

## CONVEXITY AND VARIATION DIMINISHING PROPERTY FOR BERNSTEIN POLYNOMIALS IN HIGHER DIMENSIONS

MAREK BEŚKA

*Faculty of Applied Physics and Mathematics, Technical University of Gdańsk  
 Majakowskiego 11/12, 80-952 Gdańsk, Poland*

### 1. Introduction

Let  $f(x)$  be a real function defined in  $Q := [0, 1]$ . The Bernstein polynomial associated with  $f$  is defined by

$$(1) \quad B^n(f; x) := \sum_{i=0}^n f_i \cdot \binom{n}{i} x^i (1-x)^{n-i}, \quad x \in Q,$$

where  $f_i := f(i/n)$  for  $i = 0, 1, \dots, n$ .

Joining  $((i-1)/n, f_{i-1})$  and  $(i/n, f_i)$  by a line segment, for  $i = 1, 2, \dots, n$ , we get a piecewise linear continuous function which is denoted by  $\hat{f}_n(x)$  and called the *Bézier polygon of  $B^n(f; x)$* .

It is easy to show that:

- (i) If  $\hat{f}_n(x)$  is convex in  $Q$  then so is  $B^n(f; x)$ .
- (ii) If  $f(x)$  is convex in  $Q$  then

$$(2) \quad B^n(f; x) \geq B^{n+1}(f; x), \quad n = 1, 2, \dots, \quad \text{for } x \in Q.$$

(iii) The variation diminishing property holds, i.e.

$$(3) \quad V[B^n; Q] \leq V_1[\hat{f}_n; Q],$$

with equality if and only if  $\hat{f}_n(x)$  is convex or concave. Here

$$(4) \quad V[B^n; Q] := \int_Q \left| \frac{d^2 B^n}{dx^2} \right| dx,$$

$$(5) \quad V_1[\hat{f}_n; Q] := n \sum_{i=0}^{n-2} |\Delta^2 f_i|,$$

$$\Delta f_i := f_{i+1} - f_i, \quad i = 0, 1, \dots, n-1.$$

G. Chang, P. Davis and J. Hoschek (see [1], [3]) extended these results to the Bernstein polynomials over triangles. In the present paper we attempt to extend these results to the Bernstein polynomials over a  $k$ -dimensional simplex  $Q$ . In this case the definition of a variation like (5) called now the *variation of the Bézier net* is more complicated, but in the case of  $k = 1, 2$  it coincides with the variations as given in [2], [3]. We also give an answer to the problem whether the variation of the Bézier net is equal to  $\text{Var}(\Delta f_n)$ . Here the Laplace operator  $\Delta$  is taken in the distribution sense (see a remark in Section 3). These problems were suggested to me by Professor Z. Ciesielski.

## 2. Notation

Let us begin with some definitions. Let  $Q := [P_1, P_2, \dots, P_{k+1}]$  be the  $k$ -dimensional simplex with vertices  $P_1, P_2, \dots, P_{k+1}$ , where  $P_i \in R^k$  for  $i = 1, 2, \dots, k+1$ . By  $Q_\alpha$  ( $1 \leq \alpha \leq k+1$ ) we denote the  $(k-1)$ -dimensional face of the simplex  $Q$  which does not contain the vertex  $P_\alpha$ . By  $W := [T_1, T_2, \dots, T_{k+1}]$  we denote the simplex with the vertices  $T_i = (0, \dots, 0, 1, 1, \dots, 1)$ , where  $i = 1, 2, \dots, k+1$ , and by  $K_n(W)$  the subdivision of the simplex  $W$  such that a simplex  $\Omega$  belongs to  $K_n(W)$  if and only if

$$\Omega = \Delta_{i_1 i_2 \dots i_k}^n + v$$

where

$$\Delta_{i_1 i_2 \dots i_k}^n = \{(x_1, \dots, x_k) \in R^k; 0 \leq x_{i_1} \leq x_{i_2} \leq \dots \leq x_{i_k} \leq 1/n\},$$

$i_1, i_2, \dots, i_k$  is a permutation of  $\{1, 2, \dots, k\}$ , and the coordinates of the vector  $v = (v_1, v_2, \dots, v_k) \in R^k$  satisfy the following conditions:

- (i)  $nv_i \in N = \{0, 1, 2, \dots\}$  for  $i = 1, 2, \dots, k$ ,
- (ii)  $0 \leq v_1 \leq v_2 \leq \dots \leq v_k < 1$ .

