

On some recurrence formulae for the H -function

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1. Fox ([3], p. 408), introduced the H -function in the form of Mellin-Barnes type integral, which has been symbolically denoted by Gupta and Jain [4]

$$(1.1) \quad H_{p,q}^{m,n} \left[x \left| \begin{matrix} \{(a_p, \alpha_p)\} \\ \{(b_q, \beta_q)\} \end{matrix} \right. \right] = \frac{1}{2\pi i} \int_T \frac{\prod_{j=1}^m \Gamma(b_j - \beta_j s) \prod_{j=1}^n \Gamma(1 - a_j + \alpha_j s)}{\prod_{j=m+1}^q \Gamma(1 - b_j + \beta_j s) \prod_{j=n+1}^p \Gamma(a_j - \alpha_j s)} x^s ds,$$

where $\{(f_r, \nu_r)\}$ stands for the set of the parameters $(f_1, \nu_1), \dots, (f_r, \nu_r)$; x is not equal to zero and empty product is interpreted as unity; p, q, m and n are integers satisfying $1 \leq m \leq q$; $0 \leq n \leq p$; α_j ($j = 1, 2, \dots, p$), β_j ($j = 1, 2, \dots, q$) are positive numbers and a_j ($j = 1, 2, \dots, p$), b_j ($j = 1, 2, \dots, q$) are complex numbers such that no pole of $\Gamma(b_h - \beta_h s)$ ($h = 1, 2, \dots, m$) coincides with any pole of $\Gamma(1 - a_i + \alpha_i s)$ ($i = 1, 2, \dots, n$), i.e.,

$$(1.2) \quad \alpha_i(b_h + \nu) \neq \beta_h(a_i - \eta - 1) \\
 (\nu, \eta = 0, 1, \dots; h = 1, 2, \dots, m; i = 1, 2, \dots, n).$$

Moreover, we assume that (see [2a], pp. 239-240)

$$\mu = \sum_{j=1}^q \beta_j - \sum_{j=1}^p \alpha_j \geq 0,$$

and that the relation

$$0 < |x^\mu| < \prod_{j=1}^p \alpha_j^{-\alpha_j} \prod_{j=1}^q \beta_j^{\beta_j} \quad \text{for} \quad \mu = 0$$

holds. T is a contour in the complex s -plane such that the points $s = (b_j + \nu)/\beta_j$ ($j = 1, \dots, m; \nu = 0, 1, \dots$), resp. $s = (a_j - 1 - \nu)/\alpha_j$ ($j = 1, \dots, n; \nu = 0, 1, \dots$) lie to the right, resp. left of T , while further T runs from $s = \infty - ik$ to $s = \infty + ik$. Here k is a constant with $k > |\text{Im} b_j|/\beta_j$ ($j = 1, \dots, m$). The conditions for the contour T can be fulfilled on account of (1.2).

In section 2 of this paper we have established some formulae for the derivative of the H -function, keeping in view the symmetry of the parameters involved in the function; by the process of differentiation under the sign of integration. In section 3, we have derived some recurrence formulae for the H -function, with the help of results of section 2.

2. In this section we establish the following formulae:

$$(2.1) \quad x \frac{d}{dx} \left\{ H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} (a_p, \alpha_p) \\ (b_q, \beta_q) \end{matrix} \right. \right] \right\} \\ = \frac{\delta}{\alpha_1} H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} (a_1-1, \alpha_1), (a_2, \alpha_2), \dots, (a_p, \alpha_p) \\ (b_1, \beta_1), \dots, (b_q, \beta_q) \end{matrix} \right. \right] + \\ + \frac{\delta(a_1-1)}{\alpha_1} H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} (a_p, \alpha_p) \\ (b_q, \beta_q) \end{matrix} \right. \right]$$

where $n \geq 1$,

$$(2.2) \quad x \frac{d}{dx} \left\{ H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} (a_p, \alpha_p) \\ (b_q, \beta_q) \end{matrix} \right. \right] \right\} = \frac{\delta(a_p-1)}{\alpha_p} H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} (a_p, \alpha_p) \\ (b_q, \beta_q) \end{matrix} \right. \right] - \\ - \frac{\delta}{\alpha_p} H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} (a_1, \alpha_1), \dots, (a_{p-1}, \alpha_{p-1}), (a_p-1, \alpha_p) \\ (b_1, \beta_1), \dots, (b_q, \beta_q) \end{matrix} \right. \right]$$

provided $n \leq p-1$,

$$(2.3) \quad x \frac{d}{dx} \left\{ H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} (a_p, \alpha_p) \\ (b_q, \beta_q) \end{matrix} \right. \right] \right\} = \frac{b_1 \delta}{\beta_1} H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} (a_p, \alpha_p) \\ (b_q, \beta_q) \end{matrix} \right. \right] - \\ - \frac{\delta}{\beta_1} H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} (a_1, \alpha_1), \dots, (a_p, \alpha_p) \\ (1+b_1, \beta_1), (b_2, \beta_2), \dots, (b_q, \beta_q) \end{matrix} \right. \right]$$

