

**On a generalization of the functional equation  
 for the harmonic ratio of four points  
 on a projective line over an arbitrary commutative field**

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**INTRODUCTION**

Aczél, Gołąb, Kuczma and Siwek gave in [1] the general solution of the functional equation

$$(1) \quad \varphi \left( \frac{a_{11}^{\lambda} x_1 + a_{12}^{\lambda} x_2}{a_{21}^{\lambda} x_1 + a_{22}^{\lambda} x_2} \right) = \varphi(x_1, x_2), \quad x_k, a_{ij} \in R, \quad \det \|a_{ij}\| \neq 0$$

$$(\lambda = 1, 2, 3, 4),$$

where  $\varphi$  is an unknown real-valued function ( $R$  denotes the set of all real numbers).

A function  $\varphi$  satisfying (1) is an invariant of 4 points on the real projective line with respect to the corresponding projective group. One of the invariants is the harmonic ratio.

Benz determines in [2] all the invariants of 4 points on the projective line over an arbitrary, in general non-commutative field (Schiefkörper) with respect to the corresponding projective group.

In the present paper we give the general solution of functional equation (1), which is a generalization of (1).

The main result is contained in Theorem 4.

**I. DESCRIPTION OF THE GENERALIZATION OF (1)**

1. Suppose we are given an arbitrary commutative field  $D$ . Let us denote by  $L$  the linear group of matrices of order 2 over the field  $D$ . By  $L_0$  we denote the group of matrices  $kE$ , where  $k \in D$ ,  $k \neq 0$  and  $E$  is the unit matrix of  $L$ .  $L_0$  is a normal subgroup of  $L$ . By  $A$  we denote the factor group  $L/L_0$ . The elements of  $L$  and  $A$  we denote by  $a = \|a_{ij}\|$ ,  $b = \|b_{ij}\|, \dots$  and  $\alpha, \beta, \dots$ , respectively.

$A$  defines in  $L$  an equivalence relation the classes of which are the elements of  $A$ . We denote this relation by  $R_A$ .

2. Let us introduce the set  $\mathcal{X} = D \times D \setminus_{(0,0)}$ . We denote its elements by  $x = (x_1, x_2), y = (y_1, y_2), \dots$

In the set  $\mathcal{X}$  we consider the following representation group  $F$  of the group  $L$

$$(2) \quad y_i = \sum_{j=1}^2 a_{ij} x_j,$$

or shortly

$$(2') \quad y = ax, \quad x, y \in \mathcal{X}, \quad a \in L.$$

In (2')  $a \in L$  may be treated as an operator acting on the elements of  $\mathcal{X}$ . The relation  $R_1$  defined by

$$xR_1y \Leftrightarrow \exists_{k \in D} (k \neq 0, y_i = kx_i); \quad x, y \in \mathcal{X}$$

is compatible with this operator. We denote by  $\mathcal{E}$  the factor space  $\mathcal{X}/R_1$  and the factor group  $F/R_1$  by  $\mathcal{F}$ . The elements of  $\mathcal{E}$  are denoted by  $\xi, \eta, \dots$

The group  $\mathcal{F}$  may be written in the form  $\eta = a\xi, \xi, \eta \in \mathcal{E}, a \in L$ .

The relation  $R_A$ , defined in Section 1, is compatible with the group operation of the group  $\mathcal{F}$ . We denote by  $\hat{\mathcal{F}}$  the factor group  $\mathcal{F}/R_A$ . The group  $\hat{\mathcal{F}}$  may be written in the form

$$(3) \quad \eta = a \cdot \xi, \quad \xi, \eta \in \mathcal{E}, \quad a \in A.$$

3. We consider the following representation group of the group  $L$

$$(4) \quad y_i^\lambda = a_{ij}^\lambda x_j^\lambda, \quad x, y \in \mathcal{X}, \quad a \in L \quad (\lambda = 1, 2, 3, 4; i, j = 1, 2),$$

or shortly

$$(4') \quad y^\lambda = ax^\lambda, \quad x, y \in \mathcal{X}, \quad a \in L,$$

which we denote by  $\mathcal{F}^4$ .