Now, let  $L: R^k \rightarrow R^k$  be an affine transformation such that

$$L(T_i) = P_i \quad \text{for } i = 1, 2, \dots, k+1.$$

Then  $L$  transforms the subdivision  $K_n(W)$  of the simplex  $W$  to some subdivision of the simplex  $Q$ , which we denote by  $S_n(Q)$ . It is known that each point  $P \in Q$  can be uniquely expressed as

$$P = \sum_{i=1}^{k+1} u_i P_i$$

with  $u_1 + u_2 + \dots + u_{k+1} = 1$ ,  $u_i \geq 0$ ,  $1 \leq i \leq k+1$ .

The numbers  $u_1, u_2, \dots, u_{k+1}$  are called the *barycentric coordinates* of  $P$  with respect to the simplex  $Q$ . We identify the point  $P \in Q$  with its barycentric coordinates and write  $P = (u_1, u_2, \dots, u_{k+1})$ . For  $n \in N$  and a given

function  $f: Q \rightarrow R$  we define

$$F_n := \left\{ f_\beta; f_\beta := f\left(\frac{\beta}{n}\right), \beta \in N^{k+1}, |\beta| = n \right\}$$

where

$$\beta = (\beta_1, \beta_2, \dots, \beta_{k+1}) \quad \text{and} \quad |\beta| := \sum_{i=1}^{k+1} \beta_i.$$

We also define

$$(6) \quad B^n(f; P) = \sum_{|\beta|=n} f_\beta J_\beta^n(P) \quad \text{for } P \in Q$$

where

$$(7) \quad J_\beta^n(P) := \frac{n!}{\beta!} u^\beta := \frac{n!}{\beta_1! \beta_2! \dots \beta_{k+1}!} u_1^{\beta_1} u_2^{\beta_2} \dots u_{k+1}^{\beta_{k+1}}$$

and  $P = (u_1, u_2, \dots, u_{k+1})$ .

The polynomials  $J_\beta^n(P)$  are called the *basic Bernstein polynomials*.  $B^n(f; P)$  is called the *n-th Bernstein polynomial over the simplex Q*. Setting

$$\tilde{P}_\beta := (P, f_\beta) := \left( \frac{\beta_1}{n}, \frac{\beta_2}{n}, \dots, \frac{\beta_{k+1}}{n}, f_\beta \right),$$

we get a point on the surface associated with the function  $f(P)$ . The points  $\tilde{P}_\beta$  with  $|\beta| = n$  are called the *Bézier points of  $B^n(f; P)$* . For any simplex  $\Omega \in S_n(Q)$  we have  $k+1$  Bézier points. Joining them by a  $k$ -dimensional plane we obtain a continuous piecewise linear surface  $\hat{f}_n(P)$ , which is called the *Bézier net of  $B^n(f; P)$  over the simplex Q*.

Let  $E_i$  ( $1 \leq i \leq k+1$ ) be the partial shift operator defined by

$$E_i f_\beta := f_{\beta + \hat{e}_i}$$

where  $|\beta| = n-1$ ,  $\hat{e}_i = (0, \dots, 0, 1, 0, \dots, 0) \in R^{k+1}$ .

For convenience we introduce

$$(8) \quad D_{ij}(f_\beta) := -(E_i - E_{i+1})(E_j - E_{j+1}) f_\beta$$

where  $|\beta| = n-2$ ,  $1 \leq i < j \leq k+1$  and  $E_{k+2} := E_1$ .

### 3. Results

The first theorem generalizes a result of G. Chang and P. Davis [1].

**THEOREM 1.** *The convexity of the Bézier net  $\hat{f}_n(P)$  over  $Q$  is equivalent to the following inequalities:*

$$(9) \quad D_{ij}(f_\beta) \geq 0$$

for  $1 \leq i < j \leq k+1$ ,  $|\beta| = n-2$ .

The proof is standard and will be omitted.

The next theorem is also a multidimensional analogue of a theorem of G. Chang and P. Davis.

