Abstract differential inclusions with some applications to partial differential ones

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Abstract. Let V, W, and Z be linear normed spaces and consider an operator A: dom $A \subset W \to V$, a mapping j: dom $j \subset W \to Z$, and a multifunction F: dom $F \subset Z \to \operatorname{cl}(V)$. The paper deals with the problem of existence of solutions for an abstract differential inclusion:

Find $w \in W$ such that $Aw \in F(jw)$.

Such a generally stated problem admits a solution under suitable regularity assumptions on f, A, and F, and the compactness and growth conditions with the exponents α_f , α_R , α_F , where $\alpha_f \alpha_R \alpha_F < 1$ and R is a coretraction to A. The idea of the proof is based on an existence theorem for continuous selections.

The main result is applied to the following problems for partial differential inclusions:

- (a) of elliptic type: Find u from the Sobolev space $H^2(T, \mathbb{R}^k)$ such that $\Delta u \in G(t, u(t), \nabla u(t))$ a.e. in an open bounded set $T \subset \mathbb{R}^m$ and u(t) = 0 on the boundary ∂T , where $G: T \times \mathbb{R}^k \times \mathbb{R}^{mk} \to \operatorname{cl}(\mathbb{R}^k)$;
- (b) of parabolic type: solve du/dt + Lu = g(t) with an initial condition $u(0) \in F(ju)$, where $t \in T = (0, 1)$, I = [0, a], $L = -\frac{\partial^2}{\partial x^2}$ is an operator defined on the Sobolev space $H_0^1(T, \mathbb{R}^k) \cap H^2(T, \mathbb{R}^k)$ and $g \in L^1(I, L^2(T, \mathbb{R}^k))$.

Introduction. Consider an abstract differential inclusion

$$(1) Du \in F(u),$$

where U and V are function spaces and $D: U \to V$ is a differential operator. In the case when the right-hand side F(u) is a lower semicontinuous multifunction from U into closed convex subsets of V, the existence of solutions to (1) can be concluded from the well-known Michael Theorem [11], [13]. Namely, under suitable growth and compactness conditions on F(u), every differential equation Du = f(u), with a continuous selection f(u) of F(u), $f(u) \in F(u)$, admits a solution $u \in \text{dom } F := \{u \in U : F(u) \neq \emptyset\}$.

If the values F(u) are not necessarily convex, a continuous selection need not exist. However, in some situations, the convexity assumption in the Michael Theorem can be replaced by another one. This is the case when V is the Lebesgue space of s-integrable functions, $s \in [1, \infty)$, defined on a measure space (T, \mathcal{L}, μ) . If we assume that dom F is compact and all sets F(u) are

decomposable, i.e. for all $v, v' \in F(u)$ and every $A \in \mathcal{L}$,

$$\chi_A v + (1 - \chi_A) v' \in F(u),$$

then the mapping $F(\cdot)$ admits a continuous selection. This is proved in [7] for $V = L^{1}(T, X)$, where X is a Banach space (in [7] X was required to be separable, but the proof does not actually use this condition).

In the present paper we extend this result in a simple way to an arbitrary space $L^s(T, X)$, $s \in [1, \infty)$ (see also [3], [4]). We give a precise formulation in Section 2, where we also provide some necessary definitions and results. They allow us to show the scope of the class of decomposable lower semicontinuous multifunctions. Section 3 is devoted to the proof of our main result on the existence of solutions to (1), which we apply in Section 4 to elliptic and parabolic differential inclusions. Our theorem generalizes the existence results to a wide range of differential inclusions such as partial differential inclusions [1] and a new nonstationary diffusion problem. In this case a qualitatively new phenomenon appears: we may consider a constraint on the initial conditions which depends on the future values of the trajectory.

2. Preliminaries. Let W and Z be topological spaces and let cl(Z) stand for the class of all nonempty closed subsets of Z. By a multifunction (multivalued mapping or simply mapping) we mean a mapping $F: W \rightarrow cl(Z)$.

DEFINITION 1. A mapping $F: W \to cl(Z)$ is called *lower semicontinuous* (l.s.c.) if for any closed $B \subset Z$ the set

$$(2) F^+(B) = \{ w \in W \colon F(w) \subset B \}$$

is closed in W.

Remark 1. If Z is a metric space with metric d, then F being l.s.c. is equivalent to the upper semicontinuity (u.s.c.) of the function $(w, z) \mapsto \operatorname{dist}(z, F(w))$.