where $m \geq 1$,

$$(2.4) \quad x \frac{d}{dx} \left\{ H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} (a_p, \alpha_p) \\ (b_q, \beta_q) \end{matrix} \right. \right] \right\} = \frac{\delta b_q}{\beta_q} H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} (a_p, \alpha_p) \\ (b_q, \beta_q) \end{matrix} \right. \right] + \\ + \frac{\delta}{\beta_q} H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} (a_1, \alpha_1), \dots, (a_p, \alpha_p) \\ (b_1, \beta_1), \dots, (b_{q-1}, \beta_{q-1}), (1+b_q, \beta_q) \end{matrix} \right. \right]$$

provided $1 \leq m \leq q-1$.

Proof. To prove (2.1), expressing the H -function on the left-hand side as Mellin-Barnes type integral (1.1), changing the order of differentiation and integration, which is easily justifiable, we have

$$(2.5) \quad \delta \frac{1}{2\pi i} \int_r \frac{\prod_{j=1}^m \Gamma(b_j - \beta_j s) \prod_{j=1}^n \Gamma(1 - a_j + a_j s)}{\prod_{j=m+1}^q \Gamma(1 - b_j + \beta_j s) \prod_{j=n+1}^p \Gamma(a_j - a_j s)} s x^{\delta s} ds,$$

now, in view of

$$\begin{aligned} s\Gamma(1 - a_1 + a_1 s) &= \frac{1}{\alpha_1} (1 - a_1 + a_1 s + a_1 - 1) \Gamma(1 - a_1 + a_1 s) \\ &= \frac{1}{\alpha_1} [\Gamma(2 - a_1 + a_1 s) + (a_1 - 1) \Gamma(1 - a_1 + a_1 s)], \end{aligned}$$

(2.5) reduces to

$$\begin{aligned} \frac{\delta}{\alpha_1} \cdot \frac{1}{2\pi i} \int_T \frac{\prod_{j=1}^m \Gamma(b_j - \beta_j s) \prod_{j=2}^n \Gamma(1 - a_j + a_j s)}{\prod_{j=m+1}^q \Gamma(1 - b_j + \beta_j s) \prod_{j=n+1}^p \Gamma(a_j - a_j s)} \times \\ \times [\Gamma(2 - a_1 + a_1 s) + (a_1 - 1) \Gamma(1 - a_1 + a_1 s)] x^{\delta s} ds \end{aligned}$$

again using (1.1), the definition of H -function, we get the result (2.1).

Similarly, other relations can easily be established.

3. Now, subtracting (2.1) from (2.2), (2.3) and (2.4) we respectively get

$$\begin{aligned} (3.1) \quad (a_p \alpha_1 - a_1 a_p + a_p - a_1) H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} \{(a_p, a_p)\} \\ \{(b_q, \beta_q)\} \end{matrix} \right. \right] \\ = a_p H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} (a_1 - 1, a_1), (a_2, a_2), \dots, (a_p, a_p) \\ (b_1, \beta_1), \dots, (b_q, \beta_q) \end{matrix} \right. \right] + \\ + a_1 H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} (a_1, a_1), \dots, (a_{p-1}, a_{p-1}), (a_p, a_p) \\ (b_1, \beta_1), \dots, (b_q, \beta_q) \end{matrix} \right. \right], \end{aligned}$$

where $1 \leq n \leq p - 1$,

$$\begin{aligned} (3.2) \quad (b_1 \alpha_1 - a_1 \beta_1 + \beta_1) H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} \{(a_p, a_p)\} \\ \{(b_q, \beta_q)\} \end{matrix} \right. \right] \\ = \beta_1 H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} (a_1 - 1, a_1), (a_2, a_2), \dots, (a_p, a_p) \\ (b_1, \beta_1), \dots, (b_q, \beta_q) \end{matrix} \right. \right] + \\ + a_1 H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} (a_1, a_1), \dots, (a_p, a_p) \\ (1 + b_1, \beta_1), (b_2, \beta_2), \dots, (b_q, \beta_q) \end{matrix} \right. \right], \end{aligned}$$

provided $n \geq 1$, $m \geq 1$, and

$$\begin{aligned} (3.3) \quad (b_q \alpha_1 - a_1 \beta_q + \beta_q) H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} \{(a_p, a_p)\} \\ \{(b_q, \beta_q)\} \end{matrix} \right. \right] \\ = \beta_q H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} (a_1 - 1, a_1), (a_2, a_2), \dots, (a_p, a_p) \\ (b_1, \beta_1), \dots, (b_q, \beta_q) \end{matrix} \right. \right] - \\ - a_1 H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} (a_1, a_1), \dots, (a_p, a_p) \\ (b_1, \beta_1), \dots, (b_{q-1}, \beta_{q-1}), (b_q + 1, \beta_q) \end{matrix} \right. \right], \end{aligned}$$

where $n \geq 1$, $1 \leq m \leq q - 1$.