**THEOREM 2.** (i) *If the Bézier net  $\hat{f}_n(P)$  over  $Q$  is convex then so is the Bernstein polynomial  $B^n(f; P)$ .*

(ii) *If  $f(P)$  is convex in  $Q$  then we have*

$$(10) \quad B^n(f; P) \geq B^{n+1}(f; P) \quad \text{for } P \in Q, n = 1, 2, \dots$$

*Proof.* (i) The proof is based on the well-known convexity test for any function in  $C^2(Q)$  and the following

**LEMMA 1.** *For the Bernstein polynomial  $B^n(f; P)$  we have the equality*

$$(11) \quad \frac{\partial^2 B^n(f; P)}{\partial x_r \partial x_{r'}} = \frac{n(n-1)}{k^2 |Q|} \sum_{|\beta|=n-2} \sum_{1 \leq i < j \leq k+1} \left( \sum_{\alpha=i+1}^j n_\alpha |Q_\alpha|, e_r \right) \\ \times \left( \sum_{\alpha=i+1}^j n_\alpha |Q_\alpha|, e_{r'} \right) D_{ij}(f_\beta) J_\beta^n(P) \quad \text{for } r, r' = 1, 2, \dots, k$$

where  $P \in Q$ ,  $e_r = (0, \dots, 0, \overset{r}{1}, 0, \dots, 0) \in R^k$ ,  $r = 1, 2, \dots, k$ ,  $|Q| := \text{vol}_k Q$ ,  $|Q_\alpha| := \text{vol}_{k-1}(Q_\alpha)$ ,  $(\cdot, \cdot)$  is the scalar product in  $R^k$ , and  $n_\alpha$  is the unit outward normal vector to  $Q_\alpha$ .

The tedious proof will be omitted.

(ii) G. Chang and P. Davis ([1]) proved the statement for  $k = 2$ . For  $k > 2$  the proof is similar.

Now, we define a variation of the Bernstein polynomial  $B^n(f; P)$  by

$$(12) \quad V[B^n; Q] := \int_Q |\Delta B^n|$$

where for simplicity  $B^n$  stands for  $B^n(f; P)$  and  $\Delta$  is the Laplacian. The variation  $V_1[\hat{f}_n; Q]$  of the Bézier net  $\hat{f}_n(P)$  is defined by

$$(13) \quad V_1[\hat{f}_n; Q] := \frac{n!(k-1)!}{k(n+k-2)! |Q|} \sum_{|\beta|=n-2} \sum_{1 \leq i < j \leq k+1} \|D_{ij}(f_\beta)\|^2 \sum_{\alpha=i+1}^j n_\alpha |Q_\alpha|^2$$

where  $\|\cdot\|^2 = (\cdot, \cdot)$ .

For  $k = 2$  the variation  $V_1[\hat{f}_n; Q]$  of the Bézier net coincides with the variation introduced by T. Goodman [3]. Our next theorem generalizes the result obtained by G. Chang and J. Hoschek [2].

**THEOREM 3.** *For the Bernstein polynomial over the simplex  $Q$  the variation diminishing property holds. More precisely, we have*

$$(14) \quad V[B^n; Q] \leq V_1[\hat{f}_n; Q]$$

with equality if and only if  $\hat{f}_n(P)$  is either convex or concave.

For  $k = 1, 2$  the theorem was proved by G. Chang and J. Hoschek [2].  
For  $k > 2$  the proof is similar.

Since

$$(15) \quad V[B^n; Q] = \text{Var}(\Delta B^n)$$

where  $\text{Var}(\Delta B^n)$  is the total variation of the measure

$$v(A) := \int_A \Delta B^n,$$

the question arises whether the equality

$$(16) \quad V_1[\hat{f}_n; Q] = \text{Var}(\Delta \hat{f}_n)$$

holds.

*Remark.* Here the Laplace operator  $\Delta$  is taken in the distribution sense and because  $\Delta \hat{f}_n$  is a measure (not necessarily non-negative), the total variation  $\text{Var}(\Delta \hat{f}_n)$  is well defined.

The following lemma solves this problem for  $k = 1, 2$ .

LEMMA 2. For  $k = 1, 2$  the equality (16) holds.

*Proof.* For  $k = 1$  the proof is very simple.