Since now let T be a locally compact Hausdorff topological space with a σ -field \mathcal{L} given by a nonnegative σ -finite regular Borel measure μ . For an arbitrary Banach space X with norm $|\cdot|$ we shall denote by $\mathcal{M}(T, X)$ the space (of equivalence classes) of \mathcal{L} -measurable functions from T into X and by $L^s(T, X)$ the subspace of $\mathcal{M}(T, X)$ equipped with the norm

(3)
$$||z||_{s,T} = \left\{ \int_{T} |z(t)|^{s} \, \mu(dt) \right\}^{1/s}, \quad s \in [1, \infty).$$

Let Z be a normed space contained in $\mathcal{M}(T, X)$.

DEFINITION 2. (i) A set $K \subset Z$ is decomposable if for all $z, z' \in K$ and every $A \in \mathcal{L}$

(4)
$$\chi_A z + (1 - \chi_A) z' \in K \quad (\text{in } \mathcal{M}(T, X)).$$

(ii) A mapping $F: W \to cl(Z)$ is decomposable if for every $w \in W$ the set F(w) is decomposable.

Consider a continuous mapping $f: X \to X$ and denote by $T_f: Z \to \mathcal{M}(T, X)$ the mapping given by

(5)
$$(T_f z)(t) = f(z(t)).$$

Such a T_f can be a source of new decomposable mappings:

PROPOSITION 1. Let Z and Z_1 be normed spaces in $\mathcal{M}(T,X)$ and let W and W_1 be topological spaces. Assume that the mapping T_f given by (5) is a homeomorphism between Z and Z_1 . Let $F_1: W_1 \to \operatorname{cl}(Z_1)$ be decomposable and l.s.c., and $J: W \to W_1$ a continuous mapping. Then $F = T_f^{-1} \circ F_1 \circ J: W \to \operatorname{cl}(Z)$ is also decomposable and l.s.c. where $T_f^{-1}: \operatorname{cl}(Z_1) \to \operatorname{cl}(Z)$ is induced by $T_f^{-1}: Z_1 \to Z$.

Proof. That F is l.s.c. is obvious. To prove that F is decomposable, fix $A \in \mathcal{L}$ and $w \in W$. For $z_1, z_2 \in F(w)$ set $z = \chi_A z_1 + (1 - \chi_A) z_2$. One can check that $T_f z = \chi_A T_f z_1 + (1 - \chi_A) T_f z_2$. But $T_f z_i \in F_1(Jw)$ for i = 1, 2 and thus $T_f z \in \chi_A F_1(Jw) + (1 - \chi_A) F_1(Jw) \subset F_1(Jw)$, by decomposability of F_1 . Therefore $z \in (T_f^{-1} \circ F_1 \circ J)(\omega) = F(w)$, which completes the proof. \blacksquare

COROLLARY 1. For any $p, s \in [1, \infty)$, the classes of all decomposable l.s.c. mappings from W into $\operatorname{cl}(L^s(T, X))$ and $\operatorname{cl}(L^p(T, X))$ respectively are in a bijective correspondence.

Proof. Let $f_{s,p}: X \to X$ be the function given by

$$f_{s,p}(x) = \begin{cases} |x|^{s/p-1}x & \text{if } x \neq 0, \\ 0 & \text{if } x = 0. \end{cases}$$

Consider the mapping $T_{s,p}$ given by (5) with $f = f_{s,p}$. Then $T_{s,p}$ is the famous Mazur homeomorphism ([2], Ch. IV) between $L^s(T, X)$ and $L^p(T, X)$ and now our claim follows from Proposition 1.

Consider a space $V \subset \mathcal{M}(T, X)$. We shall say that V has the continuous selection property iff for any compact topological space W, every l.s.c. decomposable mapping $F \colon W \to \operatorname{cl}(V)$ admits a continuous selection $f(\cdot)$, $f(w) \in F(w)$ for all $w \in W$. First the continuous selection property for the spaces $L^1(T, X)$ has been shown in [7] with T compact and X separable and next extended in [3] to the general case (for W a separable space). The same remains true also for $L^s(T, X)$, where $s \in [1, \infty)$:

PROPOSITION 2. Assume that W is a compact topological space and let $F: W \to \operatorname{cl}(L^s(T, X))$ be l.s.c. and decomposable. Then F admits a continuous selection.

Proof. Let $T_{1,s}$ denote the Mazur homeomorphism from $L^1(T, X)$ onto $L^s(T, X)$. From Proposition 1 it follows that $F_1 = (T_{1,s})^{-1} \circ F$ is l.s.c. and

decomposable as well. Therefore F_1 admits a continuous selection f_1 . One can check that $f = T_{1,s} \circ f_1$ is the required selection of F.

Needless to say, the family of l.s.c. decomposable mappings is very wide. Now we are going to present a class of such mappings; first, we recall the notion of measurability of multivalued mappings.

Let (S, \mathcal{S}) be an arbitrary measure space and Y a separable metric space.

