^1(\Omega)$ ,  $\alpha \geq \mathbf{0}$  and  $\lambda > 0$ . Assume that  $f, g \in L^1(\Omega)$  and that*

- (i) *there is a neighbourhood  $U$  of  $R_{\partial\Omega}$  in  $\mathbb{R}^n$  such that  $f < g$  a.e. in  $U \cap \Omega_b$ ,*
- (ii)  *$f < v + \lambda \mathcal{D}^{-\alpha} f$  and  $g > v + \lambda \mathcal{D}^{-\alpha} g$  a.e. in  $\Omega_b$ .*

*Then  $f \leq g$  a.e. in  $\Omega_b$ .*

We say that a domain  $\Omega$  satisfies *condition (V)* if for every  $x \in \Omega$  and  $t \in \Omega(x)$  the interval  $(t; x)$  belongs to  $\Omega$ .

LEMMA 1.4. *If  $f \in L^1(\Omega)$  and  $\alpha, \beta \geq \mathbf{0}$ , then*

$$(1.4) \quad \mathcal{D}^{-\alpha}(\mathcal{D}^{-\beta}|f|) \leq \mathcal{D}^{-(\alpha+\beta)}|f| \quad \text{a.e. in } \Omega.$$

*Moreover, if  $\Omega$  satisfies condition (V), then  $\mathcal{D}^{-\alpha}(\mathcal{D}^{-\beta}f) = \mathcal{D}^{-(\alpha+\beta)}f$  a.e. in  $\Omega$ .*

PROOF. We begin with the case  $\alpha, \beta > \mathbf{0}$ . By (1.1) and the Fubini theorem,

$$\mathcal{D}^{-\alpha}(\mathcal{D}^{-\beta}|f(x)|) = \int_{\Omega(x)} (x-t)^{\alpha-1} \left( \int_{\Omega(t)} (t-\tau)^{\beta-1} |f(\tau)| d\tau \right) dt / (\Gamma(\alpha)\Gamma(\beta))$$

$$\begin{aligned}
 &= \int_{\Omega(x)} \left( \int_{(\tau;x) \cap \Omega} (x-t)^{\alpha-1} (t-\tau)^{\beta-1} dt \right) |f(\tau)| d\tau / (\Gamma(\alpha)\Gamma(\beta)) \\
 &\leq \int_{\Omega(x)} (x-\tau)^{\alpha+\beta-1} |f(\tau)| d\tau / \Gamma(\alpha+\beta) = \mathcal{D}^{-(\alpha+\beta)} |f(x)|
 \end{aligned}$$

with equality if  $(\tau;x) \subset \Omega$  for all  $\tau, x \in \Omega$  such that  $\tau \leq x$  (this happens for example if  $\Omega$  satisfies condition (V)).

By Lemma 1.2, we obtain (1.4) for  $\alpha \geq \mathbf{0}$  and  $\beta \geq \mathbf{0}$ ,  $\beta \neq \mathbf{0}$ . Clearly (1.4) is also satisfied when  $\beta = \mathbf{0}$ .

The proof of the second assertion is similar.

Thus, the proof is complete.

As an immediate consequence of Lemma 1.4 and definition (1.1), we obtain

LEMMA 1.5. *If  $\alpha, \beta \geq \mathbf{0}$  and  $\mathcal{D}^{\alpha-\beta} f$  exists, and if the domain  $\Omega$  satisfies condition (V), then*

$$(1.5) \quad \mathcal{D}^\alpha \mathcal{D}^{-\beta} f(x) = \mathcal{D}^{\alpha-\beta} f(x) \quad \text{a.e. in } \Omega.$$

In the sequel we equip the space  $L^1(\Omega)$  with the norm

$$(1.6) \quad \|f\|_{1,\tau} := \int_{\Omega} |f(t)| \exp(-\tau|t|_+) dt$$

where  $\tau \in \mathbb{R}_+$  is fixed. Since  $\exp(-\tau|B|_+) \leq \exp(-\tau|x|_+) \leq 1$  in  $\Omega$ , the norms  $\|\cdot\|_{1,\tau}$  and  $\|\cdot\|_{1,0}$  are equivalent if  $\Omega$  is bounded. Hence, the space of integrable functions with norm (1.6) is complete (cf. [37], Secs. 1.7, 1.26).

LEMMA 1.6. *Assume that  $\Omega$  is bounded,  $g \in L^m(\Omega)$  with  $m \geq 1$ ,  $r \in \mathbb{N}$ ,  $\alpha^1, \dots, \alpha^r \in \mathbb{R}_+^n \setminus \{\mathbf{0}\}$  and  $\lambda^1, \dots, \lambda^r \in \mathbb{R}_+$ . If  $f \in L^m(\Omega)$  and*

$$(1.7) \quad 0 \leq f \leq g + \sum_{j=1}^r \lambda^j \mathcal{D}^{-\alpha^j} f$$

*a.e. in  $\Omega$ , then*

$$(1.8) \quad f \leq g + \sum_{\nu=1}^{\infty} \sum_{1 \leq i_1, \dots, i_\nu \leq r} \prod_{j=1}^{\nu} \lambda^j \mathcal{D}^{-\alpha^{(i,\nu)}} g$$

*where  $\alpha^{(i,\nu)} = \alpha^{i_1} + \dots + \alpha^{i_\nu}$ . Moreover, if  $\Omega$  satisfies condition (V), then the right-hand side of (1.8) is a solution of the equation*

$$(1.9) \quad f = g + \sum_{j=1}^r \lambda^j \mathcal{D}^{-\alpha^j} f$$

*with  $\lambda^1, \dots, \lambda^r \in \mathbb{R}$ . This solution is unique in the space of integrable functions.*

Proof. Applying (1.7)  $k$  times and using the properties of  $\mathcal{D}^{-\alpha}$  (cf. Lemma 1.4), we get

$$0 \leq f \leq g + \sum_{\nu=1}^k \sum_{1 \leq i_1, \dots, i_\nu \leq r} \prod_{j=1}^{\nu} \lambda^j \mathcal{D}^{-\alpha^{(i, \nu)}} g + \sum_{1 \leq i_1, \dots, i_{k+1} \leq r} \prod_{j=1}^{\nu} \lambda^j \mathcal{D}^{-\alpha^{(i, k+1)}} f$$

a.e. in  $\Omega$ .

Set  $\lambda := \max_j \lambda^j$ ,  $\alpha := (\min_{i,j} \alpha_i^j) \in \mathbb{R}_+^n$  and choose  $\tau$  so that  $q := r\lambda\tau^{-|\alpha|} < 1$ . By direct calculation one can prove

$$\left\| \sum_{1 \leq i_1, \dots, i_\nu \leq r} \prod_{j=1}^{\nu} \lambda^j \mathcal{D}^{-\alpha^{(i, k+1)}} f \right\|_{1, \tau} \leq q^{k+1} \|f\|_{1, \tau},$$

whence the series

$$\sum_{\nu=1}^{\infty} \sum_{1 \leq i_1, \dots, i_\nu \leq r} \prod_{j=1}^{\nu} \lambda^j \mathcal{D}^{-\alpha^{(i, \nu)}} g$$

is convergent in  $L^1(\Omega)$ . As  $g \in L^m(\Omega)$  the series is also convergent in  $L^m(\Omega)$  (cf. Lemma 1.1). By (1.7), this yields (1.8).

Observe that (1.7) with  $g = 0$  implies  $|f| = 0$ , which means that equation (1.9) has at most one integrable solution. One can prove the existence of such a solution in a way analogous to that above by using condition (V).

Thus, the proof of Lemma 1.6 is complete.

Setting  $r = 1$ , we have the following consequence of the above lemma:

**COROLLARY 1.2.** *Let  $\Omega$  be bounded,  $g \in L^m(\Omega)$  with  $m \geq 1$ ,  $\alpha \geq \mathbf{0}$ ,  $\alpha \neq \mathbf{0}$  and  $\lambda \in \mathbb{R}_+$ . If  $f \in L^m(\Omega)$  and (1.7) holds with  $r = 1$ , then*

$$(1.10) \quad f(x) \leq g(x) + \lambda D^1 \left( \int_{\Omega(x)} (x-t)^\alpha E_{\alpha, 1+\alpha}(\lambda(x-t)^\alpha) g(t) dt \right)$$

where

$$(1.11) \quad E_{\varrho, \mu}(z) = \sum_{k=0}^{\infty} z^k / \Gamma(k\varrho + \mu) \quad (z \in \mathbb{C}; \mu, \varrho \in \mathbb{R}_+^n \setminus \{\mathbf{0}\})$$

is the Mittag-Leffler function (cf. [13], p. 117). Moreover, if  $\Omega$  satisfies condition (V), then the right-hand side of (1.10) is a solution of equation (1.9) with  $r = 1$ . This solution is unique in the space of integrable functions.

Let us point out an interesting property of the Mittag-Leffler function  $E_{\varrho, \mu}$ . Set  $\alpha \geq \mathbf{0}$ ,  $\alpha \neq \mathbf{0}$ ,  $\Omega = [A; \infty) := \{x \in \mathbb{R}^n : A \leq x\}$  and define  $f_l(x) := (x-A)^{\alpha-l} E_{\alpha, 1+\alpha-l}(\lambda(x-A)^\alpha)$ ,  $x \in \Omega$ , where  $l \in \mathbb{N}_0^n \setminus \{\mathbf{0}\}$  is chosen so that  $\mathbf{1} + \alpha - l > \mathbf{0}$  and  $\lambda \in \mathbb{R}$ . Using the relation

$$(1.12) \quad \mathcal{D}^\beta((x-A)^\gamma / \Gamma(\mathbf{1} + \gamma)) = (x-A)^{\gamma-\beta} / \Gamma(\mathbf{1} + \gamma - \beta)$$

( $\beta \in \mathbb{R}^n$ ,  $\gamma > -\mathbf{1}$ ), which can be easily obtained by direct calculation, we notice that  $f_l$  satisfies the equation  $\mathcal{D}^\alpha f_l = \lambda f_l$  ( $\alpha \geq \mathbf{0}$ ,  $\alpha \neq \mathbf{0}$ ).

In the remainder of this section we assume that the domain  $\Omega$  is bounded and satisfies the condition  $\Omega(x) = (\mathbf{0}; x)$  (hence,  $\Omega$  satisfies also condition (V)), and that  $f \in L^1(\Omega)$ . As a consequence (cf. Lemma 1.4), for  $\alpha \leq \mathbf{0}$  we have

$$(1.13) \quad \mathcal{D}^\alpha f(x) = \mathcal{D}_1^{\alpha_1} \dots \mathcal{D}_n^{\alpha_n} f(x),$$

where  $\mathcal{D}_i^{\alpha_i}$  denotes the derivative of order  $\alpha_i$  with respect to  $x_i$  (cf. Definition (1.1)). Using Proposition 1.1  $n$  times, we extend (1.13) to arbitrary  $\alpha \in \mathbb{R}^n$ .

For  $l = (l_i) \in \mathbb{N}_0^n$  and  $x = (x_i) \in \mathbb{R}^n$ , set  $\nabla_l(x) := (x_i \operatorname{sgn} l_i)$  and  $\Delta_l(x) := (x_i \delta_{0l_i})$ , where  $\delta$  is the Kronecker symbol.

We have the following lemma which generalizes the Taylor formula:

LEMMA 1.7. *Assume that  $\mathcal{D}^\alpha f$ , where  $\alpha \geq \mathbf{0}$ , exists and is integrable. Then, for every  $\beta \geq \mathbf{0}$ , the derivative  $\mathcal{D}^{\alpha-\beta} f$  exists and*

$$(1.14) \quad \mathcal{D}^{\alpha-\beta} f(x) = \sum_{l \leq \beta} \mathcal{D}^{-\Delta_l(\beta)} \mathcal{D}^{\alpha-l} f(\Delta_l(x)) \\ \times x^{\nabla_l(\beta-l)} / \Gamma(\mathbf{1} + \nabla_l(\beta-l)) \quad \text{a.e. in } \Omega$$

(with  $p \in \mathbb{N}^n$  chosen so that  $p - \mathbf{1} < \alpha \leq p$ ).

Proof. First, we prove (1.14) for  $\alpha = \beta$ .

We use induction on  $n$ . For  $n = 1$  formula (1.14) holds (cf. [13], p. 570). Assume its validity for  $n = k - 1$  ( $k \geq 2$ ). Then

$$\mathcal{D}_k^{\alpha_k} f(x) = \sum_{r \leq q} \mathcal{D}^{-\Delta_r(\alpha')} \mathcal{D}^{\alpha'-r} \mathcal{D}_k^{\alpha_k} f(\Delta_r(x'), x_k) x'^{\nabla_r(\alpha'-r)} / \Gamma(\mathbf{1}' + \nabla_r(\alpha'-r)),$$

where  $x = (x', x_k) \in \mathbb{R}^k$ ,  $\alpha = (\alpha', \alpha_k) \in \mathbb{R}_+^k$ ,  $l = (r, l_k) \in \mathbb{N}_0^k$  and  $p = (q, p_k)$ ,  $\mathbf{1} = (\mathbf{1}', 1) \in \mathbb{N}^k$ . Applying  $\mathcal{D}_k^{-\alpha_k}$  to both sides, we obtain

$$f(x) = \sum_{l_k=1}^{p_k} \mathcal{D}_k^{\alpha_k-l_k} f(x', 0) x^{\alpha_k-l_k} / \Gamma(1 + \alpha_k - l_k) \\ + \sum_{r \leq q} \mathcal{D}_k^{-\alpha_k} \mathcal{D}^{-\Delta_r(\alpha')} \mathcal{D}^{\alpha'-r} \mathcal{D}_k^{\alpha_k} f(\Delta_r(x'), x_k) x'^{\nabla_r(\alpha'-r)} / \Gamma(\mathbf{1}' + \nabla_r(\alpha'-r)).$$

By the inductive assumption for  $\mathcal{D}_k^{\alpha_k-l_k} f(x', 0)$ , the first term on the right-hand side is

$$\sum_{l_k=1}^{p_k} \left( \sum_{r \leq q} \mathcal{D}^{-\Delta_r(\alpha')} \mathcal{D}^{\alpha'-r} \mathcal{D}_k^{\alpha_k-l_k} f(\Delta_r(x'), 0) \right. \\ \left. \times x'^{\nabla_r(\alpha'-r)} / \Gamma(\mathbf{1}' + \nabla_r(\alpha'-r)) \right) x_k^{\alpha_k-l_k} / \Gamma(1 + \alpha_k - l_k).$$

Bearing in mind the properties of  $\Delta_l$  and  $\nabla_l$ , we have

$$f(x) = \sum_{l \leq p; l_k \geq 1} \mathcal{D}^{-\Delta_l(\alpha)} \mathcal{D}^{\alpha-l} f(\Delta_l(x)) x^{\nabla_l(\alpha-l)} / \Gamma(\mathbf{1} + \nabla_l(\alpha-l)) \\ + \sum_{l \leq p; l_k \geq 0} \mathcal{D}^{-\Delta_l(\alpha)} \mathcal{D}^{\alpha-l} f(\Delta_l(x)) x^{\nabla_l(\alpha-l)} / \Gamma(\mathbf{1} + \nabla_l(\alpha-l)).$$

Thus, if (1.14) is valid for  $n = k - 1$  then it also holds for  $n = k$ . Hence we get the assertion for  $\alpha = \beta$ .