If  $k = 2$  the simplex  $Q = [P_1, P_2, P_3]$  with vertices  $P_1 = P_1(x_1, y_1)$ ,  $P_2 = P_2(x_2, y_2)$ ,  $P_3 = P_3(x_3, y_3)$  is a triangle. Without loss of generality we can assume that

$$\det[P_1 - P_3, P_2 - P_3] := \det \begin{bmatrix} x_1 - x_3 & x_2 - x_3 \\ y_1 - y_3 & y_2 - y_3 \end{bmatrix} > 0.$$

The Stokes theorem yields

$$(17) \quad \begin{aligned} (\Delta \hat{f}_n)(\varphi) &= \int_Q \hat{f}_n \Delta \varphi \\ &= - \sum_{\Omega \in S_n(Q)} \left( \int_{\partial \Omega} \frac{\partial \hat{f}_n}{\partial x} m_1 \varphi d\sigma + \int_{\partial \Omega} \frac{\partial \hat{f}_n}{\partial y} m_2 \varphi d\sigma \right) \\ &= - \sum_{\Omega \in S_n(Q)} \sum_{r=1}^3 \left( \int_{\Omega_r} \frac{\partial \hat{f}_n}{\partial x} m_1 \varphi d\sigma + \int_{\Omega_r} \frac{\partial \hat{f}_n}{\partial y} m_2 \varphi d\sigma \right) \end{aligned}$$

where  $\varphi \in D(\text{Int } Q)$ , the space of test functions,  $(m_1, m_2)$  is the unit outward normal vector to the boundary  $\partial \Omega$ , and  $\sigma$  is the Lebesgue measure on  $\partial \Omega$ . First we consider the sum

$$(18) \quad \sum_{\Omega \in S_n(Q)} \int_{\Omega_1} \frac{\partial \hat{f}_n}{\partial x} m_1 \varphi d\sigma.$$

If  $\Omega_1 \not\subset Q$  (for  $\Omega \in S_n(Q)$ ) we can find a second triangle  $\Omega'$  such that  $\Omega_1 = \Omega'_1$ .

Thus the sum (18) is equal to

$$(19) \quad \sum_{\substack{\Omega \in S_n(Q) \\ \Omega_1 \neq Q_1}} \left( \int_{\Omega_1} \frac{\partial \hat{f}_n}{\partial x} m_1 \varphi d\sigma + \int_{\Omega'_1} \frac{\partial \hat{f}_n}{\partial x} m'_1 \varphi d\sigma \right).$$

Since  $(m'_1, m'_2) = -(m_1, m_2)$  the expression (19) is equal to

$$(20) \quad \frac{1}{2} \sum_{\substack{\Omega \in S_n(Q) \\ \Omega_1 \neq Q_1}} \left( \frac{\partial \hat{f}_n|_{\Omega}}{\partial x} - \frac{\partial \hat{f}_n|_{\Omega'_1}}{\partial x} \right) \int_{\Omega_1} \varphi d\sigma$$

where  $\hat{f}_n|_{\Omega'}$ ,  $\hat{f}_n|_{\Omega}$  are the restrictions of  $\hat{f}_n$  to  $\Omega'$ ,  $\Omega$ , respectively. We can assume that the barycentric coordinates of the vertices of the triangles  $\Omega = [U_1, U_2, U_3]$ ,  $\Omega' = [U'_1, U'_2, U'_3] \in S_n(Q)$  ( $\Omega_1 \neq Q_1$ ,  $\Omega_1 = \Omega'_1$ ) are the following:

$$U_1 = \left( \frac{i}{n}, \frac{j}{n}, \frac{k}{n} \right), \quad U_2 = \left( \frac{i-1}{n}, \frac{j+1}{n}, \frac{k}{n} \right), \quad U_3 = \left( \frac{i-1}{n}, \frac{j}{n}, \frac{k+1}{n} \right),$$

$$U'_1 = \left( \frac{i-2}{n}, \frac{j+1}{n}, \frac{k+1}{n} \right), \quad U'_2 = \left( \frac{i-1}{n}, \frac{j+1}{n}, \frac{k}{n} \right), \quad U'_3 = \left( \frac{i-1}{n}, \frac{j}{n}, \frac{k+1}{n} \right),$$

for  $i+j+k = n$ ,  $j, k \geq 0$ ,  $i \geq 2$ .