DEFINITION 3. A mapping $G: S \to cl(Y)$ is called \mathscr{G} -measurable (or simply measurable) if $G^+(B) \in \mathscr{G}$ for every $B \in cl(Y)$.

Now we present a class of l.s.c. decomposable mappings which appears in the theory of differential inclusions. Let X and Y be two finite-dimensional Banach spaces and consider a mapping $G: T \times X \rightarrow cl(Y)$ satisfying the following conditions:

- (i) G is $\mathcal{L} \otimes \mathcal{B}$ -measurable, where \mathcal{B} stands for the Borel σ -field of X,
- (ii) $G(t, \cdot)$ is l.s.c. for every $t \in T$,
- (iii) G satisfies the following growth condition: there exist $\gamma > 0$, c > 0 and $m \in L^s(T, \mathbb{R})$ such that for each $t \in T$ and $x \in X$

$$\sup\{|r|:\ r\in G(t,\,x)\}\leqslant m(t)+\epsilon(1+|x|)^{\gamma},\quad s\in[1,\,\infty).$$

For such G and $w \in L^p(T, X)$ we define a new multifunction by

(6)
$$F(w) = \{z \in \mathcal{M}(T, Y): z(t) \in G(t, w(t)) \text{ a.e. in } T\}.$$

If $\gamma \in (0, p/s]$ then F(w) is a nonempty closed subset of $L^s(T, Y)$. Moreover, we have the following

PROPOSITION 3. Assume that $G: T \times X \to \operatorname{cl}(Y)$ satisfies (i)-(iii) and consider the mapping F given by (6). If $\gamma \in (0, p/s]$ and $\mu(T) < +\infty$ then $F: L^p(T, X) \to \operatorname{cl}(L^s(T, X))$ is l.s.c. and decomposable and satisfies the following growth condition: There is C > 0 such that

(7)
$$\sup\{\|z\|_{s,T}: z \in F(w)\} \leq C(1+\|w\|_{p,T})^{\gamma} \quad \text{for every } w \in L^p(T,X).$$

Proof. Fix $w \in L^p(T, X)$. One can check that the set F(w) is decomposable. By a standard argument it is also closed. We shall prove that it is nonempty, condition (7) holds and hence the mapping $F(\cdot)$ is l.s.c.

(a) Nonemptiness. From (i) it follows that $G(\cdot, w(\cdot))$ is measurable, and hence admits measurable selections, by the Kuratowski and Ryll-Nardzewski Theorem [10], [5]. From (iii) we can conclude that every measurable selection $z(\cdot)$ of $G(\cdot, w(\cdot))$ satisfies

(8)
$$|z(t)| \le m(t) + c(1 + |w(t)|)^{\gamma}$$
 a.e. in T.

But $(1+|w(\cdot)|)^{\gamma} \in L^{s}(T, \mathbb{R})$ and therefore (8) means that F(w) is a nonempty subset of $L^{s}(T, \mathbb{X})$ and for every $z \in F(w)$

$$||z||_{s,T} \leq ||m||_{s,T} + cc_0(||1+|w|||_{p,T})^{\gamma},$$

where c_0 is the norm of the embedding of $L^{p/\gamma}(T, R)$ into $L^s(T, R)$. The latter inequality provides the required estimate with $C = ||m||_{s,T} + cc_0(1 + \mu(T)^{1/p})^{\gamma}$ since $||m||_{s,T} \leq ||m||_{s,T}(1 + ||w||_{p,T})^{\gamma}$.

(b) l.s.c. Fix $B \in cl(L^s(T, Y))$ and let $w_n \in F^+(B)$ be a sequence converging to w_0 . We shall show that $w_0 \in F^+(B)$, i.e. $F(w_0) \subset B$. For every $z_0 \in F(w_0)$ and $n = 1, 2, \ldots$ there exist $z_n \in F(w_n)$ such that

$$|z_n(t)-z_0(t)| = \text{dist}(z_0(t), G(t, w_n(t)))$$
 a.e. in T.

Since $\{w_n\}$ converges in $L^s(T, X)$ to w_0 , by taking a subsequence, if necessary, we may also assume that it converges a.e. in T. Let $T_0 \subset T$ be a set of full measure such that for each $t \in T_0$

$$\lim w_n(t) = w_0(t), \quad z_n(t) \in F(t, w_n(t)).$$

Then (ii) shows that for all $t \in T_0$

$$\limsup |z_n(t) - z_0(t)| = \limsup \operatorname{dist}(z_0(t), G(t, w_n(t)))$$

$$\leq \operatorname{dist}(z_0(t), G(t, w_0(t))) = 0,$$

which means that $z_n(t)$ tends to $z_0(t)$ a.e. in T. Moreover, from (8) it follows that for any $A \in \mathcal{L}$

$$\int_{A} |z_{n}(t)|^{s} \mu(dt) \leq 2^{s-1} \int_{A} |m(t)|^{s} \mu(dt) + 2^{s-1} c^{s} \int_{A} (1 + |w_{n}(t)|)^{\gamma s} \mu(dt).$$