Applying  $\mathcal{D}^{\alpha-\beta}$  to both sides of (1.14) with  $\alpha = \beta$ , we get

$$\mathcal{D}^{\alpha-\beta} f(x) = \sum_{l \leq p} \mathcal{D}^{\Delta_l(\alpha-\beta)} \mathcal{D}^{-\Delta_l(\alpha)} \mathcal{D}^{\alpha-l} f(\Delta_l(x)) \\ \times \mathcal{D}^{\nabla_l(\alpha-\beta)} (x^{\nabla_l(\alpha-l)} / \Gamma(\mathbf{1} + \nabla_l(\alpha-l))).$$

Now (1.5) and (1.12) yield (1.14) for every  $\alpha > \mathbf{0}$  and  $\beta \geq \mathbf{0}$ , which completes the proof of Lemma 1.7.

As a consequence of Lemmas 1.4 and 1.7 we have

**COROLLARY 1.3.** *If  $\mathcal{D}^\alpha f$  is integrable, and if  $\beta \leq \alpha$ , then  $\mathcal{D}^\beta f$  exists and is given by*

$$(1.15) \quad (a) \quad \mathcal{D}^\beta f(x) = \mathcal{D}^{\beta-\alpha} \mathcal{D}^\alpha f(x) \quad \text{for } \alpha \leq \mathbf{0}, \\ (b) \quad \mathcal{D}^\beta f(x) = \sum_{l \leq p} \mathcal{D}^{-\Delta_l(\alpha-\beta)} \mathcal{D}^{\alpha-l} f(\Delta_l(x)) \\ \times x^{\nabla_l(\alpha-\beta-l)} / \Gamma(\mathbf{1} + \nabla_l(\alpha-\beta-l)) \quad \text{for } \alpha \geq \mathbf{0}, \alpha \neq \mathbf{0}$$

(with  $p$  as in (1.14)). Moreover,  $\mathcal{D}^\beta f$  is integrable in case (a) (cf. Lemma 1.1).

Observe that Corollary 1.3 generalizes the result obtained by J. D. Tamarkin (cf. [45], Th. 6).

**Remark 1.2.** It is worth noticing that in case  $\alpha \geq \mathbf{0}$ , the derivatives of order  $\beta = \alpha - k$  (where  $\mathbf{0} \leq k \leq p$ ) are integrable. Moreover, if  $\alpha = p$ , then for arbitrary  $\beta$  the derivative  $\mathcal{D}^\beta f$  can be expressed in terms of derivatives of integer orders not higher than  $p$  (that is, partial derivatives).

**Remark 1.3.** If the assumptions of Lemma 1.7 are satisfied and the derivative  $\mathcal{D}^\alpha f$  does not depend on the order of differentiations, then (1.14) with  $\alpha = \beta$  can be rewritten as

$$(1.16) \quad f(x) = \mathcal{D}^{-\alpha} \mathcal{D}^\alpha f(x) \\ - \sum_{l \leq p; l \neq \mathbf{0}} \varepsilon_l \mathcal{D}^{\nabla_l(\alpha-l)} f(\Delta_l(x)) x^{\nabla_l(\alpha-l)} / \Gamma(\mathbf{1} + \nabla_l(\alpha-l)),$$

where  $\varepsilon_l := (-1)^{|\text{sgn } l_i|_+}$ .

The following lemma, resulting from Lemma 1.7, gives necessary and sufficient conditions for the solvability of the  $n$ -dimensional Abel–Liouville equation of first kind (for the case  $n = 1$ , cf. [45], Th. 4).

LEMMA 1.8. Let  $p - \mathbf{1} < \alpha \leq p \in \mathbb{N}^n$ . If

- (i)  $\mathcal{D}^\alpha f$  exists and is integrable,
- (ii)  $\mathcal{D}^{\alpha-l} f(\Delta_l(x)) = 0$  for  $\mathbf{0} \leq l \leq p$ ,  $l \neq \mathbf{0}$ ,

then there exists exactly one function  $g = \mathcal{D}^\alpha f \in L^1(\Omega)$  which is a solution of the equation

$$(1.17) \quad \mathcal{D}^{-\alpha} g = f.$$

Conversely, if  $g \in L^1(\Omega)$  is a solution of (1.17) then  $f$  satisfies (i) and (ii).

PROOF. 1°. By (i), (ii) and Lemma 1.7, we have  $f = \mathcal{D}^{-\alpha} \mathcal{D}^\alpha f$ . Hence, the function  $g := \mathcal{D}^\alpha f$  satisfies (1.17).

2°. Assume that  $g \in L^1(\Omega)$  is a solution of (1.17). Then, by Lemma 1.6,  $\mathcal{D}^{-\alpha} f = g \in L^1(\Omega)$  and  $\mathcal{D}^{\alpha-l} f = \mathcal{D}^{-l} g$  for  $\alpha - l \geq \mathbf{0}$ . Hence  $\mathcal{D}^{-l} g(\Delta_l(x)) = 0$  for  $\mathbf{0} \leq l \leq \alpha$ ,  $l \neq \mathbf{0}$ . If there exists a positive integer  $i$  such that  $\alpha_i - l_i < 0$ , then, by definition (1.1) and Proposition 1.1, we get  $\mathcal{D}^{\alpha-l} f(\Delta_l(x)) = 0$ .

## II. Characteristic problem for the Mangeron polyvibrating equation of noninteger order

**1. The problem.** Let  $n, r \in \mathbb{N}$  and  $B = (B_i) \in \mathbb{R}_+^n$  be fixed, and  $\Omega = (\mathbf{0}; B)$ . Also fix  $\alpha = (\alpha_i) > \mathbf{0}$  and  $\beta^j = (\beta_i^j) \in \mathbb{R}^n$  ( $j = \overline{1, r}$ ) so that  $\beta^j \leq \alpha$  and  $|\beta^j|_+ < |\alpha|_+$ .

We consider the differential equation

$$(2.1) \quad \mathcal{D}^\alpha u(x) = F(x, \{\mathcal{D}^{\beta^j} u(x)\}), \quad x \in \Omega,$$

where  $F$  is a given function,  $\mathcal{D}^\alpha u$  and  $\mathcal{D}^{\beta^j} u$  are derivatives of noninteger orders  $\alpha$  and  $\beta^j$ , respectively, and  $\{\mathcal{D}^{\beta^j} u\}$  denotes the  $r$ -element sequence of derivatives  $\mathcal{D}^{\beta^j} u$ .

(2.1) is an ordinary differential equation for  $n = 1$  and a partial differential equation if  $n \geq 2$ . In the latter case it is a noninteger counterpart of the Mangeron polyvibrating equation (cf. [6], [21] and [23]). Let us note that equation (2.1) with  $n = 1$  was examined in a few papers (cf. [35] and [40]), and with  $n = 2$  in [7] (cf. Remark 2.4 below) and [24]. To the best of our knowledge the case  $n \geq 3$  has not been considered so far.

Let  $l = (l_i) \in \mathbb{N}_0^n$  be a multiindex and  $p = (p_i) \in \mathbb{N}^n$  such that  $p - \mathbf{1} < \alpha \leq p$  with  $\alpha$  being the multiindex from (2.1), and set

$$(x)^l := \begin{cases} 0 & \text{if } l > \mathbf{0}, \\ (x_{k_1}, \dots, x_{k_\nu}) & \text{if } l_{k_1} = \dots = l_{k_\nu} = 0 \\ & \text{for some } \nu \text{ where } 1 \leq k_1 < \dots < k_\nu \leq n. \end{cases}$$

In this chapter we examine the following characteristic problem (P) for equation (2.1): Find a solution  $u$  of equation (2.1) in  $\Omega$  (i.e. a function  $u : \Omega \rightarrow \mathbb{R}$  such



that  $\mathcal{D}^\alpha u \in L^1(\Omega)$  and  $u$  satisfies (2.1) a.e. in  $\Omega$  which satisfies the boundary conditions

$$(2.2) \quad \mathcal{D}^{\alpha-l} u(\Delta_l(x)) = M_l((x)^l) \quad \text{for } l \leq p, l \neq \mathbf{0},$$

for given  $M_l$ . Observe that since  $\mathcal{D}^\alpha u$  exists and is integrable, the derivatives  $\mathcal{D}^{\alpha-l} u$  are at least absolutely continuous in  $x_i$ , provided that  $l_i \geq 1$ ,  $i = \overline{1, n}$ .

Assume that  $u$  is a solution of problem (P). By Lemma 1.7,  $u$  is of the form

$$(2.3) \quad u(x) = \widehat{T}s(x) := w(x) + \mathcal{D}^{-\alpha} s(x),$$

where

$$(2.4) \quad w(x) := \sum_{l \leq p; l \neq \mathbf{0}} \mathcal{D}^{-\Delta_l(\alpha)} M_l((x)^l) x^{\nabla_l(\alpha-l)} / \Gamma(\mathbf{1} + \nabla_l(\alpha-l))$$

and  $s$ , standing for the derivative of order  $\alpha$  of  $u$ , is an integrable solution of the nonlinear integral equation

$$(2.5) \quad s(x) = Ts(x) := F(x, \{\mathcal{D}^{\beta^j} w(x) + \mathcal{D}^{\beta^j - \alpha} s(x)\}), \quad x \in \Omega.$$

By (2.3),  $\mathcal{D}^\alpha u$  does not depend on the order of differentiations. Moreover, (2.3) establishes a one-to-one correspondence between the solutions  $u$  of problem (P) and the integrable solutions  $s$  of (2.5).

**Remark 2.1.** By (2.4) and Lemma 1.7, for  $\beta \geq \mathbf{0}$  we have

$$\mathcal{D}^\beta w(x) = \sum_{l \leq p; l \neq \mathbf{0}} \mathcal{D}^{-\Delta_l(\alpha-\beta)} M_l((x)^l) x^{\nabla_l(\alpha-\beta-l)} / \Gamma(\mathbf{1} + \nabla_l(\alpha-\beta-l)).$$

**2. Existence of solutions.** In this section we give sufficient conditions for the set of solutions of problem (P) to be nonempty and relatively compact in  $L^1(\Omega)$ . Since the transformation  $\widehat{T}$  (cf. (2.3)) is completely continuous (cf. Lemma 1.1), it is enough to find sufficient conditions for the image of any bounded set under transformation  $T$  (cf. formula (2.5)) to be also bounded.

We assume the following:

I. The function  $F : \Omega \times \mathbb{R}^r \rightarrow \mathbb{R}$  satisfies the Carathéodory conditions (cf. [16], Def. 12.2) and the inequality

$$(2.6) \quad |F(x, \{z_j\})| \leq \sum_{j=1}^r \sum_{k=1}^{r_j} K_{jk}(x) |z_j|^{\kappa_{jk}} \quad \text{a.e. in } \Omega, z_j \in \mathbb{R},$$

where  $r_j \in \mathbb{N}$ ,  $0 \leq \kappa_{jk} \leq 1$  are fixed numbers and  $K_{jk} : \Omega \rightarrow \mathbb{R}_+$  are in  $L^{1/(1-\kappa_{jk})}$  (here and in the sequel  $1/0 := \infty$ ).

II. The functions  $\mathcal{D}^{\beta^j} w : \Omega \rightarrow \mathbb{R}$  are integrable.

III. The functions  $M_l : \mathbb{R}^\nu \rightarrow \mathbb{R}$  ( $1 \leq \nu := |(\text{sgn } l_i)|_+ < n$ ;  $l \leq p$ ) are integrable.

**Remark 2.2.** By Assumption I,  $\mathcal{F}(s_1, \dots, s_r)(x) := F(x, \{s_j(x)\})$  is integrable (cf. also [42]) for integrable  $s_1, \dots, s_r$ . The substitution operator  $\mathcal{F} : (L^1(\Omega))^r \rightarrow L^1(\Omega)$  is bounded and continuous (cf. [22], pp. 161–163).

By Assumptions I and II (cf. also Remark 2.2) and Lemma 1.1, the transformation  $T$  is continuous. In the case  $\beta^j < \alpha$ , it is completely continuous.

We will find a bounded and convex set  $\Lambda \subset L^1(\Omega)$  such that  $T(\Lambda) \subset \Lambda$  and  $T(\Lambda)$  is relatively compact.

By (2.6), the inequality  $(y + z)^\kappa \leq y^\kappa + z^\kappa$  ( $y, z \in \mathbb{R}_+$ ;  $0 \leq \kappa \leq 1$ ) and the well known properties of the Lebesgue integral, we have

$$(2.7) \quad |Ts(x)| \leq \sum_{j=1}^r \sum_{k=1}^{r_j} K_{jk}(x) [|\mathcal{D}^{\beta^j} w(x)|^{\kappa_{jk}} + (\mathcal{D}^{\beta^j - \alpha} |s(x)|)^{\kappa_{jk}}] \quad \text{a.e. in } \Omega.$$

Equip the space  $L^1(\Omega)$  with the norm (1.6). By the Hölder inequality, the functions  $x \rightarrow K_{jk}(x) |\mathcal{D}^{\beta^j} w(x)|^{\kappa_{jk}}$  are integrable. Then, taking into account (2.7) and (1.6), we have

$$(2.8) \quad \|Ts\|_{1,\tau} \leq \left\| \sum_{j=1}^r \sum_{k=1}^{r_j} K_{jk} |\mathcal{D}^{\beta^j} w|^{\kappa_{jk}} \right\|_{1,\tau} + \sum_{j=1}^r \sum_{k=1}^{r_j} \int_{\Omega} K_{jk}(x) (\mathcal{D}^{\beta^j - \alpha} |s(x)|)^{\kappa_{jk}} \exp(-\tau|x|_+) dx.$$

Consider the integral in (2.8). Using the Hölder inequality, and the properties of  $K_{jk}$  and the exponential function, for  $\kappa_{jk} > 0$  we have

$$\begin{aligned} \int_{\Omega} K_{jk}(x) (\mathcal{D}^{\beta^j - \alpha} |s(x)|)^{\kappa_{jk}} \exp(-\tau|x|_+) dx \\ \leq \left( \int_{\Omega} (K_{jk}(x))^{1/(1-\kappa_{jk})} \exp(-\tau|x|_+) dx \right)^{1-\kappa_{jk}} \\ \times \left( \int_{\Omega} \mathcal{D}^{\beta^j - \alpha} |s(x)| \exp((-\tau/\kappa_{jk})|x|_+) dx \right)^{\kappa_{jk}} \\ \leq \text{const} \left( \int_{\Omega} \mathcal{D}^{\beta^j - \alpha} |s(x)| \exp(-\tau|x|_+) dx \right)^{\kappa_{jk}} \end{aligned}$$

with const independent of  $s$ . For  $\kappa_{jk} = 0$ , we obtain

$$\int_{\Omega} K_{jk}(x) (\mathcal{D}^{\beta^j - \alpha} |s(x)|)^{\kappa_{jk}} \exp(-\tau|x|_+) dx \leq \text{const}.$$

Changing the order of integration one gets the estimate

$$\int_{\Omega} K_{jk}(x) (\mathcal{D}^{\beta^j - \alpha} |s(x)|)^{\kappa_{jk}} \exp(-\tau|x|_+) dx \leq \text{const} \tau^{\kappa_{jk}|\beta^j - \alpha|_+} \|s\|_{1,\tau}^{\kappa_{jk}}.$$

Using this estimate together with (2.8), we have

$$(2.9) \quad \|Ts\|_{1,\tau} \leq \text{const} \left( 1 + \sum_{j=1}^r \sum_{k=1}^{r_j} \tau^{\kappa_{jk}|\beta^j - \alpha|_+} \|s\|_{1,\tau}^{\kappa_{jk}} \right).$$

Write

$$(2.10) \quad B_\tau(R) := \{s \in L^1(\Omega) : \|s\|_{1,\tau} \leq R\},$$

where  $R$  is a positive constant. Clearly,  $B_\tau(R)$  is a closed, bounded and convex set.