Using the relations  $\hat{R}^\lambda \stackrel{\text{df}}{=} R_1$  ( $\lambda = 1, 2, 3, 4$ ) and  $R_A$  we may obtain from (4), in the way described in Section 2, the following group of transformations:

$$(5) \quad \eta^\lambda = a\xi^\lambda, \quad \xi^\lambda, \eta^\lambda \in \mathcal{E}, \quad a \in A \quad (\lambda = 1, 2, 3, 4),$$

which we denote by  $\hat{\mathcal{F}}^4$ .

4. Let us introduce the set

$$(6) \quad \mathcal{E}_*^4 = \{(\xi^\lambda): \xi^\lambda \in \mathcal{E}, \bigvee_{\lambda \neq \mu} (\xi^\lambda \neq \xi^\mu)\}.$$

If we restrict the transformations belonging to the group  $\hat{\mathcal{F}}^4$  to the set  $\mathcal{E}_*^4$  then we obtain — as can easily be proved — a new group of transformations, which we denote by  $\hat{\mathcal{F}}_*^4$ .

We give without proof the following

**Remark 1.** The restrictions of the group  $\mathcal{F}_*^4$  of transformations to its domains of transitivity are simple transitive groups (see [3]).

**5.** Let  $G$  be given representation group of the group  $L$  into an arbitrary space  $U$

$$(7) \quad v = g(u, a), \quad u, v \in U; \quad a \in L.$$

Under the assumption

**A.** For every  $u \in U$  the function  $g(u, a)$  in (7) is homogeneous of order 0 with respect to the whole group of variables  $a = (a_{ij})$ , the relation  $R_A$  is compatible with the group operation of the group  $G$ . We denote the factor group  $G/R_A$  by  $\hat{G}$ . This group may be written in the form

$$(8) \quad v = \hat{g}(u, a), \quad u, v \in U, \quad a \in A.$$

The transformation group  $\hat{G}$  is a representation group of the group  $A$ .

**6.** Now we consider the functional equation

$$(9) \quad \varphi(ax) = g(\varphi(x), a), \quad x \in \mathcal{X}, \quad a \in L,$$

where  $\varphi: \mathcal{X}^4 \rightarrow U$  is an unknown function.

Besides (9) let us consider the functional equation

$$(10) \quad \hat{\varphi}(a\xi) = \hat{g}(\varphi(\xi), a), \quad \xi \in \mathcal{E}, \quad a \in A,$$

where  $\hat{\varphi}: \mathcal{E}^4 \rightarrow U$  is unknown and  $\hat{g}$  is a given function of the type (8) (e.g.  $\hat{g} \in \hat{G}$ ).

We have the following connections between (9) and (10) (we omit the proofs):

**THEOREM 1.** If assumption **A** for the function  $g$  is satisfied and if  $\hat{\varphi}(x)$  is a solution of (9) and is homogeneous function of order 0 with respect to each variable  $x^\lambda$  ( $\lambda = 1, 2, 3, 4$ ), then the factorization<sup>(1)</sup>  $\hat{\varphi}(\xi)$  of  $\varphi(x)$  with respect to the relation  $R^4$  is a solution of (10).

Conversely,

**THEOREM 2.** If  $\hat{\varphi}(\xi)$  is a solution of (10) and assumption **A** for the function  $g$  in (9) is satisfied, then there exists one and only one solution

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<sup>(1)</sup> Suppose we are given a function  $\varphi: \mathcal{X} \rightarrow U$  and let  $R$  be an equivalence relation in  $\mathcal{X}$  such that for every  $x \in \mathcal{X}$  and every  $y \in [x]_R$  we have  $\varphi(x) = \varphi(y)$ . We may introduce a function  $\hat{\varphi}(\xi)$ ,  $\xi \in \mathcal{X}/R$ , such that  $\hat{\varphi}([x]_R) = \varphi(x)$  for every  $x \in \mathcal{X}$ . The function  $\hat{\varphi}(\xi)$  is named the factorization of the function  $\varphi(x)$  with respect to the relation  $R$  or shortly  $R$ -factorization of  $\varphi(x)$ .

$\varphi(x)$  of (9), homogeneous of order 0 with respect to each variable  $x^\lambda$ ,  $\lambda = 1, 2, 3, 4$ , such that its  $R^4$ -factorization coincides with  $\hat{\varphi}(\xi)$ .