But since $\gamma s \leq p$, using the Mazur homeomorphism we have

$$\lim_{A} \int_{A} (1+|w_n(t)|)^{\gamma s} \mu(dt) = \int_{A} (1+|w_0(t)|)^{\gamma s} \mu(dt),$$

which means in particular that the functions $|z_n(\cdot)|^s$ are equiintegrable. By the Vitali-Hahn-Saks Theorem [6], $\{z_n\}$ converges in $L^s(T, Y)$ to z_0 . But $z_n \in F(w_n) \subset B$ and B is closed, thus $z_0 \in B$. Since $z_0 \in F(w_0)$ has been arbitrary, we have $F(w_0) \subset B$, which completes the proof.

3. Abstract differential inclusions. Let V and W be arbitrary normed spaces. A mapping A: dom $A \to V$, where dom $A \subset W$, is called a retraction on V if A admits a "right inverse", i.e. there exists a continuous mapping $R: V \to W$ such that $A \circ R = \mathrm{id}_V$. Of course we must have $\mathrm{im} R \subset \mathrm{dom} A \subset W$. The map R is said to be a coretraction of A.

Let Z be a normed space and consider a multifunction F: $\operatorname{dom} F \subset Z \to \operatorname{cl}(V)$. We shall say that F satisfies the growth condition with exponent $\alpha_F \geqslant 0$ iff there exists a constant $C_F > 0$ such that for every $z \in \operatorname{dom} F$

(9)
$$\sup \{ \|v\| : v \in F(z) \} \leq C_F (1 + \|z\|)^{\alpha_F}.$$

In particular, if F is a function then the growth condition reads

(10)
$$||F(z)|| \leq C_F (1+||z||)^{a_F}.$$

Assume now that Z is a Banach space and $V \subset \mathcal{M}(T, X)$ has the continuous selection property and F is a l.s.c. decomposable mapping. Consider a completely continuous mapping j: dom $j \subset W \to Z$. The main result of this work is the following:

THEOREM 1. Suppose that F, j and a coretraction R of A satisfy the growth conditions with nonnegative exponents α_F , α_J and α_R (and constants C_F , C_j and C_R) respectively and additionally

- (i) im $R \subset \text{dom } j$, im $j \subset \text{dom } F$ and dom F is a closed convex subset of Z;
- (ii) $\alpha_F \alpha_I \alpha_R < 1$.

Then the problem

(11) Find
$$w \in W$$
 such that $Aw \in F(jw)$

has a solution $w \in \operatorname{im} R \subset \operatorname{dom} j \cap \operatorname{dom} A$.

Proof. Fix r > 0 and set $B_r = \{w \in \text{dom } j: ||w||_W \le r\}$. Then $B_r \neq \emptyset$ for any $r \ge ||R(0)||_W$ since then $R(0) \in B_r$. Let $S_r = \overline{\operatorname{co}} j(B_r)$, the closed convex hull of $j(B_r)$. Since j is completely continuous and B_r is bounded, $j(B_r)$ is relatively compact and thus S_r is compact. Moreover, for each $z \in S_r$

(12)
$$||z||_{Z} \leq \sup \{||j(w)||_{Z}: w \in B_{r}\} \leq C_{j}(1+r)^{\alpha_{j}}.$$

Clearly $S_r \subset \text{dom } F$ and the mapping F restricted to S_r is l.s.c. and decomposable as well. Thus F admits a continuous selection on S_r . The growth condition yields that for every such selection $f: S_r \to V$ and for each $z \in S_r$

(13)
$$||f(z)||_{V} \leqslant C_{F}(1+||z||_{Z})^{\alpha_{F}}.$$

The last inequality together with (12) implies that there exists a constant C_f such that for each $z \in S_r$

(14)
$$||f(z)||_{V} \leqslant C_{f}(1+r)^{\alpha_{f}\alpha_{F}}.$$

Since $||(R \circ f)(z)||_{W} \le C_R(1 + ||f(z)||)^{\alpha_R}$, from (14) we obtain for each $z \in S_r$

(15)
$$||(R \circ f)(z)||_{W} \leq C_{R} (1 + C_{f} (1+r)^{\alpha_{f} \alpha_{F}})^{\alpha_{R}}$$

$$\leq C_{R} (1 + C_{f})^{\alpha_{R}} (1+r)^{\alpha_{f} \alpha_{F} \alpha_{R}}.$$