Since  $0 \leq \kappa_{jk} \leq 1$  (cf. (2.6)), we can choose  $R$  and  $\tau$  so that

$$(2.11) \quad \text{const} \left( 1 + \sum_{j=1}^r \sum_{k=1}^{r_j} \tau^{\kappa_{jk}|\beta^j - \alpha|_+} R^{\kappa_{jk}} \right) \leq R.$$

As a result  $T$  maps  $B_\tau(R)$  into itself if  $R$  and  $\tau$  are sufficiently large to satisfy (2.11). Furthermore, if  $s$  is a solution of equation (2.3), then  $s$  belongs to  $B_\tau(R)$  with  $R$  and  $\tau$  satisfying (2.11). In the case when  $\beta^j < \alpha$ , the set  $T(B_\tau(R))$  is, obviously, relatively compact. In the more general case  $\beta^j \leq \alpha$ , define

$$(2.12) \quad Z_\tau(R) := \left\{ s \in B_\tau(R) : \forall \varepsilon > 0 \exists \delta > 0 \forall h = (h_i) > \mathbf{0} \right. \\ \left. |h|_+ < \delta \Rightarrow \int_{\Omega} |s(x+h) - s(x)| dx \leq \varepsilon \right\}.$$

This set is convex and relatively compact. Since  $T$  is continuous,  $T(A) \subset T(\bar{A}) \subset \overline{T(A)}$  for every set  $A$ . Thus  $T(\bar{A}) = \overline{T(A)}$  and  $T(A)$  is relatively compact, provided that so is  $A$ . So,  $T(Z_\tau(R))$  is relatively compact.

Thus, all assumptions of the Schauder fixed point theorem are satisfied (cf. [12], p. 57 and [22], pp. 125–126) and so, by this theorem, we have

**LEMMA 2.1.** *Under Assumptions I and II, the set of solutions of equation (2.5) is nonempty and bounded. Moreover, if  $\beta^j < \alpha$  then this set is relatively compact in  $L^1(\Omega)$ .*

**Remark 2.3.** Replace Assumptions I and II by the following:

I<sub>1</sub>. The function  $F : \Omega \times \mathbb{R}^r \rightarrow \mathbb{R}$  satisfies the Carathéodory conditions and is subadditive in the second variable.

II<sub>1</sub>. The function  $\Omega \ni x \rightarrow F(x, \{\mathcal{D}^{\beta^j} w(x)\})$  is integrable.

It is easily seen that Assumption I<sub>1</sub> yields the estimate

$$|Ts(x)| \leq |F(x, \{\mathcal{D}^{\beta^j} w(x)\})| + \sum_{j=1}^r \sum_{k=1}^{r_j} K_{jk}(x) (\mathcal{D}^{\beta^j - \alpha} |s(x)|)^{\kappa_{jk}}.$$

Hence, bearing in mind Assumptions I<sub>1</sub> and II<sub>1</sub>, and using an argument analogous to that subsequent to inequality (2.7), we can show that equation (2.5) has a solution.

By the complete continuity of the transformation defined by (2.3), and Lemma 2.1, we have

**THEOREM 2.1.** *If Assumptions I–III (or  $I_1$ ,  $II_1$  and III) are satisfied, then problem (P) has a solution. This solution is of the form (2.3), where  $s$  is an integrable solution of the nonlinear integral equation (2.5). Moreover, the set of solutions of problem (P) is relatively compact in  $L^1(\Omega)$ .*

**REMARK 2.4.** Let  $\Omega = \mathbb{R}_+^n$ . There exists an increasing sequence  $(B^k)_{k=1}^\infty$  of points from  $\Omega$  such that  $\Omega = \bigcup_{k \in \mathbb{N}} \Omega^k$ , where  $\Omega^k = (\mathbf{0}; B^k)$ . By Lemma 2.1, equation (2.5) has a solution in  $\Omega^k$  for  $k \in \mathbb{N}$ . As a consequence, the function  $s(x) = s^k(x)$ , where  $x \in \Omega^k \setminus \Omega^{k-1}$  (we set  $\Omega^0 := \emptyset$ ),  $k \in \mathbb{N}$ , is locally integrable and it is a solution of (2.5) in  $\Omega$ . Taking into account the one-to-one correspondence between the solutions of (2.5) and those of problem (P) shows that (P) has a solution  $u$  in  $\Omega$ , given by (2.3), such that  $\mathcal{D}^\alpha u \in L_{loc}^1$ .

**REMARK 2.5.** Consider equation (2.1) with the characteristic conditions

$$(2.13) \quad \mathcal{D}^{\nabla_i(\alpha-l)} u(\Delta_l(x)) = N_l((x)^l) \quad \text{for } l \leq p, l \neq \mathbf{0},$$

where  $N_l$  are given functions. Seeking a solution  $u$  of (2.1) such that the derivative  $\mathcal{D}^\alpha u$  does not depend on the order of differentiations, and assuming that the  $N_l$  ( $l \leq p$ ;  $1 \leq |(\text{sgn } l_i)|_+ < n$ ) have the derivatives  $\mathcal{D}^{\nabla_i(\alpha)} N_l$  and Assumptions I and II are satisfied, one can prove, using the Schauder fixed point theorem, that problem (2.1), (2.13) has a solution.

Let us point out that problem (2.1), (2.13) with  $n = 2$ ,  $0 < \alpha_1 \leq 1$ ,  $1 < \alpha_2 \leq 2$  and a less general right-hand side was examined in [7].

**3. Uniqueness of the solution.** Let us replace Assumption I by

$I_2$ . The function  $F : \Omega \times \mathbb{R}^r \rightarrow \mathbb{R}$  is measurable in  $x \in \Omega$  and, for almost all  $x \in \Omega$  and  $z_j^1, z_j^2 \in \mathbb{R}$ ,

$$(2.14) \quad |F(x, \{z_j^1\}) - F(x, \{z_j^2\})| \leq c_L \sum_{j=1}^r x^{-\mu^j} |z_j^1 - z_j^2|,$$

where  $c_L$  is a positive constant independent of  $x \in \Omega$ , with  $\mu^j \in \mathbb{R}_+^n$  being fixed and such that  $\alpha - \beta^j - \mu^j > \mathbf{0}$  ( $j = \overline{1, r}$ ).

We have

**LEMMA 2.2.** *If Assumptions  $I_2$  and  $II_1$  are satisfied, then equation (2.5) has a unique integrable solution in  $\Omega$ .*

**PROOF.** By Assumptions  $I_2$  and  $II_1$ , the transformation  $T$  (cf. (2.5)) maps  $L^1(\Omega)$  into a set of measurable functions.

Choose  $\tau$  so that

$$(2.15) \quad 2c_L \sum_{j=1}^r (\Gamma(\alpha - \beta^j - \mu^j) / \Gamma(\alpha - \beta^j)) \tau^{|\beta^j + \mu^j - \alpha|_+} \leq 1$$

(the possibility of such a choice follows from the assumption  $\alpha - \beta^j - \mu^j > \mathbf{0}$  ( $j = \overline{1, r}$ )). We show that  $T$  is contractive. To this end let  $s^1, s^2 \in L^1(\Omega)$ . By Assumption I<sub>2</sub>, in the case  $\beta^j < \alpha$  we obtain

$$\begin{aligned} \|Ts^1 - Ts^2\|_{1,\tau} &\leq c_L \sum_{j=1}^r \int_{\Omega} dx \int_{\Omega(x)} (x-t)^{\alpha-\beta^j-1} x^{-\mu^j} \\ &\quad \times |s^1(t) - s^2(t)| \exp(-\tau|x|_+) dt / \Gamma(\alpha - \beta^j). \end{aligned}$$

Changing the order of integration gives

$$\begin{aligned} \|Ts^1 - Ts^2\|_{1,\tau} &\leq c_L \sum_{j=1}^r \int_{\Omega} |s^1(t) - s^2(t)| \exp(-\tau|t|_+) \\ &\quad \times \left( \int_{(t;B)} (x-t)^{\alpha-\beta^j-1} \exp(-\tau|x-t|_+) x^{-\mu^j} dx \right) dt / \Gamma(\alpha - \beta^j). \end{aligned}$$

Note that

$$\int_{(t;B)} (x-t)^{\alpha-\beta^j-1} \exp(-\tau|x-t|_+) x^{-\mu^j} dx \leq \int_{\mathbb{R}_+^n} \zeta^{\alpha-\beta^j-\mu^j-1} \exp(-\tau|\zeta|_+) d\zeta$$

and hence,

$$\begin{aligned} \|Ts^1 - Ts^2\|_{1,\tau} &\leq c_L \|s^1 - s^2\|_{1,\tau} \\ &\quad \times \sum_{j=1}^r \Gamma(\alpha - \beta^j - \mu^j) \tau^{|\beta^j + \mu^j - \alpha|_+} / \Gamma(\alpha - \beta^j) \\ &\leq \frac{1}{2} \|s^1 - s^2\|_{1,\tau}. \end{aligned}$$

The argument in the remaining cases is analogous.

Thus,  $T$  is a contraction with contraction constant 1/2. Moreover,  $\|Ts\|_{1,\tau} \leq \frac{1}{2} \|s\|_{1,\tau}$ , which proves that  $Ts \in L^1(\Omega)$  provided that  $s \in L^1(\Omega)$ .

The proof is completed by using the Banach fixed point theorem.

Lemma 2.2 immediately implies

**THEOREM 2.2.** *If Assumptions I<sub>2</sub>, II<sub>1</sub> and III are satisfied, then problem (P) has exactly one solution.*

**Remark 2.6** (cf. also Remark 2.4). Let  $\Omega = \mathbb{R}_+^n$  and let  $(B^k)_{k=1}^\infty$  be the increasing sequence defined in Remark 2.4. By Theorem 2.2, for every  $k \in \mathbb{N}$  there exists exactly one solution  $u^k$  of problem (P) in  $\Omega^k$  and hence the function  $u(x) := u^k(x)$  for  $x \in \Omega^k \setminus \Omega^{k-1}$ ,  $k \in \mathbb{N}$ , is a solution of (P) in  $\Omega$  such that  $\mathcal{D}^\alpha u$  is locally integrable. Moreover,  $\mathcal{D}^\alpha u$  belongs to the Banach space

$$(2.16) \quad L_\tau^1(\mathbb{R}_+^n) := \left\{ f : \mathbb{R}_+^n \rightarrow \mathbb{R} : f \text{ measurable and} \right. \\ \left. \|s\|_{1,\tau} := \int_{\mathbb{R}_+^n} |s(x)| \exp(-\tau|x|_+) dx < \infty \right\}$$

with  $\tau$  being defined by (2.15). Note that  $L^1(\Omega_*) \subset L_\tau^1(\Omega_*) \subset L_{\text{loc}}^1(\Omega_*)$  for every  $\Omega_* \subset \mathbb{R}_+^n$  and  $\tau > 0$ .

Conversely, if  $u$  is a solution of problem (P) in  $\Omega$  such that  $\mathcal{D}^\alpha u$  is locally integrable then, by the uniqueness of the solution of (P) in  $\Omega^k$ , the function  $u^k(x) := u(x)$  for  $x \in \Omega^k$ ,  $k \in \mathbb{N}$ , is the unique solution of (P) in  $\Omega^k$  such that  $\mathcal{D}^\alpha u^k$  is integrable. It being so for every  $k$ , the uniqueness of the solution of (P) in  $\Omega$  is proved.

**4. Continuous solutions.** Set  $s(x) := x^{p-\alpha} \mathcal{D}^\alpha u(x)$ . In this section we examine the existence of solutions of problem (P) such that  $s$  is bounded and continuous in  $\Omega$ . Observe that if  $u$  is a solution of (P), then  $s$  is a solution of the integral equation

$$(2.17) \quad \begin{aligned} s(x) &= T_C s(x) \\ &:= x^{p-\alpha} F(x, \{\mathcal{D}^{\beta^j} w(x) + \mathcal{D}^{\beta^j - \alpha}(x^{\alpha-p} s(x))\}), \quad x \in \Omega. \end{aligned}$$

Denote by  $BC(\Omega)$  the space of bounded continuous functions defined on  $\Omega$ , with the norm

$$(2.18) \quad |s|_\tau := \sup_{x \in \Omega} \{|s(x) \exp(-\tau|x|_+)\|,$$

where  $\tau$  is a fixed nonnegative number.  $BC(\Omega)$  is a Banach space. Moreover, for positive  $\tau$ , the norms  $|\cdot|_0$  and  $|\cdot|_\tau$  are equivalent.

We assume the following:

I<sub>3</sub>. The function  $F$  is continuous, satisfies the Lipschitz condition in the last  $r$  variables (cf. Assumption I<sub>1</sub>) and there exists a constant  $c_F$ , independent of  $x \in \Omega$ , such that

$$(2.19) \quad |F(x, \{\mathcal{D}^{\beta^j} w(x)\})| \leq c_F x^{\alpha-p}, \quad x \in \Omega,$$

where  $w$  is given by (2.4).

III<sub>1</sub>. The functions  $M_l$  ( $1 \leq |(\text{sgn } l_i)|_+ < n; l \leq p$ ) are continuous.

We need

PROPOSITION 2.1. *If  $\mu, \nu, \tau > 0$  and  $z > 0$ , then*

$$(2.20) \quad z^{1-\nu} \int_0^z (z-\zeta)^{\nu-1} \zeta^{\mu-1} \exp(-\tau\zeta) d\zeta \leq \text{const } \tau^{-\mu},$$

where const is independent of  $z$ .

Proof. Denoting by  $I(z)$  the left-hand side of (2.20) and changing variables, we have

$$I(z) = z^\mu \int_0^1 (1-\xi)^{\nu-1} \xi^{\mu-1} \exp(-\tau z \xi) d\xi.$$

Observe that

$$\begin{aligned} & z^\mu (1-\xi)^{\nu-1} \xi^{\mu-1} \exp(-\tau z \xi) \\ & \leq \begin{cases} \max(1, 2^{1-\nu}) z^\mu \xi^{\mu-1} \exp(-\tau z \xi) & \text{for } 0 \leq \xi < 1/2, \\ 2(1-\xi)^{\nu-1} \Gamma(\mu+1) \tau^{-\mu} & \text{for } 1/2 < \xi \leq 1. \end{cases} \end{aligned}$$

As a result,  $I(z) \leq \max(1, 2^{1-\nu}) \Gamma(\mu) (1 + \mu/\nu) \tau^{-\mu}$ , and the proof is complete.

LEMMA 2.3. *If the functions  $F$  and  $M_l$  satisfy Assumptions  $I_3$  and  $III_1$ , respectively, then equation (2.17) has exactly one solution of class  $BC(\Omega)$ . Moreover, if  $s$  is a solution of (2.17), then*

$$(2.21) \quad |s(x)| \leq 2c_F \exp(\tau|x|_+), \quad x \in \Omega,$$

where  $\tau$  is a fixed nonnegative number.