7. If we denote by  $(x_k)$  the projective coordinates of a point  $X$  on the projective line  $P$  over the field  $D$  in an arbitrary projective coordinates system, then (2), or more exactly (3), represents the projective group of transformations on  $P$ . In the case where  $U = D$  and  $g(u, a) \equiv u$  equation (10) is the equation for the invariants of 4-points on  $P$ .

In this paper we shall consider 4-points such that every two points are different. This means that we shall say about the functional equation

$$(11) \quad \hat{\varphi}(a\xi) = \hat{g}(\hat{\varphi}(\xi), a), \quad \xi \in \mathcal{E}_*^4, \quad a \in \mathcal{A}.$$

## II. THE SOLUTION OF EQUATION (11)

The functional equation (11) will be solved here by using the method described in [4]. Now we are going to prepare some formulae which will be needed for the realization of this method.

1. We consider the family  $\Sigma$  of the domains of transitivity of the group  $\mathcal{F}_*^4$  [3].

DEFINITION 1 (see [4]). A set  $\mathcal{E}_*^4 \subset \mathcal{E}_*^4$  with the property of having one and only one point in common with every element of  $\Sigma$  will be called the *generator* of the set  $\mathcal{E}_*^4$  with respect to the family  $\Sigma$  (or with respect to the group  $\mathcal{F}_*^4$ ).

Without proof we give the following

THEOREM 3. *Two points of  $\mathcal{E}_*^4$  (as 4-points on  $P$ ) have the same harmonic ratio<sup>(2)</sup> if and only if they belong to the same domain of transitivity of the group  $\mathcal{F}_*^4$ .*

(<sup>2</sup>) If  $P$  is a projective line over  $D$  with an arbitrarily fixed coordinate system and if there is given a point  $(\xi) \in \mathcal{E}_*^4$ , then there exists one and only one 4 point  $(x)$  in  $P$  with the coordinates  $x = (x_i)$  such that  $\xi = [x]_{R_1}$  ( $\lambda = 1, 2, 3, 4$ ).

We give the following well-known definition: The harmonic ratio  $s$  of a point  $(\xi)$  is

$$(13') \quad s(\xi, \xi, \xi, \xi) \stackrel{\text{df}}{=} \frac{W^{13}W^{24}}{W^{14}W^{23}},$$

where

$$W^{\lambda\mu} \stackrel{\text{df}}{=} \det \begin{vmatrix} \lambda & \lambda \\ x_1 & x_2 \\ \mu & \mu \\ x_1 & x_2 \end{vmatrix}.$$

From Theorem 3 it follows that every generator of the set  $\Xi_*^4$  can be parametrized by the harmonic ratio, which we denote by  $s$ .

Let us introduce the set

$$(12) \quad \Xi_*^4 \stackrel{\text{df}}{=} \{(\overset{\lambda}{\xi}(s)): \overset{\lambda}{\xi} \in x = (\overset{\lambda}{k}\overset{\lambda}{\sigma}_i(s)), \overset{\lambda}{k} \in D, \overset{\lambda}{k} \neq 0, s \in S\},$$

where

$$(13) \quad S = \{s: s \in D, s \neq 0, 1\}$$

and

$$(14) \quad \begin{aligned} \overset{1}{\sigma}_1 &= 1, & \overset{1}{\sigma}_2 &= 0, \\ \overset{2}{\sigma}_1 &= 0, & \overset{2}{\sigma}_2 &= 1, \\ \overset{3}{\sigma}_1 &= 1, & \overset{3}{\sigma}_2 &= 1, \\ \overset{4}{\sigma}_1 &= s, & \overset{4}{\sigma}_2 &= 1. \end{aligned}$$

The parametrization of the set  $\Xi_*^4$  given by (12), (13) and (14) is one-to-one. The harmonic ratio of  $(\overset{\lambda}{\xi}(s))$  is equal to  $s$ . Indeed, we have

$$(15) \quad W^{\lambda\mu}(x, x) = \overset{\lambda}{k}\overset{\mu}{k} \cdot \omega^{\lambda\mu},$$

where

$$(16) \quad \omega^{\lambda\mu} = \det \begin{vmatrix} \overset{\lambda}{\sigma}_1 & \overset{\lambda}{\sigma}_2 \\ \overset{\mu}{\sigma}_1 & \overset{\mu}{\sigma}_2 \end{vmatrix}, \quad \omega^{\lambda\mu} = -\omega^{\mu\lambda}.$$