But $\alpha_j \alpha_F \alpha_R < 1$, so there exists r > 0 such that $[2C_R(1+C_f)^{\alpha_R}]^{1/(1-\alpha_j \alpha_F \alpha_R)} \le r$. For such an r any selection f of F restricted to S, produces the mapping $R \circ f$: $S_r \to B_r$, since im $R \subset \text{dom } j$. Then for a fixed continuous selection f of F on S, the mapping $j \circ R \circ f$: $S_r \to j(B_r) \subset S_r$ is continuous as well and by the Schauder theorem it has a fixed point $z_0 \in j(B_r)$. One can check that $w = (R \circ f)(z_0)$ is then a solution of (11).

Since every Hölder mapping satisfies the growth condition with the same exponent we obtain

COROLLARY 2. Theorem 1 remains true if instead of the growth conditions on j and R we assume that they are Hölder continuous with exponents α_j and α_R .

Remark 2. Note that if $F: Z \rightarrow cl(V)$ satisfies the condition

(ii)' there exists a bounded set V_0 such that $F(z) \subset V_0$ for any $z \in \mathbb{Z}$, then F satisfies the growth condition with exponent $\alpha_F = 0$.

COROLLARY 3. Theorem 1 is also true if we replace (ii) by (ii)'.

4. Applications. The existence theorem for abstract inclusions (11) will be applied to some examples concerning partial differential inclusions of parabolic and elliptic type.

Let T be an open set in the euclidean space R^m with smooth boundary ∂T and elements $t = (t_1, \ldots, t_m)$. For $\alpha = (\alpha_1, \ldots, \alpha_m)$ let $D^{\alpha} = D_1^{\alpha_1} \ldots D_m^{\alpha_m}$, where $D_j = \partial/\partial t_j$ stands for the distributional derivative and let $D = (D_1, \ldots, D_m)$ be the gradient. Recall that

$$H^{1}(T, \mathbf{R}^{k}) = \{ v \in L^{2}(T, \mathbf{R}^{k}) : Dv \in L^{2}(T, \mathbf{R}^{mk}) \},$$

$$H^{2}(T, \mathbf{R}^{k}) = \{ v \in L^{2}(T, \mathbf{R}^{k}) : D^{\alpha}v \in L^{2}(T, \mathbf{R}^{k}) \text{ for } |\alpha| \leq 2 \},$$

where $|\alpha| = \alpha_1 + \ldots + \alpha_m$, are Sobolev spaces with the respective norms

$$||v||_1 = \left\{ \int_T (|v(t)|^2 + |Dv(t)|^2) dt \right\}^{1/2}, \qquad ||v||_2 = \left\{ \int_T \left(\sum_{|\alpha| \leq 2} |D^{\alpha}v(t)|^2 \right) dt \right\}^{1/2}.$$

By $H_0^1(T, \mathbf{R}^k)$ we mean the subspace of $H^1(T, \mathbf{R}^k)$ consisting of those elements $v \in H^1(T, \mathbf{R}^k)$ for which $v|_{\partial T} = 0$.

Now we are ready to give some examples of the abstract inclusion (11).

- 4.1. Elliptic inclusions. Consider the following problem:
- (16) Find $u \in H^2(T, \mathbb{R}^k)$ such that $\Delta u(t) \in G(t, u(t), Du(t))$ a.e. in $T, u|_{\partial T} = 0$, where $\Delta \colon H^2(T, \mathbb{R}^k) \to L^2(T, \mathbb{R}^k)$ is the Laplace operator and $G \colon T \times \mathbb{R}^k \times \mathbb{R}^{mk} \to \operatorname{cl}(\mathbb{R}^k)$.

THEOREM 2. Suppose that

- (a) G is $\mathcal{L} \otimes \mathcal{B}(\mathbf{R}^{k+mk})$ -measurable, where \mathcal{L} is the σ -algebra of Lebesgue measurable sets in T and $\mathcal{B}(\cdot)$ stands for the Borel sets,
 - (b) the mapping $G(t, \cdot, \cdot)$ is l.s.c. for every $t \in T$,
- (c) there exist $\gamma < 1$, $M \ge 0$ and $m \in L^2(T, \mathbb{R})$ such that for any $(x, y) \in \mathbb{R}^k \times \mathbb{R}^{mk}$

$$\sup\{|r|: r \in G(t, x, y)\} \le m(t) + M(1 + |x| + |y|)^{\gamma}$$
 a.e. in T.

Then the problem (16) has a solution $u \in H^2(T, \mathbb{R}^k) \cap H^1_0(T, \mathbb{R}^k)$.