Now by elementary calculations we get

$$(21) \quad \frac{\partial \hat{f}_n|_{\Omega}}{\partial x} = -n \frac{\det \begin{bmatrix} y_1 - y_3 & y_2 - y_3 \\ f_{(i,j,k)} - f_{(i-1,j,k+1)} & f_{(i-1,j+1,k)} - f_{(i-1,j,k+1)} \end{bmatrix}}{\det [P_1 - P_3 \quad P_2 - P_3]},$$

$$(22) \quad \frac{\partial \hat{f}_n|_{\Omega'}}{\partial x} = n \frac{\det \begin{bmatrix} y_2 - y_1 & y_2 - y_3 \\ f_{(i-2,j+1,k+1)} - f_{(i-1,j,k+1)} & f_{(i-1,j+1,k)} - f_{(i-1,j,k+1)} \end{bmatrix}}{\det [P_1 - P_3 \quad P_2 - P_3]},$$

$$(23) \quad m_1 = \frac{y_3 - y_2}{|Q_1|}, \quad m_2 = \frac{x_2 - x_3}{|Q_1|}.$$

Thus the sum (20) is equal to

$$(24) \quad \sum_{\substack{i+j+k=n \\ j,k \geq 0 \\ i \geq 2}} \frac{n(y_2 - y_3)^2}{2|Q||Q_1|} (f_{(i-1,j+1,k)} + f_{(i-1,j,k+1)} - f_{(i,j,k)} - f_{(i-2,j+1,k+1)}) \int_{\Omega_1} \varphi d\sigma$$

$$= - \sum_{\substack{i+j+k=n \\ j,k \geq 0 \\ i \geq 2}} \frac{n(y_2 - y_3)^2}{2|Q||Q_1|} D_{13} f_{(i-2,j,k)} \int_{\Omega_1} \varphi d\sigma$$

$$= - \sum_{\substack{i+j+k=n-2 \\ i,j,k \geq 0}} \frac{n(y_2 - y_3)^2}{2|Q||Q_1|} D_{13} f_{(i,j,k)} \int_{\Omega_1} \varphi d\sigma.$$

In a similar way we obtain

$$(25) \quad \sum_{\Omega \in S_n(Q)} \int_{\Omega_1} \frac{\partial \hat{f}_n}{\partial y} m_2 \varphi d\sigma = - \sum_{i+j+k=n-2} \frac{n(x_2-x_3)^2}{2|Q||Q_1|} D_{13} f_{(i,j,k)} \int_{\Omega_1} \varphi d\sigma.$$

Hence

$$(26) \quad \sum_{\Omega \in S_n(Q)} \int_{\Omega_1} \left( \frac{\partial \hat{f}_n}{\partial x} m_1 + \frac{\partial \hat{f}_n}{\partial y} m_2 \right) \varphi d\sigma = - \sum_{i+j+k=n-2} \frac{n|Q_1|}{2|Q|} D_{13} f_{(i,j,k)} \int_{\Omega_1} \varphi d\sigma.$$

Now it is easy to check that

$$(27) \quad \sum_{\Omega \in S_n(Q)} \int_{\Omega_2} \left( \frac{\partial \hat{f}_n}{\partial x} m_1 + \frac{\partial \hat{f}_n}{\partial y} m_2 \right) \varphi d\sigma = - \sum_{i+j+k=n-2} \frac{n|Q_2|}{2|Q|} D_{12} f_{(i,j,k)} \int_{\Omega_2} \varphi d\sigma,$$

$$(28) \quad \sum_{\Omega \in S_n(Q)} \int_{\Omega_3} \left( \frac{\partial \hat{f}_n}{\partial x} m_1 + \frac{\partial \hat{f}_n}{\partial y} m_2 \right) \varphi d\sigma = - \sum_{i+j+k=n-2} \frac{n|Q_3|}{2|Q|} D_{23} f_{(i,j,k)} \int_{\Omega_3} \varphi d\sigma.$$

By (26), (27), (28) the variation of  $f_n$  is equal to

$$\begin{aligned} & \text{Var}(\Delta \hat{f}_n) \\ &= \frac{1}{2|Q|} \sum_{i+j+k=n-2} (|Q_1|^2 |D_{13} f_{(i,j,k)}| + |Q_2|^2 |D_{12} f_{(i,j,k)}| + |Q_3|^2 |D_{23} f_{(i,j,k)}|) \\ &= V_1[\hat{f}_n; Q]. \end{aligned}$$

In case  $k > 2$  equality (16) does not hold. More precisely the two variations  $\text{Var}(\Delta \hat{f}_n)$ ,  $V_1[\hat{f}_n; Q]$  are incomparable.