From (14) and (16) we obtain

$$(17) \quad \begin{aligned} \omega^{12} &= 1, & \omega^{23} &= -1, \\ \omega^{13} &= 1, & \omega^{24} &= -s, \\ \omega^{14} &= 1, & \omega^{34} &= 1-s. \end{aligned}$$

Using (15) and (17) we obtain

$$(\overset{1}{\xi}, \overset{2}{\xi}, \overset{3}{\xi}, \overset{4}{\xi}) = \frac{W^{13} W^{24}}{W^{14} W^{23}} = \frac{\omega^{13} \omega^{24}}{\omega^{14} \omega^{23}} = \frac{1 \cdot (-s)}{1 \cdot (-1)} = s.$$

From this it follows that the set  $\Xi_*^4$  defined by (12), (13) and (14) is a generator of the set  $\Xi_*^4$ . This means that the transformation

$$(18) \quad \overset{\lambda}{\eta} = a \overset{\lambda}{\xi}(s), \quad s \in S, \quad a \in A, \quad (\overset{\lambda}{\eta}) \in \Xi_*^4,$$

obtained by putting  $\overset{\lambda}{\xi}(s)$  in (5) instead of  $\overset{\lambda}{\xi}$ , is one-to-one.

Now it is necessary to find the inverse transformation to (18). Let us write (18) using the representatives of classes  $\overset{\lambda}{\xi}(s), \overset{\lambda}{\eta}, \alpha$ . We have

$$(19) \quad \overset{\lambda}{y}_i = r a_{ij} \overset{\lambda}{\sigma}_j(s), \quad i = 1, 2; \lambda = 1, 2, 3, 4.$$

Before calculations let us notice that

1°  $s$  does not depend on  $\overset{\lambda}{r}$  but only on  $\overset{\lambda}{y}_i$ ,

2°  $a_{ij}$  depend not only on  $\overset{\lambda}{y}_i$  but also on  $\overset{\lambda}{r}$  and the dependence is of the type

$$\bar{a}_{ij} = \varrho(\overset{\lambda}{r}) a_{ij}, \quad i, j = 1, 2,$$

where  $\varrho$  may be an arbitrary function. The quantities  $\overset{\lambda}{r}$  are functions of representatives of classes  $\overset{\lambda}{\xi}(s), \overset{\lambda}{\eta}, \alpha$ . If we change them, we do not change classes.

From Theorem 3 it follows that  $s$  must be equal to the harmonic ratio of the points  $\overset{\lambda}{\eta}$ , being connected with  $s$  by (18). Using the representatives of the classes  $\overset{\lambda}{\eta}$  we may write

$$(20) \quad s = \frac{W^{13}(y) W^{24}(y)}{W^{14}(y) W^{23}(y)},$$

where  $W^{\lambda\mu}$  are defined in (13').

The same result may be obtained by direct calculations, which are following:

By the theorem of Cauchy concerning the determinants of the products of matrices, related to (19), we have

$$(21) \quad W^{\lambda\mu}(y) = \overset{\lambda\mu}{rr} \Delta \omega^{\lambda\mu}(s),$$

where

$$\Delta = \det \|a_{ij}\|; \quad \Delta \neq 0,$$

and  $\omega^{\lambda\mu}(s)$  defined by (16) are given by (17).

From (21) we obtain

$$(22) \quad \overset{\lambda\mu}{rr} = \frac{1}{\Delta} \cdot \frac{W^{\lambda\mu}(y)}{\omega^{\lambda\mu}(s)}.$$

If we put  $\lambda = 1, 2$  in (19) and use (14), (17) and (22), then we obtain

$$(23) \quad a_{i1} = \frac{\overset{1}{y}_i}{\overset{1}{r}} = \overset{3}{r} \cdot \frac{\overset{1}{y}_i}{\overset{13}{rr}} = \overset{3}{r} \Delta \cdot \frac{\overset{1}{y}_i}{W^{13}(y)} = l \cdot \frac{\overset{1}{y}_i}{W^{13}(y)},$$

$$(24) \quad a_{i2} = \frac{\overset{2}{y}_i}{\overset{2}{r}} = \overset{3}{r} \cdot \frac{\overset{2}{y}_i}{\overset{23}{rr}} = \overset{3}{r} \Delta \cdot \frac{\overset{2}{y}_i}{W^{32}(y)} = l \cdot \frac{\overset{2}{y}_i}{W^{32}(y)}, \quad l = \overset{3}{r} \Delta.$$