Proof. By Assumptions  $I_3$  and  $III_1$ , the function  $T_C s$  (cf. (2.17)) is continuous for  $s \in BC(\Omega)$ . Let  $s^1, s^2 \in BC(\Omega)$ ,  $\beta^j < \alpha$  ( $j = \overline{1, r}$ ) and observe that, by Assumption  $I_3$  and definition (2.18), we get

$$\begin{aligned} & |T_C s^1(x) - T_C s^2(x)| \exp(-\tau|x|_+) \leq c_L x^{p-\alpha} |s^1 - s^2|_\tau \\ & \quad \times \sum_{j=1}^r \int_{(0;x)} (x-t)^{\alpha-p} t^{\alpha-\beta^j-1} \exp(-\tau|t|_+) dt / \Gamma(\alpha - \beta^j), \quad x \in \Omega. \end{aligned}$$

It follows from Proposition 2.1 and definition (2.18) that

$$|T_C s^1 - T_C s^2|_\tau \leq \text{const} |s^1 - s^2|_\tau \sum_{j=1}^r \tau^{|\beta^j - \alpha|_+},$$

where const is independent of  $s^1$  and  $s^2$ . This inequality also holds for  $\beta^j \leq \alpha$ ,  $|\beta^j|_+ < |\alpha|_+$  ( $j = \overline{1, r}$ ). Hence, for fixed  $\tau$  such that (cf. the proof of Lemma 2.2)

$$\text{const} \sum_{j=1}^r \tau^{|\beta^j + \mu^j - \alpha|_+} \leq 1/2,$$

$T_C$  is contractive. Moreover,  $|T_C s|_\tau \leq \frac{1}{2}|s|_\tau + c_F$  and hence  $|T_C s|_\tau$  is finite provided that  $s \in BC(\Omega)$ .

Notice that if  $s$  is a solution of (2.17), then  $|s|_\tau \leq 2c_F$  and so inequality (2.21) is valid.

Using the Banach fixed point theorem we easily conclude the proof.

REMARK 2.7. The function  $u(x) := w(x) + \mathcal{D}^{-\alpha}(x^{\alpha-p}s(x))$ , with  $s$  being a continuous solution of equation (2.17), is a solution of problem (P). Moreover,

if the  $M_l$  satisfy Assumption III<sub>1</sub> then the derivatives  $\mathcal{D}^m u$  ( $m = (m_i) \in \mathbb{N}_0^n$ ;  $m_i = 0, [\alpha_i], i = \overline{1, n}$ ) exist in  $\Omega$  (cf. also Lemma 1.7), are continuous and

$$(2.22) \quad |\mathcal{D}^m u(x)| \leq |\mathcal{D}^m w(x)| + \text{const } \tau^{m-\alpha} x^{\alpha-p} \exp(\tau|x|_+), \quad x \in \Omega.$$

The foregoing considerations yield

**THEOREM 2.3.** *If the functions  $F$  and  $M_l$  satisfy Assumptions I<sub>3</sub> and III<sub>1</sub>, respectively, then the  $n$ -dimensional characteristic problem (2.1), (2.2) has a solution  $u$ . This solution is such that  $x^{p-\alpha} \mathcal{D}^\alpha u \in BC(\Omega)$ ,  $\mathcal{D}^m u \in C(\Omega)$  ( $m = (m_i) \in \mathbb{N}_0^n$ ;  $m_i = 0, [\alpha_i], i = \overline{1, n}$ ) and estimates (2.22) hold.*

### 5. Continuous dependence of the solution on the boundary data.

Let  $u^1$  and  $u^2$  be two solutions of problem (P) with  $M_l^1$  and  $M_l^2$  being the corresponding boundary data (cf. conditions (2.2)).

Assume the following:

I<sub>4</sub>. The function  $F$  satisfies the Carathéodory conditions and

$$(2.23) \quad |F(x, \{z_j^1\}) - F(x, \{z_j^2\})| \leq \sum_{j=1}^r a_j(x) |z_j^1 - z_j^2| \quad \text{a.e. in } \Omega, \quad z_j^1, z_j^2 \in \mathbb{R},$$

where  $a_j : \Omega \rightarrow \mathbb{R}_+$  are bounded and such that  $a_j(x) \mathcal{D}^{\beta_j} (w^1(x) - w^2(x))$  are integrable, where  $w^1$  and  $w^2$  are given by (2.4) with  $M$  replaced by  $M_l^1$  and  $M_l^2$ , respectively.

II<sub>2</sub>. The functions  $M_l^1$  and  $M_l^2$  satisfy Assumption III and

$$\|w^1 - w^2\|_{1,0} < \delta_0 \quad \text{and} \quad \|a_j \mathcal{D}^{\beta_j} (w^1 - w^2)\|_{1,0} < \delta_j,$$

where  $\delta_j$  ( $j = \overline{0, r}$ ) are given positive numbers.

Let  $s^1 := \mathcal{D}^\alpha u^1$  and  $s^2 := \mathcal{D}^\alpha u^2$ . By (2.5) and (2.23), we have

$$|s^1(x) - s^2(x)| \leq \sum_{j=1}^r |a_j(x) \mathcal{D}^{\beta_j} (w^1(x) - w^2(x))| + c \sum_{j=1}^r \mathcal{D}^{\beta_j - \alpha} |s^1(x) - s^2(x)|,$$

where  $c := \max_{j,x} a_j(x)$ . The above inequality implies

$$\mathcal{D}^{-\alpha} |s^1(x) - s^2(x)| \leq V(x) + c \sum_{j=1}^r \mathcal{D}^{\beta_j - \alpha} (\mathcal{D}^{-\alpha} |s^1(x) - s^2(x)|),$$

with

$$V(x) := \sum_{j=1}^r \mathcal{D}^{-\alpha} (a_j(x) |\mathcal{D}^{\beta_j} (w^1(x) - w^2(x))|).$$

By Lemma 1.6, we have the estimate

$$\mathcal{D}^{-\alpha} |s^1(x) - s^2(x)| \leq V(x) + \sum_{k=1}^{\infty} \sum_{1 \leq j^1, \dots, j^k \leq r} c^k \mathcal{D}^{\beta^{(j,k)} - k\alpha} V(x)$$



where  $\beta^{(j,k)} := \beta^{j^1} + \dots + \beta^{j^k}$ , and the series is convergent. Formula (2.3) and the above estimate yield

$$|u^1(x) - u^2(x)| \leq |w^1(x) - w^2(x)| + V(x) + \sum_{k=1}^{\infty} \sum_{1 \leq j^1, \dots, j^k \leq r} c^k \mathcal{D}^{\beta^{(j,k)} - k\alpha} V(x),$$

whence

$$(2.25) \quad \|u^1 - u^2\|_{1,0} \leq \delta_0 + \sum_{j=1}^r \delta_j \left( \sum_{k=1}^{\infty} \sum_{1 \leq j^1, \dots, j^k \leq r} c^k B^{k\alpha - \beta^{(j,k)}} / \Gamma(\mathbf{1} + k\alpha - \beta^{(j,k)}) \right)$$

with the series appearing in (2.25) being convergent.

It follows from inequality (2.25) that the following theorem is valid:

**THEOREM 2.4.** *If Assumptions I<sub>4</sub> and II<sub>2</sub> are satisfied, then the solutions of problem (P) depend continuously on the boundary data, i.e. for every  $\varepsilon > 0$  there is a  $\delta > 0$  such that if  $\delta_j < \delta$  ( $j = \overline{0, r}$ ) then for any two solutions  $u^1$  and  $u^2$  of problem (P) with boundary functions  $M_l^1$  and  $M_l^2$ , respectively, the estimate  $\|u^1 - u^2\|_{1,0} < \varepsilon$  holds.*

**Remark 2.8.** One can observe that if Assumptions I<sub>2</sub>, I<sub>4</sub>, II<sub>1</sub>, II<sub>2</sub>, and III are satisfied then problem (P) is well posed in the space of integrable functions with integrable derivatives of order  $\alpha$ .

### III. Noncharacteristic boundary value problem

**1. The problem.** In this section, which extends earlier research of J. Conlan (cf. [7]) and the present author (cf. [28]), we deal with the counterpart of Z. Szymdt's problem (cf. [44]) for a partial differential equation of noninteger order with two independent variables.

Let  $\Omega := (0, A) \times (0, B)$ , where  $0 < A, B < \infty$ . Assume that  $\alpha, \beta > 0$  and set  $q_1 := -[-\alpha]$ ,  $q_2 := -[-\beta]$ .

For  $i = \overline{1, q_1}$  and  $j = \overline{1, q_2}$ , let  $g_j : [0, A] \rightarrow [0, B]$ ,  $h_i : [0, B] \rightarrow [0, A]$ ,  $G_j : (0, A) \rightarrow \mathbb{R}$ , and  $H_i : (0, B) \rightarrow \mathbb{R}$  be given functions (the curves of equations  $y = g_j(x)$  and  $x = h_i(y)$  will be denoted by  $l_j^1$  and  $l_i^2$ , respectively),  $(x_{ij}, y_{ij})$  fixed points of  $\overline{\Omega}$  and  $u_{ij}^0$  given numbers.

We deal with the partial differential equation

$$(3.1) \quad \mathcal{D}_x^\alpha \mathcal{D}_y^\beta u(x, y) = F(x, y, \{\mathcal{D}_x^\gamma \mathcal{D}_y^\lambda u(x, y)\}), \quad (x, y) \in \Omega,$$

where  $\{\mathcal{D}_x^\gamma \mathcal{D}_y^\lambda u\}$  is the finite sequence of  $\mathcal{D}_x^\gamma \mathcal{D}_y^\lambda u$  such that  $\gamma \leq \alpha$ ,  $\lambda \leq \beta$ , and  $\gamma + \lambda < \alpha + \beta$  (the total number of these derivatives will be denoted by  $r$ ).

We study the problem (S) which consists in finding a solution of equation (3.1) in  $\Omega$  (cf. Section II.1) satisfying

$$(3.2) \quad \mathcal{D}_x^\alpha \mathcal{D}_y^{\beta-j} u(x, g_j(x)) = G_j(x), \quad \mathcal{D}_x^{\alpha-i} \mathcal{D}_y^\beta u(h_i(y), y) = H_i(y),$$

$$(3.3) \quad \mathcal{D}_x^{\alpha-i} \mathcal{D}_y^{\beta-j} u(x_{ij}, y_{ij}) = u_{ij}^0.$$

( $i = \overline{1, q_1}$ ;  $j = \overline{1, q_2}$ ). The above problem was considered by Z. Szmydt (in the paper quoted above), in the case when  $\alpha, \beta \in \mathbb{N}$ , as a generalization of the classical Goursat problem.

We assume the following:

I. The function  $F : \Omega \times \mathbb{R}^r \rightarrow \mathbb{R}$  satisfies the Carathéodory conditions and

$$(3.4) \quad |F(x, y, \{z_{\gamma\lambda}\})| \\ \leq K(x, y) + \sum_{\gamma, \lambda} \sum_{l=1}^{r_{\gamma\lambda}} K_{\gamma\lambda l}(x, y) |z_{\gamma\lambda}|^{\kappa_{\gamma\lambda l}} \quad \text{a.e. in } \Omega, \quad z_{\gamma\lambda} \in \mathbb{R},$$

where  $r_{\gamma\lambda} \in \mathbb{N}$ ,  $0 < \kappa_{\gamma\lambda l} \leq 1$ , and  $K, K_{\gamma\lambda l} : \Omega \rightarrow \mathbb{R}_+$  are given functions of class  $L^1(\Omega)$  and  $L^{1/(1-\kappa_{\gamma\lambda l})}(\Omega)$ , respectively.

II. The functions  $g_j$  and  $h_i$  ( $i = \overline{1, q_1}$ ;  $j = \overline{1, q_2}$ ) are continuous.

III. The functions  $G_j$  and  $H_i$  ( $i = \overline{1, q_1}$ ;  $j = \overline{1, q_2}$ ) are integrable.

IV. The functions  $x^{\alpha-\gamma-k}/\Gamma(1+\alpha-\gamma-k)$  and  $y^{\beta-\lambda-l}/\Gamma(1+\beta-\lambda-l)$  ( $k = \overline{1, q_1}$ ;  $l = \overline{1, q_2}$ ) are integrable.

**2. Local solutions of the problem.** Let  $s = \mathcal{D}_x^\alpha \mathcal{D}_y^\beta u$ . By an argument analogous to that in [6] (cf. also [23], p. 99) one can establish

LEMMA 3.1. *If  $u$  is a solution of equation (3.1) in  $\Omega$ , then there are integrable functions  $\varphi_j : (0, A) \rightarrow \mathbb{R}$  and  $\psi_i : (0, B) \rightarrow \mathbb{R}$ , and constants  $c_{ij} \in \mathbb{R}$  ( $i = \overline{1, q_1}$ ;  $j = \overline{1, q_2}$ ) such that*

$$(3.5) \quad u(x, y) = \sum_{k=1}^{q_1} \sum_{l=1}^{q_2} c_{kl} x^{\alpha-k} y^{\beta-l} / (\Gamma(1+\alpha-k)\Gamma(1+\beta-l)) \\ + \sum_{k=1}^{q_1} x^{\alpha-k} \psi_k^{(-\beta)}(y) / \Gamma(1+\alpha-k) \\ + \sum_{l=1}^{q_2} \varphi_l^{(-\alpha)}(x) y^{\beta-l} / \Gamma(1+\beta-l) + \mathcal{D}_x^{-\alpha} \mathcal{D}_y^{-\beta} s(x, y)$$

( $\varphi^{(-\alpha)}(x) := \mathcal{D}_x^{-\alpha} \varphi(x)$ ;  $\psi^{(-\beta)}(y) := \mathcal{D}_y^{-\beta} \psi(y)$ ).

Conversely, if  $u$  is given by (3.5) with some integrable  $\varphi_j : (0, A) \rightarrow \mathbb{R}$  and  $\psi_i : (0, B) \rightarrow \mathbb{R}$ , and  $c_{ij} \in \mathbb{R}$ , then  $u$  is a solution of (3.1) in  $\Omega$ .

Imposing on  $u$  (cf. (3.5)) conditions (3.2) and (3.3), we obtain

$$(3.6) \quad \begin{aligned} \varphi_j(x) = G_j(x) - \sum_{l=1}^{j-1} \varphi_l(x) [g_j(x)]^{j-l} / (j-l)! \\ - \int_0^{g_j(x)} [g_j(x) - \eta]^{j-1} s(x, \eta) d\eta / (j-1)!, \end{aligned}$$

$$(3.7) \quad \begin{aligned} \psi_i(y) = H_i(y) - \sum_{k=1}^{i-1} [h_i(y)]^{i-k} \psi_k(y) / (i-k)! \\ - \int_0^{h_i(y)} [h_i(y) - \xi]^{i-1} s(\xi, y) d\xi / (i-1)! \end{aligned}$$

and

$$(3.8) \quad \begin{aligned} c_{ij} = u_{ij}^0 - \left( \sum_{\substack{1 \leq k \leq i, 1 \leq l \leq j \\ k+l < i+j}} c_{kl} x_{ij}^{i-k} y_{ij}^{j-l} / ((i-k)!(j-l)!) \right) \\ + \sum_{k=1}^i x_{ij}^{i-k} \psi_k^{(-j)}(y_{ij}) / (i-k)! + \sum_{l=1}^j \varphi_l^{(-i)}(x_{ij}) y_{ij}^{j-l} / (j-l)! \\ + \int_0^{x_{ij}} d\xi \int_0^{y_{ij}} (x_{ij} - \xi)^{i-1} (y_{ij} - \eta)^{j-1} s(\xi, \eta) d\eta / ((i-1)!(j-1)!) \end{aligned}$$

( $i = \overline{1, q_1}$ ;  $j = \overline{1, q_2}$ ).

Note that  $\varphi_j$ ,  $\psi_i$  and  $c_{ij}$  depend on  $s$  but each of them can be represented as the sum of two terms the first of which depends linearly on  $s$  and the second is independent of  $s$  (depends only on the boundary data).