Subtracting (2.2) from (2.3) and (2.4), we have

$$(3.4) \quad (a_p \beta_1 - b_1 a_p - \beta_1) H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} \{(a_p, a_p)\} \\ \{(b_q, \beta_q)\} \end{matrix} \right. \right] \\ - \beta_1 H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} (a_1, a_1), \dots, (a_{p-1}, a_{p-1}), (a_p - 1, a_p) \\ (b_1, \beta_1), \dots, (b_q, \beta_q) \end{matrix} \right. \right] \\ - a_p H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} (a_1, a_1), \dots, (a_p, a_p) \\ (1 + b_1, \beta_1), (b_2, \beta_2), \dots, (b_q, \beta_q) \end{matrix} \right. \right],$$

provided $m \leq 1$, $n \leq p - 1$, and

$$(3.5) \quad (a_p \beta_q - b_q a_p - \beta_q) H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} \{(a_p, a_p)\} \\ \{(b_q, \beta_q)\} \end{matrix} \right. \right] \\ - \beta_q H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} (a_1, a_1), \dots, (a_{p-1}, a_{p-1}), (a_p - 1, a_p) \\ (b_1, \beta_1), \dots, (b_q, \beta_q) \end{matrix} \right. \right] \\ - a_p H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} (a_1, a_1), \dots, (a_p, a_p) \\ (b_1, \beta_1), \dots, (b_{q-1}, \beta_{q-1}), (1 + b_q, \beta_q) \end{matrix} \right. \right],$$

where $1 \leq m \leq q - 1$, $n \leq p - 1$.

Subtracting (2.3) from (2.4), we obtain

$$(3.6) \quad (b_1 \beta_q - b_q \beta_1) H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} \{(a_p, a_p)\} \\ \{(b_q, \beta_q)\} \end{matrix} \right. \right] \\ - \beta_q H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} (a_1, a_1), \dots, (a_p, a_p) \\ (1 + b_1, \beta_1), (b_2, \beta_2), \dots, (b_q, \beta_q) \end{matrix} \right. \right] \\ - \beta_1 H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} (a_1, a_1), \dots, (a_p, a_p) \\ (b_1, \beta_1), \dots, (b_{q-1}, \beta_{q-1}), (1 + b_q, \beta_q) \end{matrix} \right. \right],$$

provided $1 \leq m \leq q - 1$.

Since the H -function is symmetrical in the pairs $(a_1, a_1), \dots, (a_n, a_n)$; likewise in $(a_{n+1}, a_{n+1}), \dots, (a_p, a_p)$; in $(b_1, \beta_1), \dots, (b_m, \beta_m)$ and in $(b_{m+1}, \beta_{m+1}), \dots, (b_q, \beta_q)$, so the results established in sections 2 and 3 can be written in various other forms.

4. Particular cases

(i) (2.1) with $\delta = a_1$, (2.2) with $\delta = a_p$, (2.3) with $\delta = \beta_1$, (2.4) with $\delta = \beta_q$ reduce to results due to author [1].

(ii) Taking $\delta = a_j = \beta_h = 1$ ($j = 1, 2, \dots, p$, $h = 1, 2, \dots, q$) in (2.1), (3.1) and (3.2), we respectively get the known results ([2], p. 210(13), [2], p. 210 (12) and [2], p. 209(11)).

(iii) Setting $a_1 = \beta_q$ and $\delta = 1$ in (3.3), we get the relation as in [4], p. 103, 4 (ii).

(iv) Due to the symmetry of the parameters $(a_1, \alpha_1), (a_2, \alpha_2), \dots, (a_n, \alpha_n)$, (2.1) can also be written as

$$(4.1) \quad x \frac{d}{dx} \left\{ H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} \{(a_p, \alpha_p)\} \\ \{(b_q, \beta_q)\} \end{matrix} \right. \right] \right\} \\ = \frac{\delta}{a_2} H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} (a_1, \alpha_1), (a_2-1, \alpha_2), (a_3, \alpha_3), \dots, (a_p, \alpha_p) \\ (b_1, \beta_1), \dots, (b_q, \beta_q) \end{matrix} \right. \right] \\ + \frac{\delta(a_2-1)}{a_2} H_{p,q}^{m,n} \left[x^\delta \left| \begin{matrix} \{(a_p, \alpha_p)\} \\ \{(b_q, \beta_q)\} \end{matrix} \right. \right],$$

where $n \geq 2$.

Now subtracting (4.1) from (2.1) and putting $a_2 = a_1$ we obtain a known formula ([4], p. 103, 4(i)).

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