Proof. Let G be the mapping from $L^2(T, \mathbb{R}^{k+mk})$ into $\operatorname{cl}(L^2(T, \mathbb{R}^k))$ given by

$$G(u) = \{z \in L^2(T, \mathbb{R}^k): z(t) \in G(t, u_0(t), \dots, u_m(t)) \text{ a.e. in } T\},$$

where $u(\cdot) = (u_0(\cdot), u_1(\cdot), \ldots, u_m(\cdot))$. This mapping is decomposable and l.s.c. by Proposition 3.

Since the operator (id, D) is continuous from $H^1(T, \mathbb{R}^k)$ into $L^2(T, \mathbb{R}^k) \times L^2(T, \mathbb{R}^{mk})$, $F(\cdot)$ defined on $H^1(T, \mathbb{R}^k)$ by

$$F(v) = \{ z \in L^2(T, \mathbb{R}^k) : \ z(t) \in G(t, v(t), Dv(t)) \text{ a.e. in } T \}$$

is decomposable and l.s.c. as well. By Proposition 3, the mapping $F(\cdot)$ satisfies the growth condition with exponent γ (and constant C_F).

By Rz denote the unique solution in $H^2(T, \mathbb{R}^k)$ of the Dirichlet problem

$$\Delta u = z, \quad u|_{\partial T} = 0$$

for any $z \in L^2(T, \mathbb{R}^k)$. The mapping R is a continuous linear operator from $L^2(T, \mathbb{R}^k)$ into $H^2(T, \mathbb{R}^k) \cap H^1_0(T, \mathbb{R}^k)$ (see [12]). Therefore in order to obtain a solution of (16) we can apply Theorem 1 for $W = H^2(T, \mathbb{R}^k)$, $V = L^2(T, \mathbb{R}^k)$, $Z = H^1(T, \mathbb{R}^k)$, $A = \Delta$ and the embedding $j: H^2(T, \mathbb{R}^k) \to H^1(T, \mathbb{R}^k)$, which is compact by the Rellich Theorem.

Example 1. A particular case of (16) is the problem

(17)
$$\Delta u \in G(u), \quad u|_{\partial T} = 0,$$

where $T \subset \mathbb{R}^2$ and $G: \mathbb{R}^2 \to \operatorname{cl}(\mathbb{R}^2)$ is the standard continuous multifunction given by

$$G(x) = \begin{cases} \{-x/|x|\} & \text{for } |x| \ge 1, \\ \{(\cos\alpha, \sin\alpha) \colon |\pi\alpha - \varphi| \le \pi(1-|x|)\} & \text{if } x = |x|(\cos\alpha, \sin\alpha) \\ & \text{for } 1 > |x| > 0, \\ \{(\cos\alpha, \sin\alpha) \colon \alpha \in R\} & \text{for } x = 0, \end{cases}$$

which does not admit a continuous selection. Thus the problem (17) has a solution which is a Lipschitz function on \overline{T} (by the Sobolev embedding theorems).

4.2. Parabolic inclusions. Let T = (0, 1) and I = [0, a] and set $H = L^2(T, \mathbb{R}^k)$ with the norm $|\cdot|$.

Consider the class of parabolic problems

(18) Find a continuous function $u: [0, a] \rightarrow H$ such that

$$\frac{du}{dt}+Lu=g(t), \quad u(0)\in F(ju),$$

where the operator L is defined on $H_0^1(T, \mathbb{R}^k) \cap H^2(T, \mathbb{R}^k)$ by $Lu = (-\partial^2 u_1/\partial x^2, \ldots, -\partial^2 u_k/\partial x^2)$ with $u = (u_1, \ldots, u_k)$ and $g \in L^1(I, H)$. We impose the following assumptions on the data j, Z, and F:

- (19) Z is a Banach space;
- (20) $j: \mathcal{C}(I, H) \to Z$ is completely continuous and satisfies the growth condition with exponent α (and constant C_i);

(21) F is l.s.c. and decomposable and satisfies the growth condition with exponent β (and constant C_F).

We now explain the notions of "strong" and "weak" solution of the equation du/dt + Lu = g and of the problem (18).

By a strong solution of the equation above we mean a mapping $u \in \mathcal{C}(I, H)$ such that for every $\varepsilon > 0$, $u: [\varepsilon, a - \varepsilon] \to H$ is absolutely continuous, $u(t) \in \text{dom } L$ a.e. in I and

(22)
$$du/dt + Lu = g \quad \text{a.e. in } I.$$

A weak solution is a limit u of strong solutions u_n satisfying (22) with right-hand sides g_n tending to g in $L^1(I, H)$.

A weak solution of the problem (18) is a weak solution of the equation satisfying the initial condition $u(0) \in F(ju)$.

Now we are in a position to formulate our result.