Observe that

$$(3.9) \quad \begin{aligned} \int_0^A |\varphi_j(x)| dx \leq \text{const}(1 + \|s\|_{1,\tau}), \\ \int_0^B |\psi_i(y)| dy \leq \text{const}(1 + \|s\|_{1,\tau}) \end{aligned}$$

( $i = \overline{1, q_1}$ ;  $j = \overline{1, q_2}$ ), where  $\|\cdot\|_{1,\tau}$  is the norm in  $L^1(\Omega)$  defined in (1.6), and  $\text{const}$ , here and in the sequel, does not depend on  $s$ . Using the Fubini theorem and (3.9), we get

$$(3.10) \quad \begin{aligned} \int_0^A |\varphi_j^{(-\alpha)}(x)| dx \leq \text{const} A^\alpha (1 + \|s\|_{1,\tau}), \\ \int_0^B |\psi_i^{(-\beta)}(y)| dy \leq \text{const} B^\beta (1 + \|s\|_{1,\tau}). \end{aligned}$$

Thus (cf. (3.9) and (3.10)), we have

$$(3.11) \quad |c_{ij}| \leq \text{const}(1 + \|s\|_{1,\tau}).$$

Set

$$(3.12) \quad \begin{aligned} L_{\gamma\lambda}s(x, y) &= \sum_{k=1}^{q_1} \sum_{l=1}^{q_2} c_{kl} x^{\alpha-\gamma-k} y^{\beta-\lambda-l} / (\Gamma(1+\alpha-\gamma-k)\Gamma(1+\beta-\lambda-l)) \\ &\quad + \sum_{k=1}^{q_1} x^{\alpha-\gamma-k} \psi_k^{(\lambda-\beta)}(y) / \Gamma(1+\alpha-\gamma-k) \\ &\quad + \sum_{l=1}^{q_2} \varphi_l^{(\gamma-\alpha)}(x) y^{\beta-\lambda-l} / \Gamma(1+\beta-\lambda-l) + \mathcal{D}_x^{\gamma-\alpha} \mathcal{D}_y^{\lambda-\beta} s(x, y) \end{aligned}$$

with  $c_{ij}$ ,  $\varphi_j$  and  $\psi_i$  ( $i = \overline{1, q_1}$ ;  $j = \overline{1, q_2}$ ) being given by (3.6)–(3.8), respectively. Observe that Problem (S) is equivalent to the integro-functional equation

$$(3.13) \quad s(x, y) = T_s s(x, y) := F(x, y, \{L_{\gamma\lambda}s(x, y)\}), \quad (x, y) \in \Omega.$$

Now, we prove that equation (3.13) has at least one solution. To this end consider the transformation  $T_s$  on  $L^1(\Omega)$ . Clearly,  $T_s$  is the composition of two transformations: the affine transformation  $L_{\gamma\lambda}$  (cf. [39], pp. 170, 171) and the substitution operator  $\mathcal{F}$  (cf. Remark 2.2).

It follows from Assumption IV, and from the inequality

$$(3.14) \quad \|L_{\gamma\lambda}s^1 - L_{\gamma\lambda}s^2\|_{1,\tau} \leq \text{const} A^{\alpha-\gamma} B^{\beta-\lambda} \|s^1 - s^2\|_{1,\tau}, \quad s^1, s^2 \in L^1(\Omega),$$

resulting from (3.7)–(3.12), that  $L_{\gamma\lambda}$  is a continuous mapping of  $L^1(\Omega)$  into itself. By an argument based on the Riesz compactness theorem (cf. [12], p. 166) one can prove

**LEMMA 3.2.** *If  $\gamma < \alpha$  and  $\lambda < \beta$ , then the transformation  $L_{\gamma\lambda} : L^1(\Omega) \rightarrow L^1(\Omega)$  is completely continuous.*

By Assumptions I and III, the substitution operator is continuous from  $L^1(\Omega)$  into itself (cf. [16], Th. 12.10), whence and by the continuity of  $L_{\gamma\lambda}$ ,  $T_s$  is also continuous. Moreover, by Lemma 3.2, it is completely continuous in the case  $\gamma < \alpha$ ,  $\lambda < \beta$ .

Note that in that case, Lemma 3.2 implies the complete continuity of the transformation defined by the right-hand side of (3.5), where  $c_{ij}$ ,  $\varphi_i$  and  $\psi_i$  ( $i = \overline{1, q_1}$ ;  $j = \overline{1, q_2}$ ) are given by (3.6)–(3.8), respectively.

Consider the set  $B_\varrho := B_0(\varrho + \varrho_K)$ , where  $\varrho_K := \|K\|_{1,\tau}$  and  $\varrho$  is a positive number, and its relatively compact subset  $Z_\varrho := Z_0(\varrho + \varrho_K)$  (cf. (2.10), (2.12)).

Let  $s \in L^1(\Omega)$ . We have the estimate (cf. (3.4))

$$(3.15) \quad |T_s s(x, y)| \leq K(x, y) + \sum_{\gamma, \lambda} \sum_{l=1}^{r_{\gamma\lambda}} K_{\gamma\lambda l}(x, y) |L_{\gamma\lambda} s(x, y)|^{\kappa_{\gamma\lambda l}}.$$

By the Hölder inequality and (3.14), (3.15), we get

$$\begin{aligned} \|T_s s\|_{1, \tau} &\leq \varrho_K + \sum_{\gamma, \lambda} \sum_{l=1}^{r_{\gamma\lambda}} \|K_{\gamma\lambda l}^{1/(1-\kappa_{\gamma\lambda l})}\|_{1, \tau}^{1-\kappa_{\gamma\lambda l}} \\ &\quad \times (A^{\alpha-\gamma} B^{\beta-\lambda} / (\Gamma(1+\alpha-\gamma)\Gamma(1+\beta-\lambda))) (1 + \|s\|_{1, \tau}^{\kappa_{\gamma\lambda l}}), \end{aligned}$$

whence

$$(3.16) \quad \|T_s\|_{1, \tau} \leq \varrho_K + c_T \mathcal{A} (1 + \|s\|_{1, \tau}^{\kappa}),$$

where  $c_T$  is a positive constant independent of  $s$ ,  $\mathcal{A} := \max(A, B)$ , and  $\kappa := \max_{\gamma, \lambda, l} \kappa_{\gamma\lambda l}$ .

Obviously, the condition

$$(3.17) \quad c_T \mathcal{A} (1 + (\varrho_K + \varrho)^\kappa) \leq \varrho.$$

is sufficient for the inclusion  $T_s(B_\varrho) \subset B_\varrho$ .

Let us distinguish two cases: (a)  $\kappa < 1$ , (b)  $\kappa = 1$ .

In case (a), inequality (3.17) is satisfied provided that

$$\varrho \geq \max(2c_T \mathcal{A} + \varrho_K, (2c_T \mathcal{A})^{1/(1-\kappa)} - \varrho_K).$$

In case (b), (3.17) holds if

$$\mathcal{A} < 1/c_T \quad \text{and} \quad \varrho \geq c_T \mathcal{A} (1 + \varrho_K) / (1 - c_T \mathcal{A}).$$

By the continuity of  $T_s$ , we infer that  $T_s(\bar{Z}_\varrho)$  is a compact subset of  $L^1(\Omega)$  and hence it is the closure of a set which is uniformly continuous in average.

Thus, the inclusion  $T_s(\bar{Z}_\varrho) \subset \bar{Z}_\varrho$  holds. By the Schauder fixed point theorem, equation (3.13) has an integrable solution. Moreover, if  $s$  is a solution to (3.13) then, by (3.16),  $\|s\|_{1, \tau} \leq \varrho_0$ , where the real  $\varrho = \varrho_0$  is a solution of (3.17).

The foregoing considerations establish

**THEOREM 3.1.** *If Assumptions I–IV are satisfied, then problem (S) has a global solution in the case  $\kappa < 1$  and a local one in the case  $\kappa = 1$  (cf. the discussion subsequent to (3.17)). These solutions are continuous when  $\alpha, \beta \in \mathbb{N}$ .*

**3. Extension of the local solution.** In this section we extend a local solution of problem (S) to a global one in the case  $\kappa = 1$ .

First of all we consider the problem  $(S_0)$ , that is, problem (S) in which

$$(3.18) \quad \kappa = 1, \quad \lambda < \beta, \quad y_{ij} = 0, \quad g_j \equiv 0 \quad (i = \overline{1, q_1}; j = \overline{1, q_2}).$$

As a result,  $\varphi_j = G_j$  and  $c_{ij} = u_{ij}^0$  ( $i = \overline{1, q_1}; j = \overline{1, q_2}$ ). Clearly,  $(S_0)$  is a counterpart of the Picard problem.

Equip  $L^1(\Omega)$  with the norm

$$(3.19) \quad |s|_\tau := \int_\Omega |s(x, y)| \exp(-\tau y) \, dx \, dy,$$

where  $\tau$  is a positive number. Using the Hölder inequality, we obtain

$$(3.20) \quad \int_\Omega K_{\gamma\lambda l}(x, y) |L_{\gamma\lambda} s(x, y)|^{\kappa_{\gamma\lambda l}} \exp(-\tau y) \, dx \, dy \\ \leq |K_{\gamma\lambda l}^{1/(1-\kappa_{\gamma\lambda l})}|_\tau^{1-\kappa_{\gamma\lambda l}} \left| \int_\Omega L_{\gamma\lambda} s(x, y) \exp(-\tau y) \, dx \, dy \right|^{\kappa_{\gamma\lambda l}}.$$

By direct calculation, we can easily show that

$$(3.21) \quad \int_\Omega \exp(-\tau y) x^{\alpha-\gamma-k} |\psi_j^{(\lambda-\beta)}(y)| \, dx \, dy \leq \text{const } \tau^{\lambda-\beta} A^{1+\alpha-\gamma-k} (1 + |s|_\tau),$$

$$(3.22) \quad \int_\Omega \exp(-\tau y) \mathcal{D}_x^{\gamma-\alpha} \mathcal{D}_y^{\lambda-\beta} |s(x, y)| \, dx \, dy \leq \text{const } \tau^{\lambda-\beta} A^{1+\alpha-\gamma-k} (1 + |s|_\tau).$$

Finally, we have

$$(3.23) \quad |T_s s|_\tau \leq \varrho_K + \text{const} \sum_{\gamma, \lambda} \sum_{l=1}^{r_{\gamma\lambda}} (1 + (\tau^{\lambda-\beta} (1 + |s|_\tau))^{\kappa_{\gamma\lambda l}}).$$

Hence, for  $\tau$  and  $\varrho$  sufficiently large to satisfy

$$(3.24) \quad \text{const} \sum_{\gamma, \lambda} \sum_{l=1}^{r_{\gamma\lambda}} (1 + (\tau^{\lambda-\beta} (1 + \varrho_K + \varrho))^{\kappa_{\gamma\lambda l}}) \leq \varrho,$$

$T_s$  continuously maps the compact  $\bar{Z}_{\varrho, \tau}$  (i.e.  $\bar{Z}_\varrho$  with  $\|\cdot\|_{1, \tau}$  replaced by  $|\cdot|_\tau$ ) into itself.

**LEMMA 3.3.** *If Assumptions I–IV and (3.18) are satisfied, then problem (S<sub>0</sub>) has a global solution.*

**Remark 3.1.** Lemma 3.3 is valid if condition (3.18) is replaced by

$$\kappa = 1, \quad \lambda < \alpha, \quad x_{ij} = 0, \quad h_i \equiv 0 \quad (i = \overline{1, q_1}; j = \overline{1, q_2}).$$

**Remark 3.2.** Since the right-hand sides of estimates (3.21) and (3.22) do not depend on  $B$ , one can show that if  $\Omega = (0, A) \times (0, \infty)$ , then equation (3.13) has a solution  $s$  in the class of measurable functions such that  $|s|_\tau < \infty$  (the parameters  $\tau$  in (3.19) and  $\varrho$  in the definition of  $B_\varrho$  are chosen so that inequality (3.24) is satisfied).

Replace Assumption II by

II<sub>1</sub>. The functions  $g_j$  and  $h_i$  ( $i = \overline{1, q_1}; j = \overline{1, q_2}$ ) are continuous, satisfy  $g_j(0) = h_i(0) = 0$  and the curves  $l_j^1$  and  $l_i^2$  do not intersect each other in  $\Omega$ .

Moreover, we also assume that  $\gamma < \alpha$ ,  $\lambda < \beta$  and  $x_{ij} = y_{ij} = 0$ .

Notice (cf. Theorem 3.1, (3.5) and (3.17)) that there exists a sufficiently small  $\delta > 0$  such that Problem (S) has a solution, say  $u_1$ , in  $(0, \delta)^2 \subset \Omega$ .

Now, we will use Lemma 3.3 to extend the local solution of Problem (S) (cf. [9] and [10]). To this end we assume that  $g_{q_2}(\delta) < \delta$  (in the opposite case  $h_{q_1}(\delta) < \delta$ ) and define  $a := \max\{x \in [\delta, A] : g_{q_2}(x) \leq \delta\}$ .

We seek a function  $u : (0, a) \times (0, \delta) \rightarrow \mathbb{R}$  such that  $u = u_1$  in  $(0, \delta)^2$ , which is a solution of equation (3.1) in  $(\delta, a) \times (0, \delta)$  and satisfies

$$\begin{aligned} \mathcal{D}_x^\alpha \mathcal{D}_y^{\beta-j} u(x, g_j(x)) &= G_j(x), & \mathcal{D}_x^{\alpha-i} \mathcal{D}_y^\beta u(\delta, y) &= \mathcal{D}_x^{\alpha-i} \mathcal{D}_y^\beta u_1(\delta, y), \\ \mathcal{D}_x^{\alpha-i} \mathcal{D}_y^{\beta-j} u(\delta, 0) &= \mathcal{D}_x^{\alpha-i} \mathcal{D}_y^{\beta-j} u_1(\delta, 0) \end{aligned}$$

$(x \in (\delta, a); y \in (0, \delta); i = \overline{1, q_1}; j = \overline{1, q_2})$ .

It can be shown by an argument analogous to that in the proof of Lemma 3.3 that there is a solution, say  $u_2$ , of the above problem.

Set  $b := \max\{y \in [\delta, B] : h_{q_1}(y) \leq a\}$ . Similarly to the above, we search for  $u : (0, a) \times (0, b) \rightarrow \mathbb{R}$  such that  $u = u_2$  in  $(0, a) \times (0, \delta)$ ,  $u$  is a solution of (3.1) in  $(0, a) \times (\delta, b)$  and

$$\begin{aligned} \mathcal{D}_x^\alpha \mathcal{D}_y^{\beta-j} u(x, \delta) &= \mathcal{D}_x^\alpha \mathcal{D}_y^{\beta-j} u_2(x, \delta), & \mathcal{D}_x^{\alpha-i} \mathcal{D}_y^\beta u(h_i(y), y) &= H_i(y), \\ \mathcal{D}_x^{\alpha-i} \mathcal{D}_y^{\beta-j} u(0, \delta) &= \mathcal{D}_x^{\alpha-i} \mathcal{D}_y^{\beta-j} u_2(0, \delta) \end{aligned}$$

$(x \in (0, a); y \in (\delta, b); i = \overline{1, q_1}; j = \overline{1, q_2})$ .

Denote by  $u_3$  a solution of the above problem. Clearly,  $u_3$  is a solution of (3.1) in  $(0, a) \times (0, b)$  and, moreover, satisfies (3.2) for  $x \in (0, a)$  and  $y \in (0, b)$ , and (3.3) with  $x_{ij} = y_{ij} = 0$ .