Now if we put  $\lambda = 4$  in (19) and if we use (23), (24) and (14), then we have

$$(25) \quad \begin{aligned} y_1^4 &= l \cdot \frac{r^4}{1} \left( s \cdot \frac{y_1^1}{W^{13}(y)} + \frac{y_1^2}{W^{32}(y)} \right), \\ y_2^4 &= l \cdot \frac{r^4}{1} \left( s \cdot \frac{y_2^1}{W^{13}(y)} + \frac{y_2^2}{W^{32}(y)} \right). \end{aligned}$$

Multiplying the first equation of (25) by  $y_2^4$  and the second by  $-y_1^4$  and adding, we obtain

$$0 = l \cdot \frac{r^4}{1} \left( s \cdot \frac{W^{14}(y)}{W^{13}(y)} - \frac{W^{24}(y)}{W^{32}(y)} \right),$$

whence follows immediately formula (20).

Formulae (20), (23) and (24) give us the inverse transformation to (18).

**2.** From Theorems 1 and 2 it follows that the solving of functional equation (11) is equivalent to the solving of equation (9) in the family of homogeneous functions of order 0 with respect to each variable  $x^\lambda$  by assumption A about the function  $g$  and the assumption that the points  $x^\lambda$  are different.

If we put arbitrary representatives of classes  $\xi^\lambda(s)$  in formula (9) instead of  $x^\lambda$ 's, then we obtain (remember that  $\varphi$  is homogeneous of order 0)

$$(26) \quad \varphi(r a_{ij}^\lambda \sigma_j^\lambda(s)) = g(\varphi(\sigma_i^\lambda(s)), a_{ij}).$$

Let us put, by definition,

$$(27) \quad \Phi(s) \stackrel{\text{df}}{=} \varphi(\sigma(s)) = \varphi(1, 0; 0, 1; 1, 1; s, 1), \quad s \in S.$$

Using formulae (19) and (27) we may write (26) in the form

$$(28) \quad \varphi(y_i^\lambda) = g(\Phi(s), a_{ij}).$$

Now we use formulae (20), (23), (24) and from (28) we get

$$(29) \quad \varphi(y_i^\lambda) = g \left( \Phi \left( \frac{W^{13}(y) \cdot W^{24}(y)}{W^{14}(y) \cdot W^{23}(y)} \right), \frac{y_1^1}{W^{13}(y)}, \frac{y_2^1}{W^{13}(y)}, \frac{y_1^2}{W^{32}(y)}, \frac{y_2^2}{W^{32}(y)} \right),$$

where

$$W^{\lambda\mu}(y) \stackrel{\text{def}}{=} \det \begin{vmatrix} y_1^\lambda & y_2^\lambda \\ y_1^\mu & y_2^\mu \end{vmatrix}.$$

We obtain the following

**THEOREM 4.** *If in (9) there is given a function  $g(u, a_{ij})$ ,  $u \in U$ ,  $\|a_{ij}\| \in L$  satisfying condition A, then the general solution  $\varphi$  of (9) in the set of all 4-points  $(\overset{\lambda}{x})$  with different points and in the family of homogeneous functions of order 0 with respect to each variable  $\overset{\lambda}{x}$  is of form (29), where  $\Phi$  is an arbitrary function*

$$\Phi: S \rightarrow U,$$

where  $U$  is the space of acting of the transformation group  $G \ni g$  and  $S$  is defined by (13). The function  $\hat{\varphi}$  obtained from function (29) by using the operation of factorization with respect to the relation  $R^4$  introduced in Section 3 is the general solution of (11), where  $\hat{g}$  denotes the factorization of  $g$  with respect to the relation  $R_A$ .

**Remark 2.** In the case where  $g(u, a_{ij}) \equiv u$ ,  $u \in D = R$  we obtain from (29) the result presented in [1].

**Remark 3.** Moreover, if we assume for the unknown function  $\varphi$  the initial condition

$$\varphi(1, 0; 0, 1; 1, 1; s, 1) \equiv s,$$

then we obtain for the solution of (11)

$$\varphi(\overset{\lambda}{y}_i) = \frac{W^{13}(y) \cdot W^{24}(y)}{W^{14}(y) \cdot W^{23}(y)}.$$

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