EXAMPLE 1. Let

$$f_\beta = \begin{cases} 1 & \text{for } \beta = n\hat{e}_i, \\ 0 & \text{for } \beta \neq n\hat{e}_i, \end{cases} \quad i = 1, 2, \dots, k+1, |\beta| = n.$$

One can prove that the following equalities hold:

$$\begin{aligned} V_1[f_n; Q] &= \frac{n!(k-1)!}{k|Q|(n+k-2)!} \sum_{j=1}^{k+1} |D_{j,j+1}(f_{\beta_{j+1}})| \cdot |Q_{j+1}|^2, \\ \text{Var}(\Delta \hat{f}_n) &= \frac{1}{k|Q|n^{k-2}} \sum_{j=1}^{k+1} |D_{j,j+1}(f_{\beta_{j+1}})| \cdot |Q_{j+1}|^2, \end{aligned}$$

where  $\beta_j = (n-2)\hat{e}_j$  for  $j = 1, 2, \dots, k+1$  and  $D_{k+1,k+2} := D_{1,k+1}$ ,  $\beta_{k+2} := \beta_1$ ,  $Q_{k+2} := Q_1$ .

Now, it is easy to see that

$$V_1[\hat{f}_n, Q] > \text{Var}(\Delta \hat{f}_n) \quad \text{for } k = 3, 4, \dots, n = 2, 3, \dots$$

Because the Bézier net is convex (by Theorem 1) we obtain (by Theorem 3)

$$\text{Var}(\Delta B^n) = V_1[\hat{f}_n; Q] > \text{Var}(\Delta \hat{f}_n).$$

Hence, the multidimensional version of the variation diminishing property for the Laplacian does not hold for  $k > 2$ .

EXAMPLE 2. Let  $n = p(k+1) + 2$ ,  $k, p \in N$ ,  $p \geq 3$ . Define

$$f_\beta = \begin{cases} 1 & \text{for } \beta = (p, p, \dots, p, p+2) \in N^{k+1}, \\ 0 & \text{for } \beta \neq (p, p, \dots, p, p+2) \in N^{k+1}, \end{cases} \quad |\beta| = n.$$

One can prove that the following equalities hold

$$V_1[\hat{f}_n; Q] = \frac{n!(k-1)!}{k|Q|(n+k-2)!} \sum_{|\beta|=n-2} \sum_{1 \leq i < j \leq k+1} |D_{ij}(f_\beta)| \left\| \sum_{\alpha=i+1}^j n_\alpha Q_\alpha \right\|^2,$$

$$\text{Var}(\Delta \hat{f}_n) = \frac{(k-1)!}{k|Q|n^{k-2}} \sum_{|\beta|=n-2} \sum_{1 \leq i < j \leq k+1} |D_{ij}(f_\beta)| \left\| \sum_{\alpha=i+1}^j n_\alpha Q_\alpha \right\|^2.$$

Now, it is easy to see that

$$V_1[\hat{f}_n; Q] < \text{Var}(\Delta \hat{f}_n) \quad \text{for } n = 2, 3, \dots, k = 3, 4, \dots$$

Fortunately, we can estimate the variation  $\text{Var}(\Delta \hat{f}_n)$  by  $V_1[\hat{f}_n; Q]$ .

LEMMA 3. For the Bézier net  $\hat{f}_n$  we have the inequalities

$$(29) \quad \frac{(n+k-2)!}{n^{k-2}n!} V_1[\hat{f}_n; Q] \geq \text{Var}(\Delta \hat{f}_n) \geq \frac{1}{(k-1)!} V_1[\hat{f}_n; Q],$$

$$k = 1, 2, \dots, n = 2, 3, \dots$$

The tedious proof will be omitted.

Theorem 3 and the above lemma yield the "multidimensional version of the variation diminishing property for the Laplacian".

THEOREM 4. For the Bernstein polynomial  $B_n(f; P)$  over the  $k$ -dimensional simplex  $Q$  the following inequality holds:

$$(30) \quad \text{Var}(\Delta B^n) \leq (k-1)! \text{Var}(\Delta \hat{f}_n),$$

where for large  $n$  the constant  $(k-1)!$  is best possible.

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