Continuing this process, we extend a local solution of problem (S) to get a global one.

**THEOREM 3.2.** *If Assumptions I, II<sub>1</sub>, III and IV (with  $\kappa = 1$ ,  $\gamma < \alpha$  and  $\lambda < \beta$ ) are satisfied, then problem (S) with  $x_{ij} = y_{ij} = 0$  has a global solution.*

## IV. Some problems for ordinary differential equations

### 1. Multipoint problem

**1.1. The problem.** Set  $n = 1$ ,  $\Omega := (0; B)$  and let  $r \in \mathbb{N}$ ,  $\alpha > 0$ ,  $\beta^l < \alpha$  ( $l = \overline{1, r}$ ) be fixed numbers. As usual, we set  $p := -[-\alpha]$  and denote by  $\{y^{(\beta^l)}\}$  the  $r$ -element sequence of  $y^{(\beta^l)}$ .

Consider the following nonlinear multipoint problem (M): Find a solution of the differential equation of noninteger order

$$(4.1) \quad y^{(\alpha)}(x) = F(x, \{y^{(\beta^l)}(x)\}), \quad x \in \Omega,$$

where  $F$  is given, with the multipoint conditions

$$(4.2) \quad \sum_{i=1}^p \left( \sum_{k=1}^{m_{ij}} z_{ijk} y^{(\alpha-i)}(x_{ijk}) + \int_0^B b_{ij}(x) y^{(\alpha-i)}(x) dx \right) = \eta_j$$

( $j = \overline{1, p}$ ), where  $0 \leq x_{ijk} \leq B$ ,  $m_{ij} \in \mathbb{N}$ ,  $z_{ijk}, \eta_j \in \mathbb{R}$  are fixed numbers and  $b_{ij} : \Omega \rightarrow \mathbb{R}$  given functions. This solution is understood analogously to the solution of (2.1).

A multipoint problem of similar type for a linear ordinary differential equation was posed by J. D. Tamarkin (cf. [43], p. 113 and references). If  $b_{ij} \equiv 0$ ,  $x_{ijk} = 0$  ( $i, j = \overline{1, p}; k = \overline{1, m_{ij}}$ ),  $m_{ij}$  and  $z_{ijk}$  are such that  $z_{ij1} + z_{ij2} + \dots + z_{ijm_{ij}} = \delta_{ij}$  ( $i, j = \overline{1, p}$ ), where  $\delta_{ij}$  is the Kronecker symbol, then (M) becomes the Cauchy problem.

The multipoint problem (M) also generalizes the Bellman problem (cf. [5]). Namely, on setting  $z_{ijk} = 0$  ( $i, j = \overline{1, p}; k = \overline{1, m_{ij}}$ ) and  $b_{ij} \equiv 0$  ( $i = \overline{1, p-1}; j = \overline{1, p}$ ), conditions (4.2) are reduced to those of Bellman type

$$\int_0^B b_{pj}(x)y^{(\alpha-p)}(x) dx = \eta_j \quad (j = \overline{1, p}),$$

where  $\eta_j \in \mathbb{R}$  and  $b_{pj}$  are given functions.

In the sequel we examine problem (M) by using the Schauder fixed point theorem.

We assume the following:

I. The function  $F : \Omega \times \mathbb{R}^r \rightarrow \mathbb{R}$  satisfies the Carathéodory conditions and

$$(4.3) \quad |F(x, \{z_l\})| \leq \sum_{l=1}^r \sum_{i=1}^{r_l} K_{il}(x)|z_l|^{\kappa_{il}} \quad \text{a.e. in } \Omega, \quad z_l \in \mathbb{R},$$

where  $r_l \in \mathbb{N}$ ,  $0 \leq \kappa_{il} \leq \kappa < 1$  are fixed numbers and  $K_{il} : \Omega \rightarrow \mathbb{R}$  given functions of class  $L^{1/(1-\kappa_{il})}$ .

II. The functions  $b_{ij}$  ( $i, j = \overline{1, p}$ ) are integrable and the matrix

$$(4.4) \quad W = \left[ \sum_{i=m}^p \left( \sum_{k=1}^{m_{ij}} z_{ijk} x_{ijk}^{i-m} + \int_0^B x^{i-m} b_{ij}(x) dx \right) / (i-m)! \right]_{1 \leq j, m \leq p}$$

is nonsingular (this assumption is satisfied for example in the case of the Cauchy and Bellman problems).

III. The functions  $x \rightarrow w^{(\beta^l)}(x)$  ( $l = \overline{1, r}$ ) are integrable.

**1.2. Solution of the problem.** Any solution  $y$  of (4.1) (cf. Lemma 1.7) is of the form

$$(4.5) \quad y(x) = w(x) + s^{(-\alpha)}(x),$$

where  $s := y^{(\alpha)}$  satisfies the equation

$$(4.6) \quad s(x) = T_M s(x) := F(x, \{w^{(\beta^l)}(x) + s^{(\beta^l - \alpha)}(x)\}), \quad x \in \Omega,$$

with

$$(4.7) \quad w(x) := \sum_{m=1}^p c_m x^{\alpha-m} / \Gamma(1 + \alpha - m)$$

and  $c_1, \dots, c_p$  being arbitrary constants.



Imposing on  $y$  (cf. (4.5)) the multipoint conditions (4.2), we have

$$(4.8) \quad \sum_{m=1}^p c_m \sum_{i=m}^p \left( \sum_{k=1}^{m_{ij}} z_{ijk} x_{ijk}^{i-m} + \int_0^B x^{i-m} b_{ij}(x) dx \right) / (i-m)! \\ = \eta_j - \sum_{i=1}^p \left( \sum_{k=1}^{m_{ij}} z_{ijk} s^{(-i)}(x_{ijk}) + \int_0^B b_{ij}(x) s(x) dx \right)$$

for  $j = \overline{1, p}$ .

By Assumption II and the Cramer formulae, we easily get

$$(4.9) \quad c_m = \sum_{j=1}^p (\det W^{mj} / \det W) \\ \times \left( \eta_j - \sum_{i=1}^p \left( \sum_{k=1}^{m_{ij}} z_{ijk} s^{(-i)}(x_{ijk}) + \int_0^B b_{ij}(x) s^{(-i)}(x) dx \right) \right)$$

( $m = \overline{1, p}$ ), where  $W^{mj}$  is the matrix obtained from  $W$  (cf. (4.4)) by deleting its  $m$ th row and  $j$ th column and then multiplying the result by  $(-1)^{m+j}$ .

We examine the transform  $T_M$  (cf. (4.6)), where  $w$  is given by (4.7) with the constants  $c_1, \dots, c_p$  defined by (4.9). This transform is the superposition of the operators  $N_l s := w^{(\beta^l)} + s^{(\beta^l - \alpha)}$  ( $l = \overline{1, r}$ ) and the substitution operator  $\mathcal{F}$ .

Define  $B_\varrho := \{s \in L^1(\Omega) : \|s\| \leq \varrho\}$ , where  $\|\cdot\|$  denotes the (standard) norm in  $L^1(\Omega)$ .

**PROPOSITION 4.1.** *Under Assumption III, the operators  $N_l$  are affine and completely continuous from  $L^1(\Omega)$  into  $L^1(\Omega)$ .*

**Proof.** By Assumption II and Lemma 1.1,  $N_l$  ( $l = \overline{1, r}$ ) maps  $L^1(\Omega)$  into itself. Moreover, the second term of  $N_l$  is linear and completely continuous.

Let  $s^1, s^2 \in L^1(\Omega)$ . By direct calculation we get

$$|c_m^1 - c_m^2| \leq \text{const} \|s^1 - s^2\| \sum_{i=1}^p \left( \sum_{k=1}^{m_{ij}} |z_{ijk}| B^{i-1} + \int_0^B x^{i-1} b_{ij}(x) dx \right)$$

( $m = \overline{1, p}$ ), where  $c_m^1, c_m^2$  are given by (4.9) with  $s$  replaced by  $s^1$  and  $s^2$ , respectively, and  $\text{const}$  (here and in the sequel) is a constant independent of  $s$ .

As a consequence, assuming that  $w^1$  and  $w^2$  are given by (4.7) with  $s$  replaced by  $s^1$  and  $s^2$ , respectively, we have  $\|w^1(\beta^l) - w^2(\beta^l)\| \leq \text{const} \|s^1 - s^2\|$ , which proves the continuity of the second term of  $N_l$ .

In order to prove the complete continuity of  $N_l$ , we use the Riesz theorem. Let  $s \in B_\varrho$ . By an argument analogous to that used above one can show that

$$\int_0^B |w^{(\beta^l)}(x)| dx \leq \sum_{m=1}^p |c_m| B^{1+\alpha-\beta^l-m} / \Gamma(1+\alpha-\beta^l-m) \leq \text{const}(1+\varrho).$$

Moreover, if  $h \in \mathbb{R}$  then

$$\begin{aligned} & \int_0^B |w^{(\beta^l)}(x+h) - w^{(\beta^l)}(x)| dx \\ & \leq \text{const}(1+\varrho) \sum_{m=1}^p (h^{1+\alpha-\beta^l-m} + h^{\min(1,1+\alpha-\beta^l-m)}) \rightarrow 0 \end{aligned}$$

for  $h \rightarrow 0$ , where const is independent of  $s$  and hence the convergence is uniform in  $s \in B_\varrho$ .

By the Riesz theorem,  $N_l$  maps  $B_\varrho$  into a relatively compact subset of  $L^1(\Omega)$ . Thus the proof is complete.

By Assumption I, we have

$$(4.10) \quad |T_M s(x)| \leq \sum_{l=1}^r \sum_{i=1}^{r_l} K_{il}(x) \times \left( \sum_{m=1}^p |c_m x^{\alpha-\beta^l-m} / \Gamma(1+\alpha-\beta^l-m)|^{\kappa_{il}} + |s^{(\beta^l-\alpha)}(x)|^{\kappa_{il}} \right) \quad \text{a.e. in } \Omega.$$

Notice that (4.9) yields  $|c_m| \leq \text{const}(1 + \|s\|)$  ( $m = \overline{1, p}$ ).

By the Hölder inequality and the Fubini theorem, we have

$$\|K_{il} |s^{(\beta^l-\alpha)}|^{\kappa_{il}}\| \leq \text{const} \|s\|^{\kappa_{il}} \quad (i = \overline{1, r_l}; l = \overline{1, r}).$$

Finally, we obtain  $\|T_M s\| \leq c_*(1 + \|s\|^\kappa)$ , where  $c_*$  is a positive constant independent of  $s$ .

Thus, if  $c_*(1 + \varrho^\kappa) \leq \varrho$  (it is sufficient to assume that  $\varrho \geq \max(2c_*, (2c_*)^{1/(1-\kappa)})$ ), then  $T_M$  maps  $B_\varrho$  into itself. Moreover, it is completely continuous (cf. Proposition 4.1).

Using the Schauder fixed point theorem we conclude that the set of solutions of (4.6) is nonempty and relatively compact in  $L^1(\Omega)$ .

**THEOREM 4.1.** *If Assumptions I–III are satisfied, then the multipoint problem (M) has a solution given by (4.5), where  $s$  is a solution of (4.6).*

**Remark 4.1.** The operator  $T_M$  given by (4.5) is completely continuous (cf. Proposition 4.1 with  $\beta_l = 0$ ) and hence the set of solutions of the considered multipoint problem is relatively compact.

## 2. Polarographic equation

**2.1. The Cauchy problem.** The equation

$$(4.11) \quad y^{(1/2)}(x) - \nu x^\beta y(x) = x^{-1/2}, \quad x > 0$$

( $-1/2 < \beta \leq 0$ ;  $\nu \in \mathbb{R}_+$ ) plays an important role in polarography (for chemical background cf. [17] and [31]–[33]). Notice that the above equation was examined

by K. Wiener in [48], [49] under the assumption that the derivative of noninteger order appearing in (4.11) is meant in the sense of Hadamard.

Let  $\alpha > 0$ . We consider the equation

$$(4.12) \quad y^{(\alpha)}(x) - \nu x^\beta y(x) = h(x), \quad x > 0,$$

where  $h$  is a given function and  $\nu \in \mathbb{R}_+$ ,  $\beta \in \mathbb{R}$  are fixed. We examine the Cauchy problem which consists in finding a function  $y \in L^1_{\text{loc}}(\mathbb{R}_+)$  with  $y^{(\alpha-1)}$  absolutely continuous, satisfying (4.12) a.e. in  $\mathbb{R}_+$  and fulfilling the initial conditions

$$(4.13) \quad y^{(\alpha-k)}(0) = c_k, \quad (k = \overline{1, p}),$$

where  $c_k$  are given constants.

It follows from Theorems 2.2 and 2.4 that, for  $\beta \geq 0$ ,  $x \in (0, A)$  with arbitrary positive  $A$ , and  $h \in L^1(0, A)$ , the Cauchy problem is well posed in a certain class of functions (cf. Remark 2.8 and Section 1.1).

In the sequel we examine (4.12), with negative  $\beta$ , in the Banach space  $L^1_\tau(\mathbb{R}_+)$  (cf. Remark 2.6) with some  $\tau$ .

Assume the following:

IV. The function  $h$  is in  $L^1_\tau(\mathbb{R}_+)$  and the number  $\beta \in (-\alpha, 0]$  is such that  $x^\beta w(x)$  belongs to  $L^1_\tau(\mathbb{R}_+)$  with  $\tau$  sufficiently large to satisfy

$$(4.16) \quad q := \nu \Gamma(\alpha + \beta) \tau^{-(\alpha+\beta)} / \Gamma(\alpha) < 1.$$

Write, as in Section 1.2,

$$s(x) := y^{(\alpha)}(x) \quad \text{and} \quad w(x) := \sum_{k=1}^p c_k x^{\alpha-k} / \Gamma(1 + \alpha - k).$$

The function  $s$  is a solution of the equation

$$(4.14) \quad s(x) = \nu x^\beta w(x) + h(x) + \nu x^\beta s^{(-\alpha)}(x),$$

whence  $y = w + s^{(-\alpha)}$  is a solution of the Cauchy problem for (4.12) with conditions (4.13).

For  $s \in L^1_\tau(\mathbb{R}_+)$ , define a transformation  $T_P$  by the formula

$$(4.15) \quad T_P s(x) := \nu x^\beta w(x) + h(x) + \nu x^\beta s^{(-\alpha)}(x).$$

Observe that

$$\begin{aligned} \|T_P s^1 - T_P s^2\|_{1, \tau} &\leq \nu \int_0^\infty x^\beta \exp(-\tau x) \left( \int_0^x (x-t)^{\alpha-1} |s^1(t) - s^2(t)| dt \right) dx / \Gamma(\alpha) \\ &\leq \nu \int_0^\infty |s^1(t) - s^2(t)| \exp(-\tau t) \\ &\quad \times \left( \int_t^\infty (x-t)^{\alpha-1} x^\beta \exp(-\tau(x-t)) dx \right) dt / \Gamma(\alpha). \end{aligned}$$

We examine the integral with respect to  $x$ . Changing variables and bearing in mind the definition of Euler's gamma function we have

$$\begin{aligned} & \int_t^\infty (x-t)^{\alpha-1} x^\beta \exp(-\tau(x-t)) dx \\ & \leq t^{\alpha+\beta} \int_0^\infty \xi^{\alpha-1} (1+\xi)^\beta \exp(-\tau t \xi) d\xi \leq \Gamma(\alpha+\beta) \tau^{-(\alpha+\beta)}, \end{aligned}$$

which implies

$$\|T_P s^1 - T_P s^2\|_{1,\tau} \leq \nu \Gamma(\alpha+\beta) \tau^{-(\alpha+\beta)} \|s^1 - s^2\|_{1,\tau} / \Gamma(\alpha) \leq q \|s^1 - s^2\|_{1,\tau}.$$

Thus, for  $\tau$  satisfying (4.16),  $T_P$  is contractive with contraction constant  $q$ . Moreover,  $T_P$  maps  $L_\tau^1(\mathbb{R}_+)$  into itself. Using the Banach fixed point theorem we conclude that there exists in  $L_\tau^1(\mathbb{R}_+)$  exactly one solution of (4.14). Thus,  $y = w + s^{(-\alpha)}$  is the only solution of the Cauchy problem for (4.12), (4.13) such that  $y^{(\alpha)} \in L_\tau^1(\mathbb{R}_+)$ .