THEOREM 3. Assume that (19)–(21) hold and $\alpha\beta$ < 1. Then the problem (18) admits a weak solution $u: I \rightarrow H$.

This is a generalization of Theorem 38 in [8] which asserts that for every $g \in L^1(I, H)$ and $f \in H$ there exists a weak solution of the problem (18) with $Z = \{0\}$ and $F(0) = \{f\}$.

A unique weak solution of

(23)
$$du/dt + Lu = g, \quad u(0) = f$$

corresponding to given f and g is denoted by S(g, f).

For a fixed $g \in L^1(I, H)$ we define an operator $R: H \to \mathcal{C}(I, H)$ by the formula

$$(24) Rf = S(g, f).$$

Before we present a proof of Theorem 3 we need two technical lemmas.

LEMMA 1. The operator R given by (24) maps H isometrically into $\mathcal{C}(I, H)$.

Proof. First we show that S(g, f) is a Lipschitz contraction on the product $L^1(I, H) \times H$, i.e.

$$(25) ||S(g_1, f_1) - S(g_2, f_2)||_{\Psi(I, H)} \le |f_1 - f_2| + ||g_1 - g_2||_{L^1(I, H)}$$

for all $g_1, g_2 \in L^1(I, H)$ and $f_1, f_2 \in H$.

Indeed, Theorem 34 in [8] asserts that two weak solutions u_1 and u_2 of (22) with right-hand sides g_1 and g_2 respectively satisfy

$$|u_1(t) - u_2(t)| \le |u_1(s) - u_2(s)| + \int_{s}^{t} |g_1(\tau) - g_2(\tau)| d\tau$$

for all $0 \le s \le t \le a$. Moreover, for each $f \in \overline{\text{dom } L}$ there exists exactly one weak solution S(g, f) of the initial problem. If we take $u_1 = S(g_1, f_1)$ and

 $u_2 = S(g_2, f_2)$, the weak solutions of (18) with initial values f_1 and $f_2 \in \overline{\text{dom } L} = H$ respectively and s = 0, we obtain

$$\begin{split} \|S(g_1,f_1)-S(g_2,f_2)\|_{\mathscr{C}(I,H)} &= \sup_{t\in I} |u_1(t)-u_2(t)| \\ &\leqslant \sup_{t\in [0,a]} \left(|u_1(0)-u_2(0)| + \int\limits_0^t |g_1(\tau)-g_2(\tau)| d\tau\right) \\ &\leqslant |f_1-f_2| + \int\limits_0^a |g_1(\tau)-g_2(\tau)| d\tau = |f_1-f_2| + \|g_1-g_2\|_{L^1(I,H)}. \end{split}$$

This completes the proof of (25).

From (25) applied to $g_1 = g_2 = g$ we conclude that the operator R given by (24) satisfies

$$||Rf_1 - Rf_2||_{\mathscr{C}(I,H)} \leq |f_1 - f_2|.$$

On the other hand, $\sup |Rf_1(t) - Rf_2(t)| \ge Rf_1(0) - Rf_2(0)| = |f_1 - f_2|$, which proves that R is an isometry.

Remark 3. The above lemma implies the existence of the inverse operator to R with domain im R closed in $\mathcal{C}(I, H)$.

LEMMA 2. The operator A from $\mathcal{C}(I, H)$ into H given by Au = u(0) is a retraction on H. A coretraction for it is the map R given by (24). Moreover, R satisfies the growth condition with exponent $\alpha_R = 1$.

Proof. Observe that $(A \circ R)f = Au = u(0)$ for every weak solution of the problem (23). Thus $(A \circ R)f = f$ for each $f \in H$, because $\dim L = H^2(T, \mathbb{R}^k) \cap H^1_0(T, \mathbb{R}^k)$ is dense in H and a weak solution of the above problem exists for each initial value f in $H = \overline{\dim L}$.

Since R is an isometry by Lemma 1, it is a Lipschitz mapping and, as in Corollary 2, it satisfies the inequality

$$||Rf||_{\mathscr{C}(I,H)} \le C(1+|f|)$$
 for some constant C .

Now having proved lemmas we can proceed to the proof of Theorem 3.

Proof of Theorem 3. By Lemma 2, the coretraction R satisfies the growth condition with exponent $\alpha_R = 1$. Because of (20) and (21), the same holds for j and F with $\alpha_j = \alpha$ and $\alpha_F = \beta$. Thus $\alpha_R \alpha_j \alpha_F < 1$ and $\text{dom } j \supset \text{im } R$ and dom F = Z. This means that all assumptions of Theorem 1 are fulfilled. Therefore we conclude that there exists $u \in \mathcal{C}(I, H)$ such that $u(0) \in F(ju)$ and $u \in \text{im } R$; in other words, u is a weak solution of (22).