By the above argument, the function

$$\begin{aligned} (4.17) \quad y(x) &= \sum_{n=1}^{\infty} (\nu/\Gamma(\alpha))^{n-1} \int_0^x K_n(x,t) t^{-\beta} h(t) dt / \Gamma(\alpha) \\ &+ \sum_{k=1}^p c_k x^{\alpha-k} \left( 1 + \sum_{l=1}^{\infty} (\nu x^{\alpha+\beta} / \Gamma(\alpha))^l \right. \\ &\left. \times \prod_{j=1}^l B(\alpha, j(\alpha+\beta) + 1 - k) \right) / \Gamma(1 + \alpha - k), \end{aligned}$$

where

$$K_n(x,t) = \begin{cases} (x-t)^{\alpha-1} t^\beta & \text{for } n=1, \\ \int_t^x K_n(x,\xi) K_1(\xi,t) d\xi & \text{for } n \geq 2, \end{cases}$$

and  $B$  is Euler's beta function, is a solution of the Cauchy problem for equation (4.12).

**THEOREM 4.2.** *If Assumption IV is satisfied, then there exists exactly one solution  $y$  of the Cauchy problem for equation (4.12) such that  $y^{(\alpha)} \in L_\tau^1(\mathbb{R}_+)$ . This solution is given by (4.17).*

**Remark 4.2.** The improper integral  $\int_0^\infty t^{\kappa-1} \exp(-\tau t) dt$  ( $\tau > 0$ ) is convergent if and only if  $\kappa > 0$ . Hence, the condition

$$c_k = 0 \text{ for } k \in \{1, \dots, p\} \text{ such that } 1 + \alpha + \beta - k \leq 0$$

is necessary and sufficient for the function  $x^\beta w(x)$  to be in  $L_\tau^1(\mathbb{R}_+)$ .

**Remark 4.3.** We point out two special cases. For  $\beta = 0$  the solution of

equation (4.12), say  $y^0$ , has the form

$$(4.18) \quad y^0(x) = \int_0^x t^{\alpha-1} E_{\alpha,\alpha}(\nu t^\alpha) h(x-t) dt + \sum_{k=1}^p c_k x^{\alpha-k} E_{\alpha,1+\alpha-k}(\nu x^\alpha),$$

where  $E_{\rho,\mu}$  is given by (1.11).

In the case  $h(x) = \gamma x^{\kappa-1}$  ( $\kappa > 0$ ), the function

$$\begin{aligned} y(x) &= (\gamma/\Gamma(\alpha)) x^{\alpha+\kappa-1} \sum_{n=0}^{\infty} (\nu x^{\alpha+\beta}/\Gamma(\alpha))^n \prod_{j=0}^n B(\alpha, j(\alpha+\beta) + \kappa) \\ &\quad + \sum_{k=1}^p c_k x^{\alpha-k} \left( 1 + \sum_{l=1}^{\infty} (\nu x^{\alpha+\beta}/\Gamma(\alpha))^l \right. \\ &\quad \left. \times \prod_{j=1}^n B(\alpha, j(\alpha+\beta) + 1 - k) \right) / \Gamma(1 + \alpha - k), \end{aligned}$$

is a solution of the Cauchy problem for (4.12). Moreover,  $y(x) = \gamma x^{\alpha+\kappa-1} \times (\Gamma(\alpha+\kappa)/\Gamma(\kappa) - \nu)^{-1}$  is a solution of (4.12) with  $\beta = -\alpha$  and  $\nu \neq \Gamma(\alpha+\kappa)/\Gamma(\kappa)$  (cf. also [49], pp. 165–166).

By Theorem 4.2 we can formulate the following corollaries.

**COROLLARY 4.1.** *Let Assumption IV be satisfied and  $c_k \geq 0$  ( $k = \overline{1, p}$ ),  $\nu \geq 0$ , and  $h \geq 0$  a.e. in  $(0, \delta) \subset (0, 1)$ . If  $y$  and  $y^0$  are two solutions of the Cauchy problem for equation (4.12) with  $\beta < 0$  and  $\beta = 0$ , respectively, then  $y > y^0 > 0$  a.e. in  $(0, \delta)$ . Moreover, if  $\alpha \notin \mathbb{N}$  and  $c_p > 0$ , then  $\lim_{x \rightarrow 0^+} y(x) = \infty$ .*

**Proof.** By induction, for every positive integer  $n$ ,

$$K_n(x, t) t^{-\beta} > (\Gamma(\alpha))^n (x-t)^{n\alpha-1} / \Gamma(n\alpha).$$

Furthermore, if  $x < 1$ , then

$$\begin{aligned} x^{\alpha+\beta} B(\alpha, j(\alpha+\beta) + 1 - k) &= x^{\alpha+\beta} \int_0^1 t^{\alpha-1} (1-t)^{j(\alpha+\beta)-k} dt \\ &> x^\alpha \int_0^1 t^{\alpha-1} (1-t)^{j\alpha-k} dt \\ &= x^\alpha B(\alpha, j\alpha + 1 - k). \end{aligned}$$

Hence, by (4.17) and (4.18), we get our assertion.

**COROLLARY 4.2.** *If Assumption IV is satisfied and  $c_k \geq 0$  ( $k = \overline{1, p}$ ),  $\sum_{k=1}^p |c_k| > 0$ ,  $\nu \geq 0$ ,  $h \geq 0$  a.e. in  $\mathbb{R}_+$ , and if  $y$  is a solution of (4.12), then  $y > 0$  a.e. in  $\mathbb{R}_+$  and  $\lim_{x \rightarrow \infty} y(x) = \infty$ .*

**2.2.** *Continuous dependence of the solution on the initial data.* If  $s = y^{(\alpha)} \in L^1_\tau(\mathbb{R}_+)$ , then  $y = w + s^{(-\alpha)}$  is measurable and

$$\|y\|_{1,\tau} \leq \tau^{-\alpha} \left( \sum_{k=1}^p c_k \tau^{k-1} + \|s\|_{1,\tau} \right),$$

whence  $y \in L^1_\tau(\mathbb{R}_+)$ .

**THEOREM 4.3.** *Let  $y^1$  and  $y^2$  be solutions of the Cauchy problem for equation (4.12) with the initial constants  $c_k^1$  and  $c_k^2$  ( $k = \overline{1, p}$ ), and right-hand sides  $h^1$  and  $h^2$ , and let Assumption IV be satisfied with  $h$  replaced by  $h^1$  or  $h^2$ , respectively. For every  $\varepsilon > 0$  there is a  $\delta > 0$  such that  $\max_{1 \leq k \leq p} |c_k^1 - c_k^2| < \delta$  and  $\|h^1 - h^2\|_{1,\tau} < \delta$  imply  $\|y^1 - y^2\|_{1,\tau} < \varepsilon$ .*

**Proof.** Let  $\widehat{\delta} = \max_{1 \leq k \leq p} |c_k^1 - c_k^2|$  and  $h(t) = |h^1(t) - h^2(t)|$ . For  $n \geq 2$ ,

$$K_n(x, t)t^{-\beta} \leq (x - t)^{n\alpha + \beta - 1} \prod_{j=1}^{n-1} B(\alpha, j\alpha + \beta).$$

Hence, by (4.17) and (1.6), we have

$$\begin{aligned} \|y^1 - y^2\|_{1,\tau} &\leq \|h\|_{1,\tau} \left( \tau^{-\alpha} + (\tau^{-\beta}/\nu) \sum_{l=2}^{\infty} (\nu\tau^{-\alpha}/\Gamma(\alpha))^l \Gamma((l+1)\alpha + \beta) \right. \\ &\quad \times \left. \prod_{j=1}^{l-1} B(\alpha, j\alpha + \beta) \right) + \widehat{\delta} \sum_{k=1}^p \tau^{-(1+\alpha-k)} \left( 1 + \sum_{l=1}^{\infty} (\nu\tau^{-(\alpha+\beta)}/\Gamma(\alpha))^l \right. \\ &\quad \times \left. \Gamma(1 + \alpha - k + l(\alpha + \beta))/\Gamma(1 + \alpha - k) \prod_{j=1}^l B(\alpha, j(\alpha + \beta) + 1 - k) \right). \end{aligned}$$

For every finite value of  $\tau$  the series appearing in the above inequality are convergent. Thus,  $\|y^1 - y^2\|_{1,\tau} \leq \text{const } \widehat{\delta} = \varepsilon$  for  $\max(\widehat{\delta}, \|h\|_{1,\tau}) < \delta$ .

**2.3.** *The multipoint problem.* Let  $r$  be the greatest integer such that  $1 + \alpha + \beta - r > 0$ . Consider equation (4.12) with the multipoint conditions

$$(4.19) \quad y^{(\alpha-m)}(x_m) = \eta_m \quad (m = \overline{1, r}),$$

where  $x_m \in \mathbb{R}_+$  and  $\eta_m \in \mathbb{R}$  are given.

Imposing (4.19) on the general solution (4.17) of (4.12), we get the following algebraic system with unknowns  $c_1, \dots, c_r$ :

$$(4.20) \quad \sum_{k=1}^r c_k x_m^{m-k} \left( 1/\Gamma(1 + m - k) \right. \\ \left. + \sum_{l=1}^{\infty} (\nu x_m^{\alpha+\beta}/\Gamma(\alpha))^l \prod_{j=1}^l B(\alpha, j(\alpha + \beta) + 1 - k) \right)$$

$$\begin{aligned} & \times \Gamma(1 + \alpha - k + l(\alpha + \beta)) / (\Gamma(1 + m - k + l(\alpha + \beta))\Gamma(1 + \alpha - k)) \\ & = \eta_m - y_N^{(\alpha-m)}(x_m) \end{aligned}$$

( $m = \overline{1, r}$ ; by Remark 4.2,  $c_k = 0$  for  $k = \overline{r+1, p}$ ), where  $y_N$  is a solution of the nonhomogeneous equation (4.12) with homogeneous initial conditions.

**THEOREM 4.4.** *If Assumption IV is satisfied and system (4.20) has a solution, then the multipoint problem for equation (4.12) has a solution in the class of locally integrable functions such that their derivatives of order  $\alpha$  belong to  $L^1_\tau(\mathbb{R}_+)$ . Moreover, if the determinant of (4.20) is not 0, then the solution is unique.*

## V. Further applications of the derivatives of noninteger order

In this chapter we give some further applications of the derivatives of non-integer order. In the first section we use the properties of those derivatives to construct some new examples of Mikusiński operators which are functions. In the second section we prove some integral formulae for analytic functions in a subset of  $\mathbb{C}^n$ . These formulae, generalizing the classical integral formulae of Cauchy and Schwarz, extend to the case of arbitrary  $n$  some result of Dzhrbashyan obtained for  $n = 1$ .

**1. An application to Mikusiński's operator theory.** Let  $M = \{f : \mathbb{R}_+ \rightarrow \mathbb{C} : f' \in L^1_{\text{loc}}(\mathbb{R}_+)\}$  and define in  $M$  the operation

$$f(t) \otimes g(t) = \left( \int_0^t f(t-\tau)g(\tau) d\tau \right)'.$$

Let  $(M, +, \otimes)$ , where  $+$  is addition of functions, be the Mikusiński ring and  $\mathcal{M}(M)$  the field of operators generated by  $M$ . Finally, define

$$P(\lambda) := \sum_{i=1}^m a_i \lambda^{\alpha_i} \quad \text{and} \quad Q(\lambda) := \sum_{j=1}^r b_j \lambda^{\beta_j}$$

with  $a_i, b_j \in \mathbb{C}$ ,  $\alpha_i, \beta_j \in \mathbb{R}_+$  ( $i = 1, \dots, m$ ;  $j = 1, \dots, r$ ).

Let  $s := \frac{1}{t} \in \mathcal{M}(M)$  be the differential operator. Then  $R(s) := \frac{Q(s)}{P(s)}$  is called the *rational operator*.

Let  $\alpha$  be a positive number,  $p$  a positive integer,  $p-1 < \alpha \leq p$ , and  $f \in M$  such that  $f^{(p)}$  exists. Then

$$\begin{aligned} s^\alpha \otimes f(t) &= \frac{\Gamma(1+\alpha)}{t^\alpha} \otimes f(t) = \Gamma(1+\alpha) \frac{t^{p-\alpha} \otimes f(t)}{t^{p-\alpha} \otimes t^\alpha} \\ &= \frac{p!}{\Gamma(1+p-\alpha)} \frac{t^{p-\alpha} \otimes f(t)}{t^p} = \frac{1}{\Gamma(1+p-\alpha)} s^p \otimes t^{p-\alpha} \otimes f(t). \end{aligned}$$

Furthermore, assuming that the derivative of order  $p - 1$  of  $t^{p-\alpha} \otimes f(t)$  is absolutely continuous, and bearing in mind the formula (cf. [11], p. 103)

$$s^p \otimes g(t) = g^{(p)}(t) + \sum_{k=1}^p s^k g^{(p-k)}(0)$$

(where, by assumption,  $g^{(p)}$  exists) with  $g(t) = t^{p-\alpha} \otimes f(t)$ , we obtain

$$(5.1) \quad s^\alpha \otimes f(t) = f^{(\alpha)}(t) + \sum_{k=1}^p s^k f^{(\alpha-k)}(0),$$

where  $f^{(\alpha-k)}(t) := (t^{p-\alpha} \otimes f(t))^{(p-k)} / \Gamma(1+p-\alpha)$  ( $k = \overline{0, p}$ ) is the one-dimensional derivative of order  $\alpha - k$  (cf. def. (1.1)). Hence,  $s^\alpha$  is called a *differential operator of noninteger order*.

Consider  $f_j(t) := t^{\alpha-j} {}_1E_{\alpha, 1+\alpha-j}(\lambda t^\alpha)$  ( $\lambda \in \mathbb{C}$ ;  $j = \overline{1, p}$ ), where (cf. also formula (1.11))

$${}_kE_{\varrho, \mu}(z) := \sum_{m \geq \mathbf{0}} z^m / \Gamma\left(\sum_{i=1}^k m_i \varrho_i + \mu\right)$$

( $z = (z_i) \in \mathbb{C}^k$ ,  $m = (m_i) \in \mathbb{N}_0^k$ ,  $\varrho = (\varrho_i) \in \mathbb{R}_+^k \setminus \{\mathbf{0}\}$ ,  $\mu > 0$ ).

By Corollary 1.2 and Lemma 1.7,  $f_j$  is the only solution of  $f_j^{(\alpha)} = \lambda f_j$  such that  $f_j^{(\alpha-k)}(0) = \delta_{jk}$  ( $j, k = \overline{1, p}$ ).

Hence,  $s^\alpha \otimes f_j(t) = \lambda f_j(t) + s^j$ , which implies

$$(5.2) \quad \frac{s^j}{s^\alpha - \lambda} = t^{\alpha-j} {}_1E_{\alpha, 1+\alpha-j}(\lambda t^\alpha) \quad (j = \overline{1, p}).$$

Moreover,

$$\frac{1}{s^\alpha - \lambda} = t \otimes t^{\alpha-1} {}_1E_{\alpha, \alpha}(\lambda t^\alpha) = \int_0^t \tau^{\alpha-1} {}_1E_{\alpha, \alpha}(\lambda \tau^\alpha) d\tau = t^\alpha {}_1E_{\alpha, 1+\alpha}(\lambda t^\alpha),$$

which proves that (5.2) also holds for  $j = 0$ . Notice that  $f_j \in M$  ( $j = \overline{1, p-1}$ ) and  $f_p \in L_{\text{loc}}^1(\mathbb{R}_+) \cap C^\infty(0, \infty)$ .

We extend (5.2) to some noninteger values of  $j$ . By (5.2),

$$\frac{s^{j+\kappa}}{s^\alpha - \lambda} = s^\kappa \otimes f_j(t) \quad (0 \leq \kappa < 1; j = \overline{0, p}).$$

Moreover,  $f_j^{(\kappa)}(t) = t^{\alpha-j-\kappa} {}_1E_{\alpha, 1+\alpha-j-\kappa}(\lambda t^\alpha)$  and  $f_j^{(\kappa-1)}(0) = 0$  if  $1+\alpha-j-\kappa > 0$  ( $j = \overline{0, p}$ ). Hence, and by (5.1), we obtain (5.2) with  $j$  replaced by  $\beta$  such that  $0 \leq \beta < 1 + \alpha$ .

Basing on (5.2) one can construct examples of rational operators which are functions. By induction we can prove the equality

$$\frac{s^{\beta_1}}{s^{\alpha_1} - \lambda_1} \otimes \dots \otimes \frac{s^{\beta_k}}{s^{\alpha_k} - \lambda_k} = t^\mu {}_kE_{(\alpha_i), 1+\mu}((\lambda_i t^{\alpha_i})).$$

with  $\mu = |\alpha - \beta|_+$ .



**Remark 5.1.**  $R(s)$  is a function if and only if  $\max \beta_i \leq \max \alpha_j$ , provided that  $\alpha_i, \beta_j \in \mathbb{N}_0$  (cf. [11], p. 118). Generally, this conclusion is not true for all  $\alpha_i, \beta_j \in \mathbb{R}_+$  (cf. (5.2) with  $\alpha < j = p$ ).

The above results imply the following final

**THEOREM 5.1.** *If*

$$Q(\lambda) = \prod_{i=1}^k \sum_{j=1}^{r_i} b_{ij} \lambda^{\beta_{ij}} \quad \text{and} \quad P(\lambda) = a \prod_{i=1}^l (\lambda^{\gamma_i} - \lambda_i)$$

( $a, b_{ij}, \lambda_i \in \mathbb{C}$ ;  $\beta_{ij}, \gamma_i \in \mathbb{R}_+$ ,  $k, l, r_i \in \mathbb{N}$  are fixed),  $k \leq l$  and  $\beta_{ij} < 1 + \gamma_i$  ( $i = \overline{1, k}$ ;  $j = \overline{1, r_i}$ ), then the operator  $R(s) := \frac{Q(s)}{P(s)}$  is a function of class  $C^\infty(0, \infty)$ . If, moreover,  $\prod_{i=1}^k (\gamma_i - \beta_{ij}) \geq 0$  ( $j = \overline{1, r_i}$ ) then  $R(s) \in M$ .

**2. Integral representation of analytic functions.** Let  $n \in \mathbb{N}$ ,  $\alpha = (\alpha_j)$ ,  $\varrho = (\varrho_j)$ ,  $R = (R_j) \in \mathbb{R}_+^n$ , and introduce the set

$$(5.3) \quad B_R := \{z = (z_j) \in \mathbb{C}^n : |z_j| < R_j\},$$

and the functions

$$(5.4) \quad C_\alpha(z) := \Gamma(\mathbf{1} + \alpha)(\mathbf{1} - z)^{-\mathbf{1} - \alpha},$$

$$(5.5) \quad S_\alpha(z) := 2C_\alpha(z) - C_\alpha(\mathbf{0})$$

( $\alpha \geq -\mathbf{1}$ ,  $z = (z_j) \in B_{\mathbf{1}}$ ). Assume that  $f : B_R \rightarrow \mathbb{C}$  is analytic, whence it has, for  $z \in B_R$ , the representation by the uniformly convergent series (cf. [41], pp. 30–32)

$$(5.6) \quad f(z) = \sum_{k \geq \mathbf{0}} a_k z^k,$$

( $k = (k_j) \in \mathbb{N}_0^n$ ), where  $a_k = D^k f(\mathbf{0})/k! \in \mathbb{C}$ .

The following theorem generalizes a result of Dzhrbashyan (cf. [13], p. 594).

**THEOREM 5.2.** (i) *For every  $\alpha > -\mathbf{1}$ ,*

$$(5.7) \quad f_\alpha(z) := r^{-\alpha} \mathcal{D}^{-\alpha} f(z) = \sum_{k \geq \mathbf{0}} a_k (\Gamma(\mathbf{1} + k)/\Gamma(\mathbf{1} + k + \alpha)) z^k$$

( $z = (z_j)$ ,  $z_j = r_j \exp(i\varphi_j)$ ,  $\mathbf{0} \leq r = (r_j) < R$ ,  $\varphi = (\varphi_j)$ ;  $k = (k_j) \in \mathbb{N}_0^n$  and the differentiation  $\mathcal{D}^{-\alpha}$  is performed with respect to  $r$ ) is analytic in  $B_R$ .

(ii) *For every  $\alpha > -\mathbf{1}$ ,  $\mathbf{0} < \varrho < R$  and  $z \in B_R$ ,*

$$(5.8) \quad f(z) = (2\pi)^{-n} \int_0^{2\pi} d\vartheta_1 \dots \int_0^{2\pi} C_\alpha(z_{\varrho_\vartheta}) f_\alpha(\varrho_\vartheta) d\vartheta_n,$$

$$(5.9) \quad f(z) = i\Im f(\mathbf{0}) + (2\pi)^{-n} \int_0^{2\pi} d\vartheta_1 \dots \int_0^{2\pi} S_\alpha(z_{\varrho_\vartheta}) \Re f_\alpha(\varrho_\vartheta) d\vartheta_n,$$

where  $\varrho_\vartheta = (\varrho_j \exp(i\vartheta_j))$ ,  $z_{\varrho_\vartheta} = (\exp(-i\vartheta_j) z_j / \varrho_j) \in \mathbb{C}^n$  and  $\Re$  and  $\Im$  denote the real and imaginary part, respectively.

Proof. (i) The function  $f$ , being analytic in  $B_R$ , can be represented by the series (5.6), and if  $z_j = r_j \exp(i\varphi_j)$  ( $j = \overline{1, n}$ ) then  $z^k = r^k \exp(i|(k_j\varphi_j)|_+)$  and

$$f(z) = \sum_{k \geq \mathbf{0}} a_k r^k \exp(i|(k_j\varphi_j)|_+),$$

where  $r = (r_j) \in \mathbb{R}_+^n$ . Hence,  $f_\alpha$  is of the form

$$f_\alpha(z) = \sum_{k \geq \mathbf{0}} a_k r^k (\Gamma(\mathbf{1} + \alpha) / \Gamma(\mathbf{1} + \alpha + k)) \exp(i|(k_j\varphi_j)|_+),$$

which implies the series representation of  $f_\alpha$  in  $B_R$ . Furthermore, for every  $\alpha > -\mathbf{1}$ ,

$$\lim_{|k|_+ \rightarrow \infty} (\Gamma(\mathbf{1} + k) / \Gamma(\mathbf{1} + \alpha + k))^{1/|k|_+} = 1$$

and hence  $f_\alpha$  is analytic in  $B_R$ .

(ii) Clearly,  $C_\alpha$  can be expanded in the uniformly convergent series

$$\begin{aligned} C_\alpha(z_{\varrho\vartheta}) &= \sum_{l \geq \mathbf{0}} (\Gamma(\mathbf{1} + \alpha + l) / \Gamma(\mathbf{1} + l)) z_{\varrho\vartheta}^l \\ &= \sum_{l \geq \mathbf{0}} (\Gamma(\mathbf{1} + \alpha + l) / \Gamma(\mathbf{1} + l)) \varrho^{-l} z^l \exp(-i|(l_j\vartheta_j)|_+) \end{aligned}$$

( $l = (l_j) \in \mathbb{N}_0^n$ ) for every  $z \in B_\varrho$  and  $\vartheta \in [0, 2\pi)^n$ .

Consider the integral appearing in (5.8). We have

$$\begin{aligned} &\int_0^{2\pi} d\vartheta_1 \dots \int_0^{2\pi} C_\alpha(z_{\varrho\vartheta}) f_\alpha(\varrho\vartheta) d\vartheta_n \\ &= \int_0^{2\pi} d\vartheta_1 \dots \int_0^{2\pi} \sum_{l \geq \mathbf{0}} (\Gamma(\mathbf{1} + \alpha + l) / \Gamma(\mathbf{1} + l)) \varrho^{-l} z^l \exp(-i|(l_j\vartheta_j)|_+) \\ &\quad \times \sum_{k \geq \mathbf{0}} a_k \varrho^k (\Gamma(\mathbf{1} + k) / \Gamma(\mathbf{1} + \alpha + k)) \exp(i|(k_j\vartheta_j)|_+) d\vartheta_n. \end{aligned}$$

By the uniform convergence of the above series we can interchange the integrals and sums to obtain

$$\begin{aligned} &\int_0^{2\pi} d\vartheta_1 \dots \int_0^{2\pi} C_\alpha(z_{\varrho\vartheta}) f_\alpha(\varrho\vartheta) d\vartheta_n \\ &= \sum_{k \geq \mathbf{0}} \sum_{l \geq \mathbf{0}} a_k [\Gamma(\mathbf{1} + k) \Gamma(\mathbf{1} + \alpha + l) / (\Gamma(\mathbf{1} + l) \Gamma(\mathbf{1} + \alpha + k))] \varrho^{k-l} z^l \\ &\quad \times \int_0^{2\pi} d\vartheta_1 \dots \int_0^{2\pi} \exp(i|((l_j - k_j)\vartheta_j)|_+) d\vartheta_n. \end{aligned}$$

Using the equality

$$(5.10) \quad \int_0^{2\pi} d\vartheta_1 \dots \int_0^{2\pi} \exp(i((l_j - k_j)\vartheta_j)|_+) d\vartheta_n = (2\pi)^n \delta_{k,l},$$

(the symbol  $\delta_{k,l}$  is understood analogously to Kronecker's delta), which follows from the properties of exponential function, we get (5.8).

We now prove (5.9). Repeating the argument used above we have

$$\begin{aligned} & \int_0^{2\pi} d\vartheta_1 \dots \int_0^{2\pi} C_\alpha(z_{\varrho\vartheta}) \overline{f_\alpha(\varrho\vartheta)} d\vartheta_n \\ &= \sum_{k \geq \mathbf{0}} \sum_{l \geq \mathbf{0}} a_k [\Gamma(\mathbf{1} + k) \Gamma(\mathbf{1} + \alpha + l) / (\Gamma(\mathbf{1} + l) \Gamma(\mathbf{1} + \alpha + k))] \\ & \quad \times \varrho^{-k-l} z^l \delta_{-k,l} = \overline{f(\mathbf{0})}. \end{aligned}$$

Thus

$$f(z) + \overline{f(\mathbf{0})} = 2(2\pi)^{-n} \int_0^{2\pi} d\vartheta_1 \dots \int_0^{2\pi} C_\alpha(z_{\varrho\vartheta}) \Re f_\alpha(\varrho\vartheta) d\vartheta_n.$$

By the above equality and (5.5), we obtain

$$\begin{aligned} f(z) &= -\overline{f(\mathbf{0})} + (2\pi)^{-n} \int_0^{2\pi} d\vartheta_1 \dots \int_0^{2\pi} C_\alpha(\mathbf{0}) \Re f_\alpha(\varrho\vartheta) d\vartheta_n \\ & \quad + (2\pi)^{-n} \int_0^{2\pi} d\vartheta_1 \dots \int_0^{2\pi} S_\alpha(z_{\varrho\vartheta}) \Re f_\alpha(\varrho\vartheta) d\vartheta_n. \end{aligned}$$

Consider the second term on the right-hand side of the last relation. Since  $\Re : \mathbb{C} \rightarrow \mathbb{R}$  is linear, we can interchange it with integration (cf. [39], p. 508). Hence using (5.8) with  $z = \mathbf{0}$  we have

$$\Re f(\mathbf{0}) = (2\pi)^{-n} \int_0^{2\pi} d\vartheta_1 \dots \int_0^{2\pi} C_\alpha(\mathbf{0}) \Re f_\alpha(\varrho\vartheta) d\vartheta_n.$$

The above results yield (5.9), which completes the proof of Theorem 5.2.

Let  $G \subset \mathbb{R}^{2n}$ . A function  $u : G \rightarrow \mathbb{R}$  is called *pluriharmonic* in  $G$  (cf. [19], p. 81, [41], p. 25) if it is in  $C^2(G)$  and the equations

$$D_{x_k} D_{x_l} u + D_{y_k} D_{y_l} u = 0, \quad D_{x_k} D_{y_l} u - D_{x_l} D_{y_k} u = 0$$

( $k, l = \overline{1, n}$ ,  $(x_j), (y_j) \in \mathbb{R}^n$ ) are satisfied for  $(x, y) \in G$ .

Define  $G = B_R^* := \{(x, y) \in \mathbb{R}^{2n} : z = x + iy \in B_R\}$ .

**COROLLARY 5.1.** (i) *If  $u$  is pluriharmonic in  $B_R$  and if  $\alpha > -1$ , then*

$$(5.11) \quad u_\alpha(z) := r^{-\alpha} \mathcal{D}^{-\alpha} u(z)$$

( $z_j = r_j \exp(i\varphi_j)$ ,  $\mathbf{0} \leq r = (r_j) < R$  and the differentiation  $\mathcal{D}^{-\alpha}$  is performed with respect to  $r$ ) considered as a function of  $(x, y)$  ( $(x, y) \in \mathbb{R}^{2n}$ ,  $z = x + iy$ ) is pluriharmonic in  $B_R^*$ .

(ii) For every  $\mathbf{0} < \varrho < R$  and  $z \in B_R$ ,

$$(5.12) \quad u(z) = (2\pi)^{-n} \int_0^{2\pi} d\vartheta_1 \dots \int_0^{2\pi} \Re S_\alpha(z_{\varrho\vartheta}) u_\alpha(\varrho\vartheta) d\vartheta_n,$$

where  $\varrho\vartheta = (\varrho_j \exp(i\vartheta_j))$ ,  $z_{\varrho\vartheta} = (\exp(-i\vartheta_j) z_j / \varrho_j) \in \mathbb{C}^n$ .

**Proof.** There exists  $f$  analytic in  $B_R$  such that  $u = \Re f$  (cf. [19], p. 82). By Theorem 5.2, for every  $\alpha > -1$ ,  $f_\alpha(z)$  (cf. (5.7)) is analytic, and hence its real part  $u_\alpha = \Re f_\alpha$  (considered as a function of  $(x, y)$ ) is pluriharmonic in  $B_R^*$ . The proof of (5.12) is completed by taking the real part of both sides of (5.9).

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