Example 2. A special case of (18) is the class of problems

(26) Find a function u such that

$$\frac{\partial u}{\partial t} - \frac{\partial^2 u}{\partial x^2} = g(t, x),$$

$$u(0, x) \in F\left[\left| \int_I \int_T \chi(\tau, z, x) u |u|^{q_1 - 1} (\tau, z) d\tau dz \right|^{1/q_2}\right],$$

$$u(t, 0) = 0 = u(t, 1),$$

where I = [0, a], T = (0, 1), $\chi \in L^1(I \times T \times T, R^{k \times k})$ and the mapping $F(\cdot)$ from $L^2(T, R)$ into the closed subsets of $H = L^2(T, R^k)$ need not admit a continuous selection. The physical model of such a situation can be the problem of seeking the distribution of concentrations and/or temperatures u(t, x) in a pipe of length 1 for a given arbitrary emission-absorption field g(t, x). Initial constraints depend on a nonlinear mean-value observed from a measuring device with characteristic χ which can depend on time. If we fix $q_2 = 2$, $q_1 = 1$ and $\chi = \chi_{[a-\epsilon,a]\times T\times T} \mathrm{id}_{R^k}$, we deduce that for an arbitrary time a there exists a real $b \ge 0$ such that

$$b^2 = \Big| \int_{a-\epsilon}^{a} \int_{T} u(t, z) dt dz \Big|$$

and the trajectories u(t, x) are generated by the set of initial values F(b).

COROLLARY 4. The problem (26) admits a weak solution $u \in \mathcal{C}(I, H)$ if we assume that $0 < q_1 < 2$, $\max(1, q_1) < q_2 < +\infty$, $\chi(\cdot, \cdot, x) \in L^r(I \times T, \mathbb{R}^{k \times k})$, $\chi(\tau, z, \cdot) \in L^r(T, \mathbb{R}^{k \times k})$, $\tau \sigma > 1$ and $\tau, \sigma \in [1, +\infty]$.

It is sufficient to show that the mapping $j: \mathcal{C}(I, H) \to L^2(T, R)$ defined by

(27)
$$(ju)(x) = \left| \int_{T} \int_{T} \chi(\tau, z, x) u |u|^{q_1 - 1} (\tau, z) d\tau dz \right|^{1/q_2}$$

is completely continuous and fulfils the growth condition with $Z = L^2(T, R)$.

LEMMA 3. The mapping $j: \mathcal{C}(I, H) \to Z$ given by (27) is completely continuous and satisfies the growth condition with exponent $\alpha = q_1/q_2 < 1$.

Proof. Step 1. The mapping T_{q_1} given by $T_{q_1}(u) = u |u|^{q_1-1}$ is continuous from $\mathcal{C}(I, H)$ into $L^s(I \times T, \mathbb{R}^k)$ as in the proof of Corollary 1 and, moreover,

$$||T_{q_1}u||_{s,I\times T}\leqslant C_1||u||_{\mathscr{C}(I,H)}^{q_1},$$

provided only $s = 2/q_1 \ge 1$.

Step 2. The operator U from $L^s(I \times T, \mathbb{R}^k)$ into $L^s(T, \mathbb{R}^k)$ given by

$$U(v) = \iint_{I} v(\tau, z) \chi(\tau, z, x) d\tau dz$$

is linear and compact if we assume that s > 1 and $r\sigma > 1$. This is an immediate consequence of Theorem XI.3.3 from [9].

Step 3. The mapping $|T_{1/q_1}|(w) = |w|^{1/q_1}$ is continuous from $L^s(T, \mathbb{R})$ into $L^{2q_2/q_1}(T, \mathbb{R})$ if $q_2 > 1$ and into $Z = L^2(T, \mathbb{R})$ for $q_1/q_2 \le 1$. We also have

$$|T_{1/q_2}w|_H \leqslant C_2 ||w||_{s,T}^{1/q_2}.$$

Step 4. The mapping $j = |T_{1/q_2}| \circ U \circ T_{q_1}$ is actually into W and since U is compact, j is completely continuous. Moreover,

$$|ju| \leq C_i (1 + ||u||_{\mathcal{C}(I,H)})^{q_1/q_2}.$$

Indeed,

$$|ju|\leqslant C_2\,\|(U\circ T_{q_1})(u)\|_{s,T}^{1/q_2}\leqslant C_3\,\|\,T_{q_1}u\|_{s,I\times T}^{1/q_2}\leqslant C\,\|u\|_{C(I,H)}^{q_1/q_2}.\quad\blacksquare$$

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> Reçu par la Rédaction le 19.12.1988 Révisé le 20.09.1989